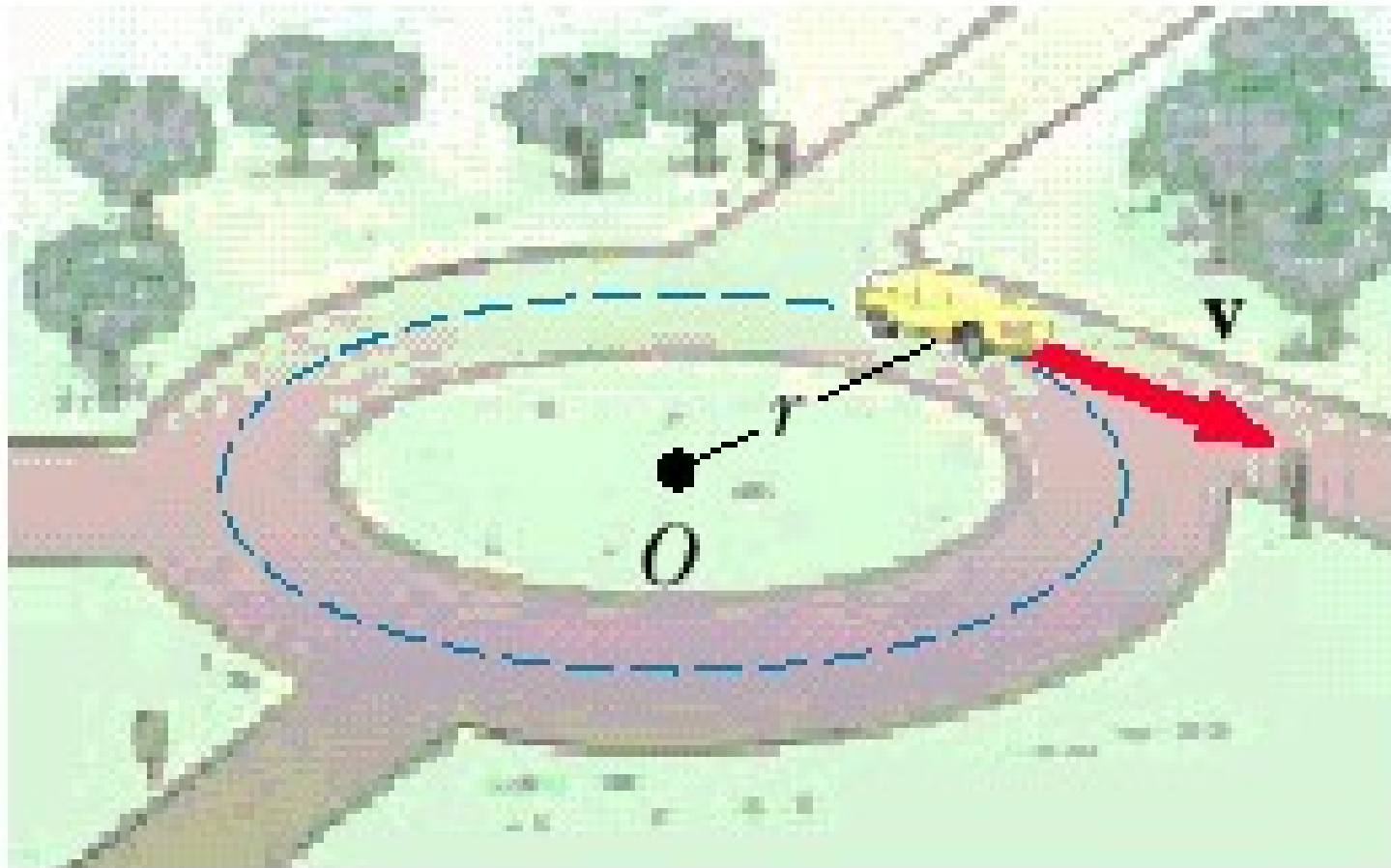
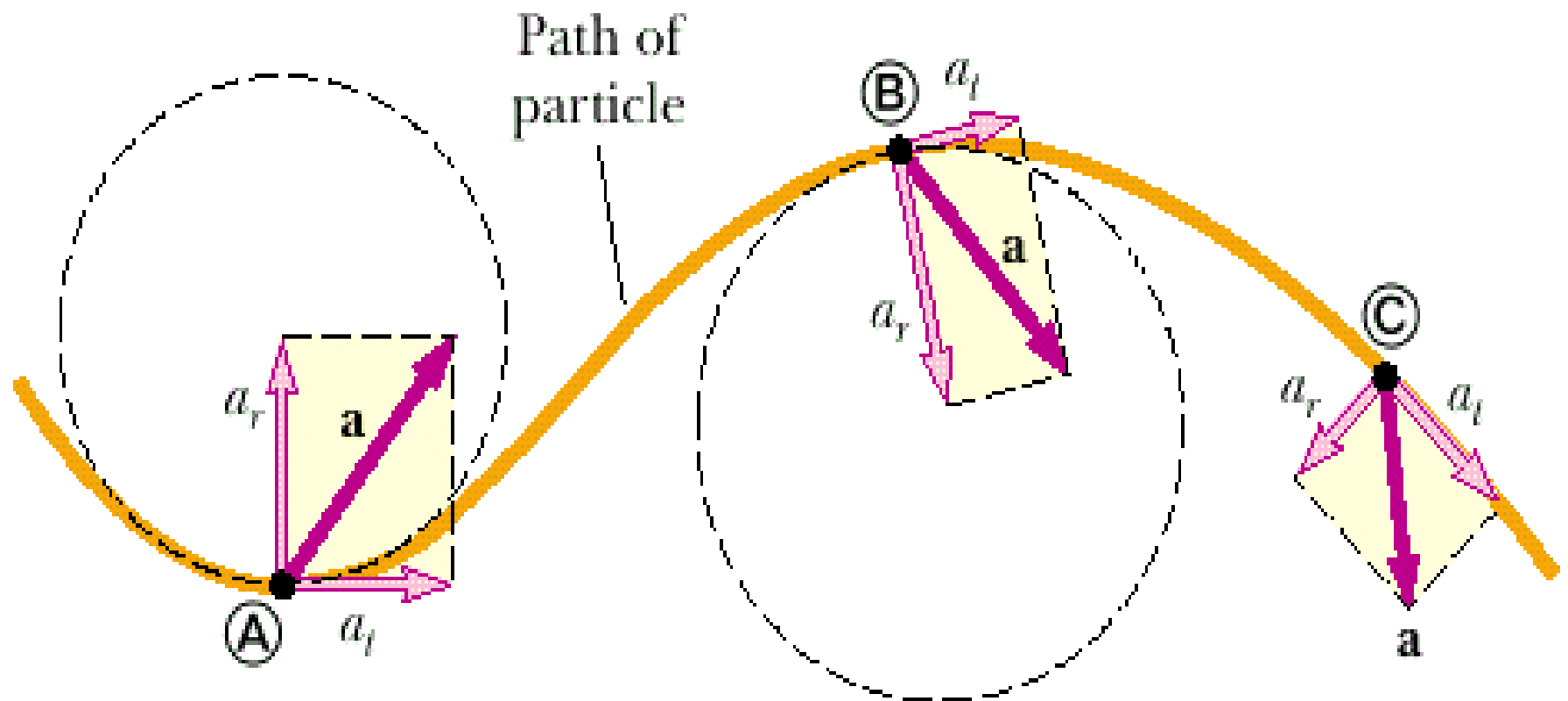


Movimiento Circular Uniforme

Trayectoria circular con radio y rapidez constante

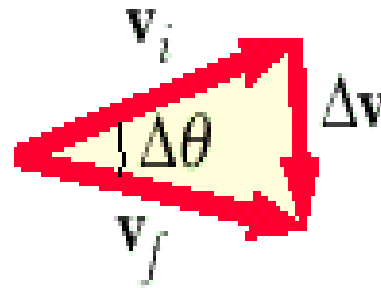
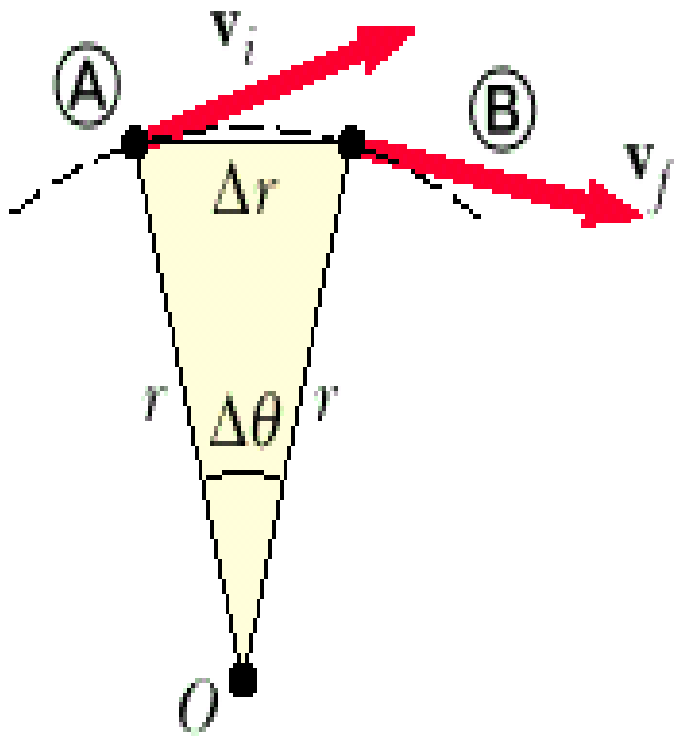


Movimiento Circular NO Uniforme



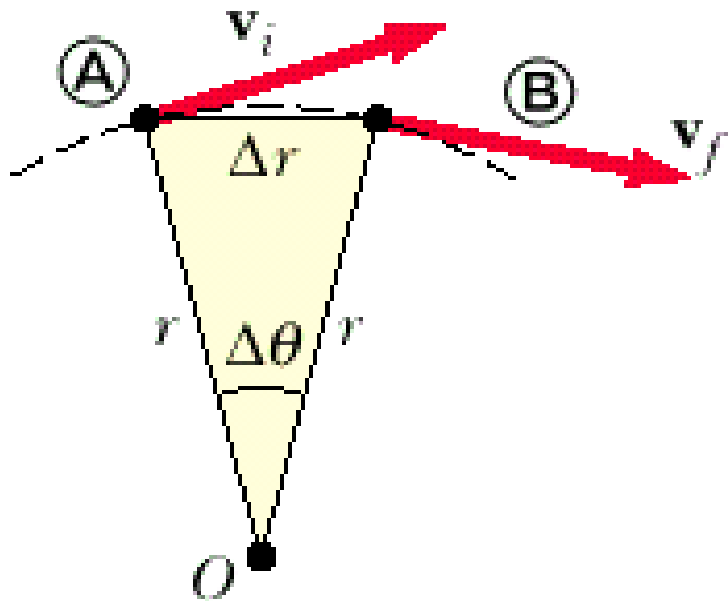
Movimiento Circular Uniforme

Movimiento con aceleración hacia el centro del círculo.



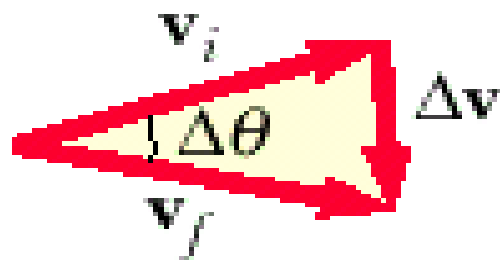
$$a_r = \frac{v^2}{r}$$

Movimiento Circular Uniforme



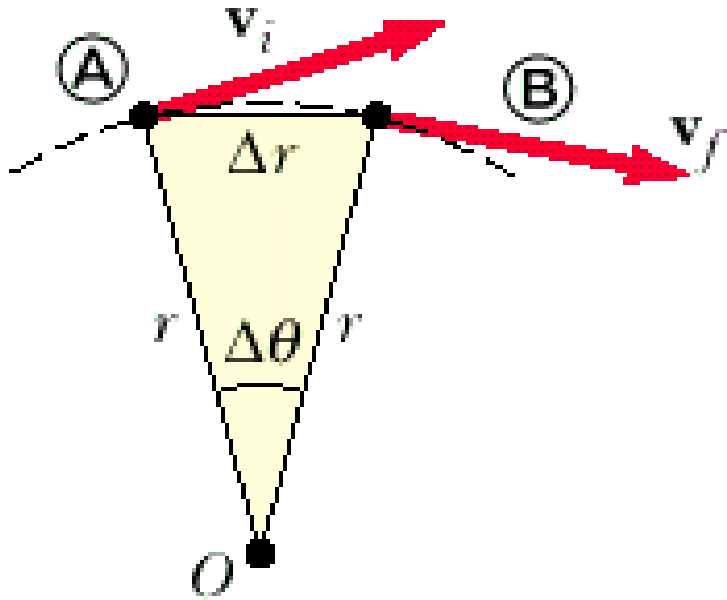
$$\bar{\mathbf{a}} = \frac{\mathbf{v}_f - \mathbf{v}_i}{t_f - t_i} = \frac{\Delta \mathbf{v}}{\Delta t}$$

$$\frac{\Delta v}{v} = \frac{\Delta r}{r}$$



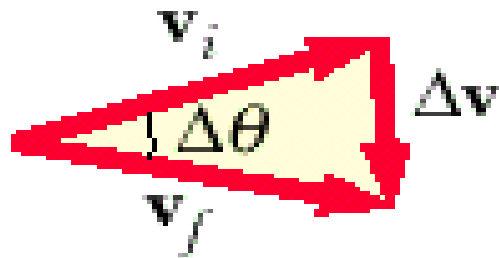
$$\bar{a} = \frac{v \Delta r}{r \Delta t}$$

Movimiento Circular Uniforme



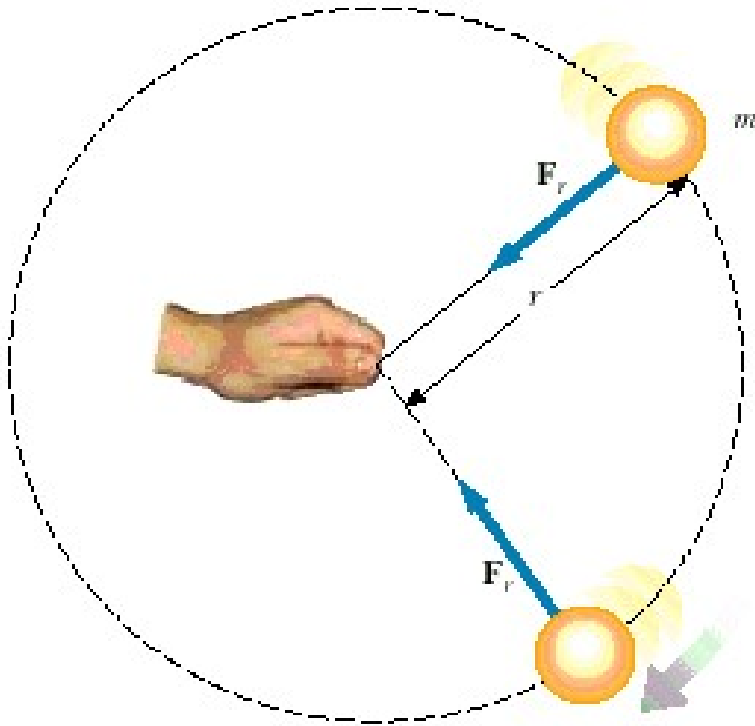
$$\frac{\Delta v}{v} = \frac{\Delta r}{r}$$

$$\overline{a} = \frac{v \Delta r}{r \Delta t}$$



$$a_r = \frac{v^2}{r}$$

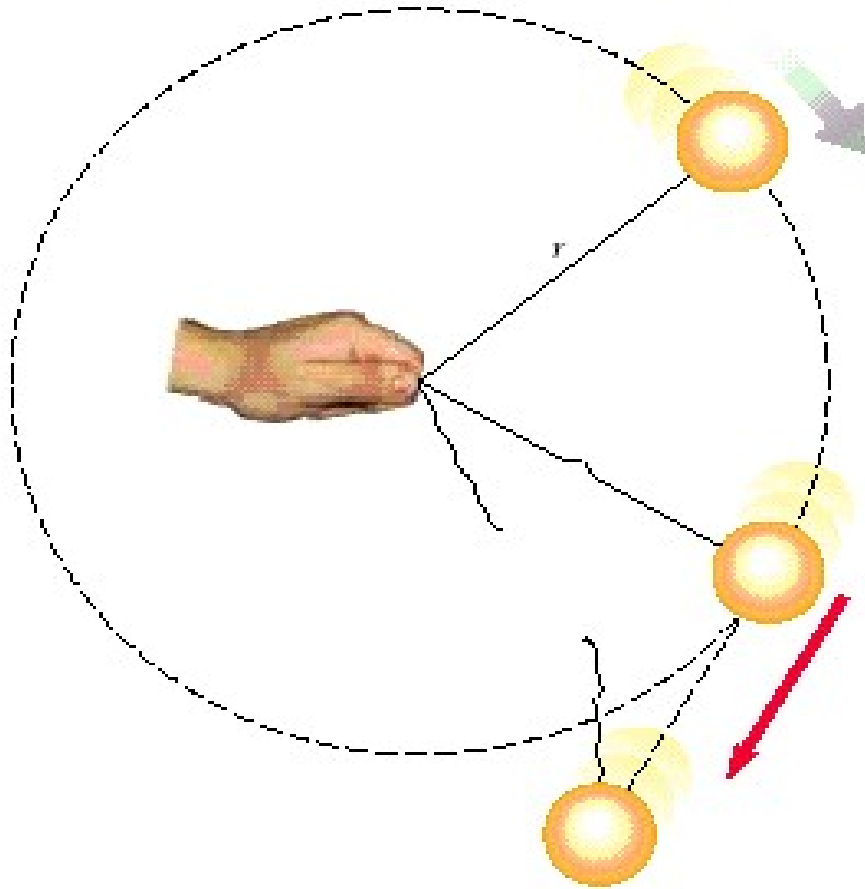
Dinámica del Movimiento Circular Uniforme



Si aplicamos la Ley de Newton al movimiento circular, obtenemos:

$$\sum F_r = ma_r = m \frac{v^2}{r}$$

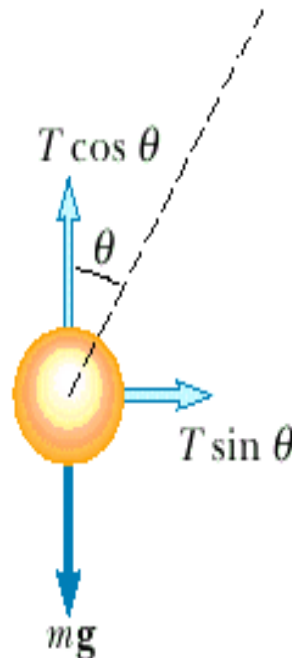
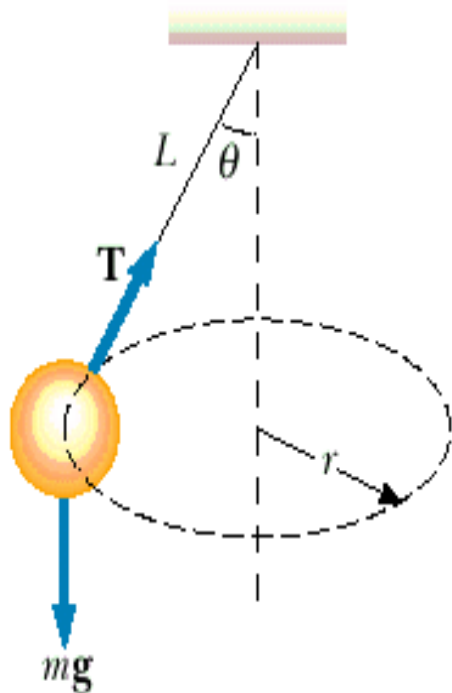
Dinámica del Movimiento Circular Uniforme



Cuando se corta la cuerda, ya no existe la fuerza para seguir la trayectoria circular.

$$\sum F_r = ma_r = m \frac{v^2}{r}$$

Dinámica del Movimiento Circular Uniforme



$$(1) \quad T \cos \theta = mg$$

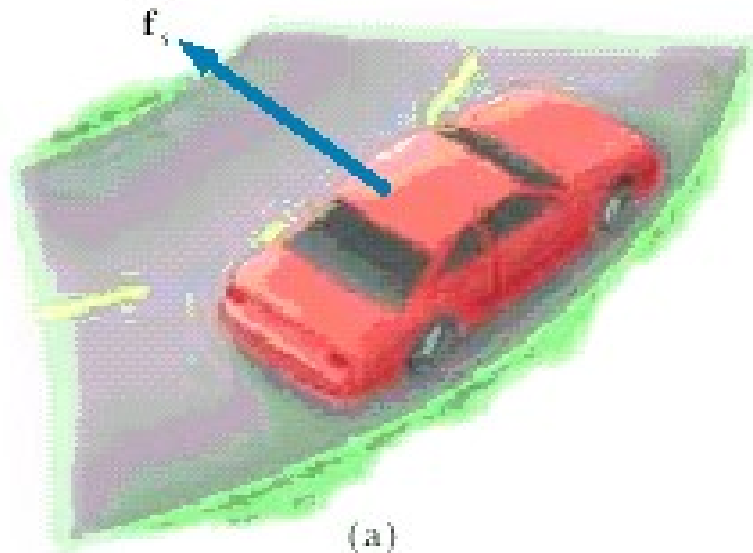
$$(2) \quad \sum F_r = T \sin \theta = ma_r = \frac{mv^2}{r}$$

$$\tan \theta = \frac{v^2}{rg}$$

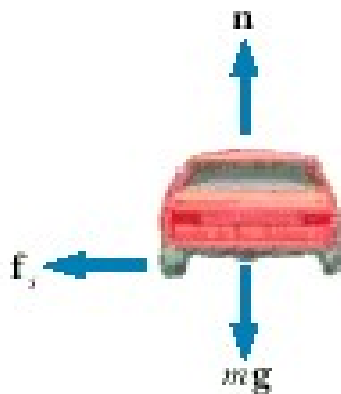
$$v = \sqrt{rg \tan \theta}$$

$$v = \sqrt{Lg \sin \theta \tan \theta}$$

Dinámica del Movimiento Circular Uniforme

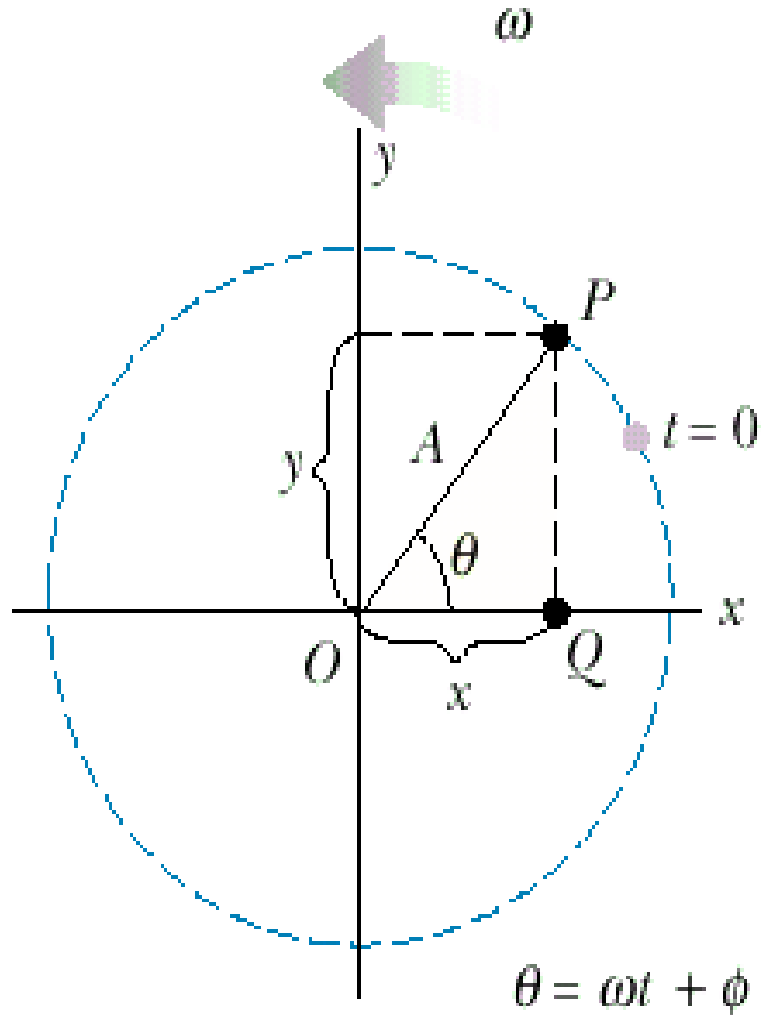
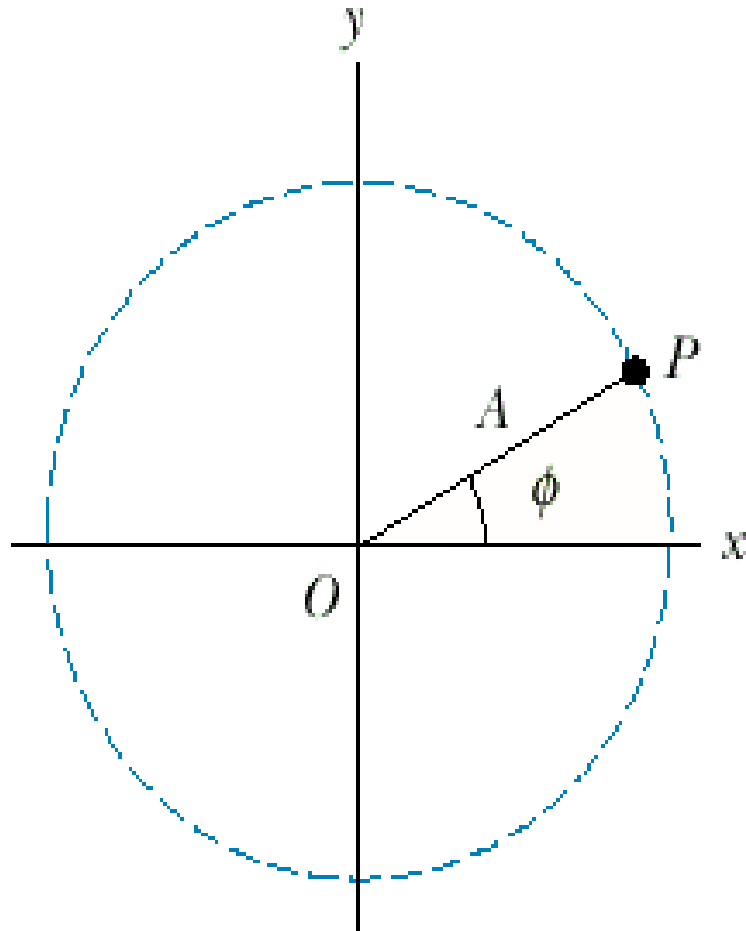


$$(1) \quad f_s = m \frac{v^2}{r}$$



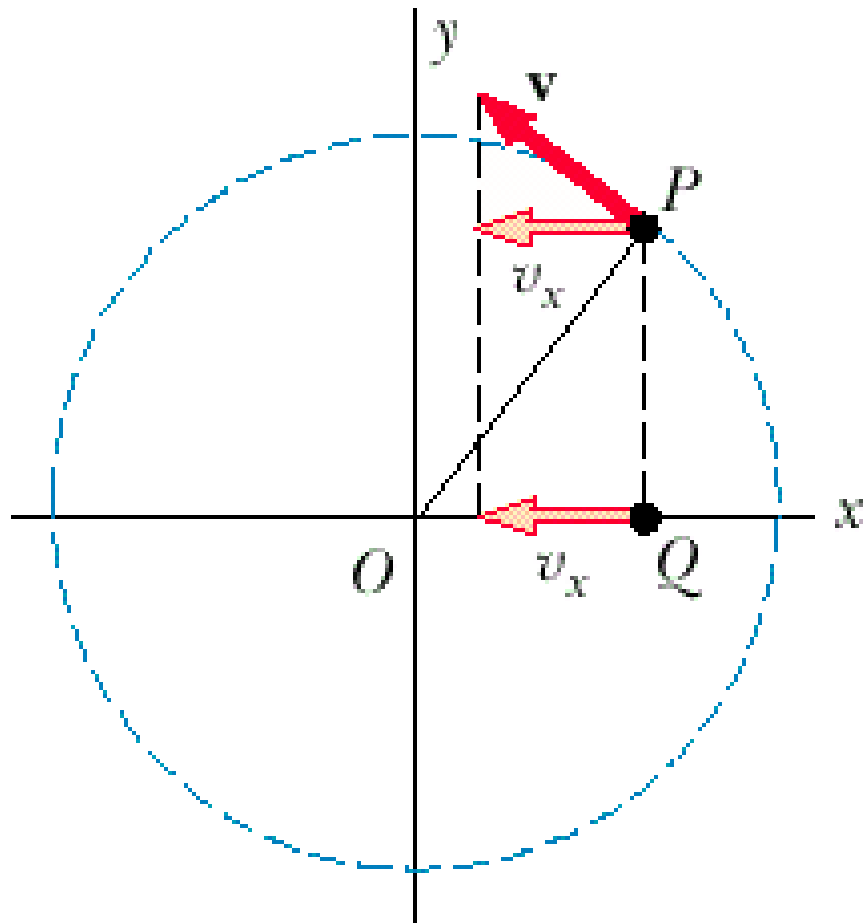
$$\begin{aligned} v_{\max} &= \sqrt{\frac{f_{s,\max} r}{m}} = \sqrt{\frac{\mu_s m g r}{m}} = \sqrt{\mu_s g r} \\ &= \sqrt{(0.500)(9.80 \text{ m/s}^2)(35.0 \text{ m})} = 13.1 \text{ m/s} \end{aligned}$$

Movimiento Circular Uniforme y Movimiento Armónico Simple MAS

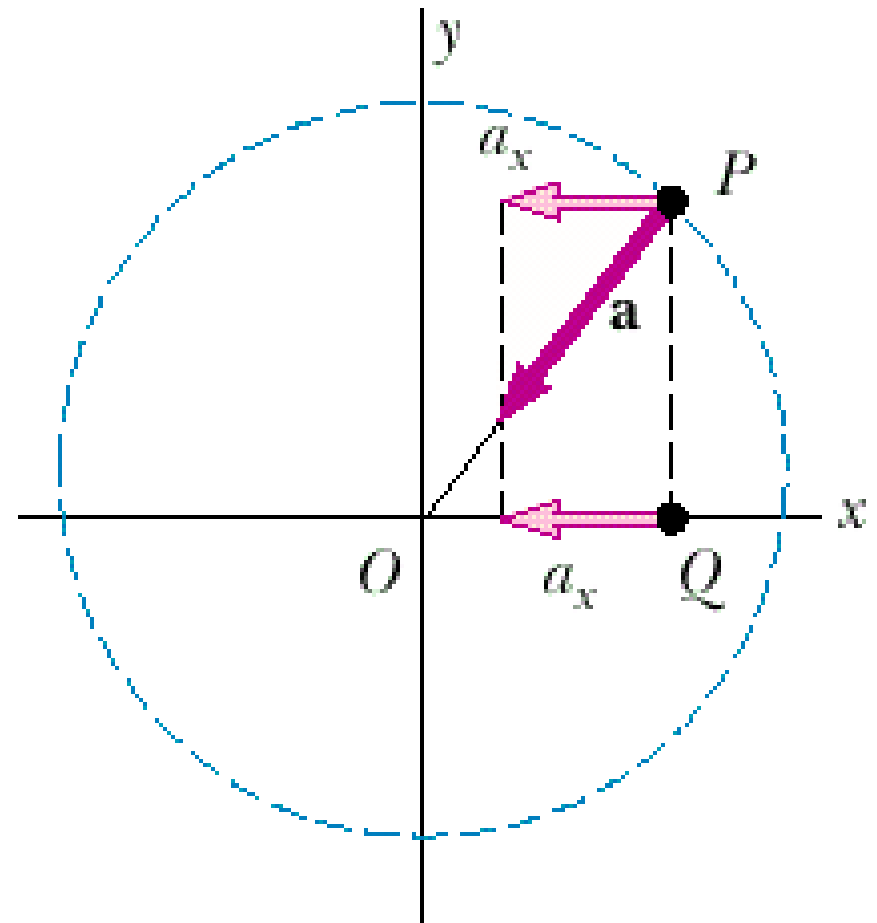


Movimiento Circular Uniforme y Movimiento Armónico Simple MAS

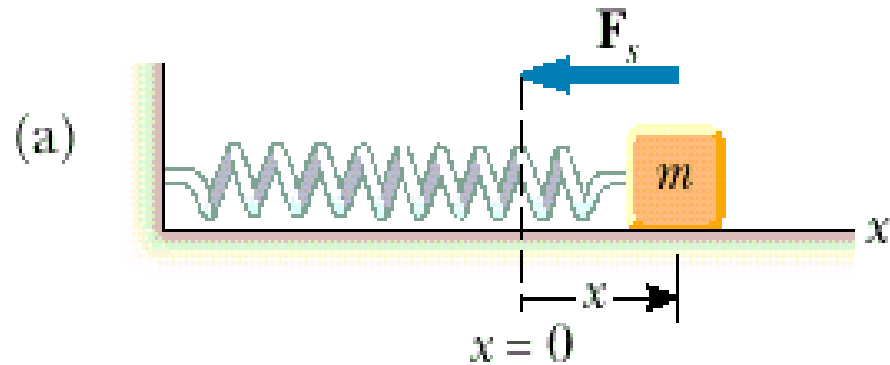
$$v = \omega A$$



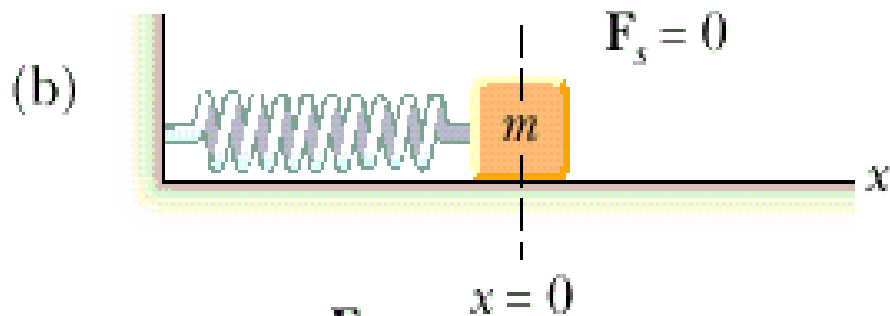
$$a = \omega^2 A$$



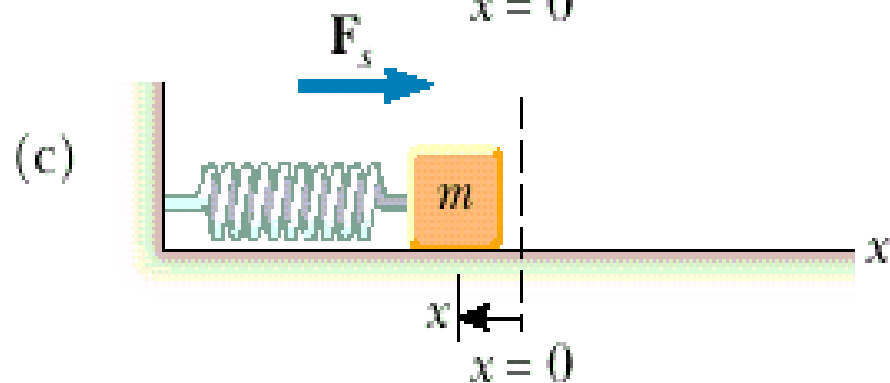
Movimiento Armónico Simple MAS



$$F_s = -kx$$

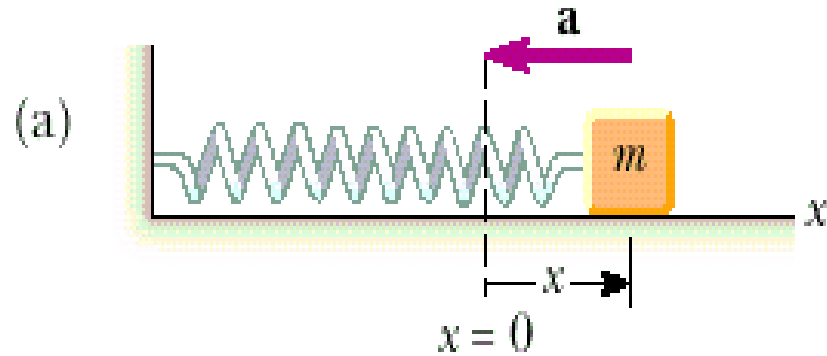


$$F_s = -kx = ma$$

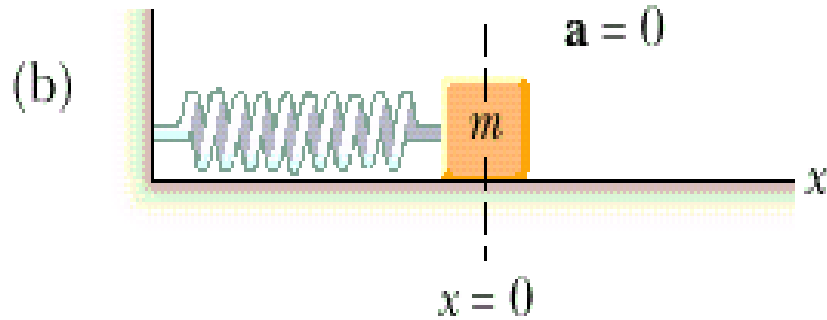


$$a = -\frac{k}{m}x$$

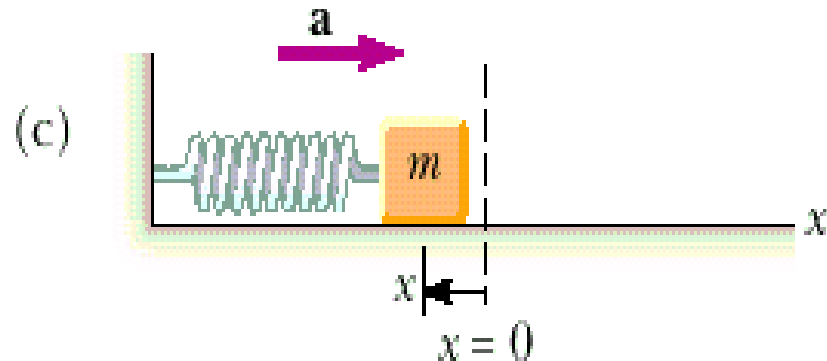
Movimiento Armónico Simple MAS



$$\frac{d^2x}{dt^2} = -\frac{k}{m}x$$

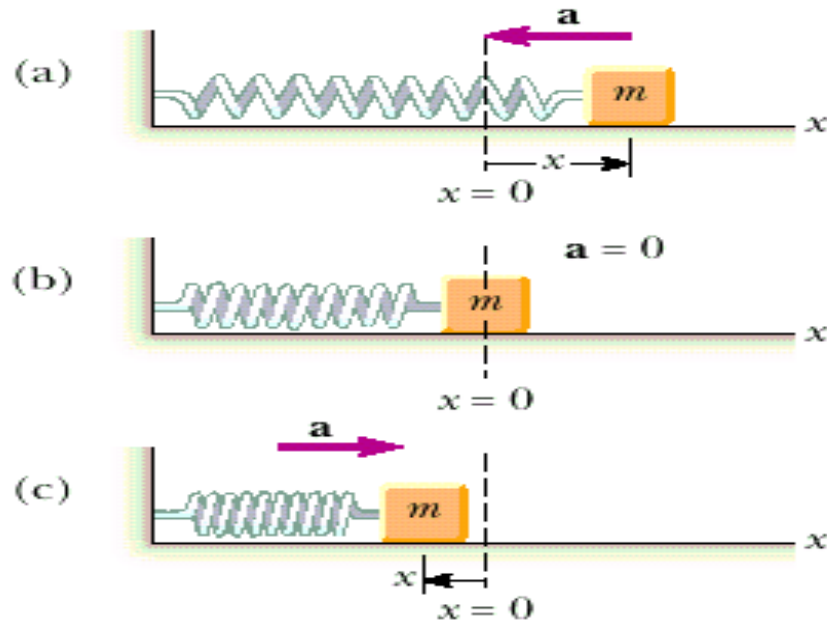


$$\frac{d^2x}{dt^2} = -\omega^2x$$



$$x = A \cos(\omega t + \phi)$$

Movimiento Armónico Simple MAS



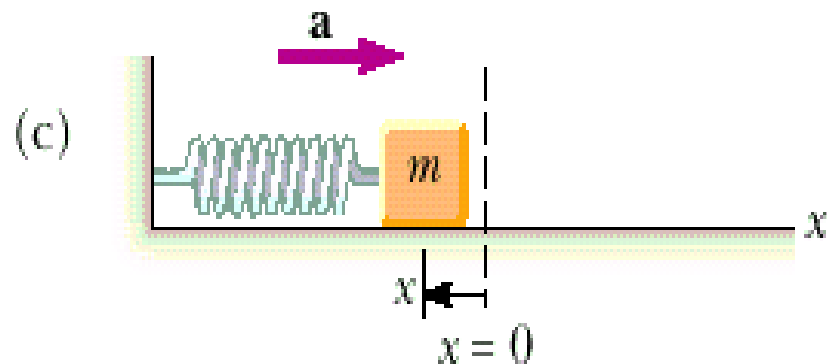
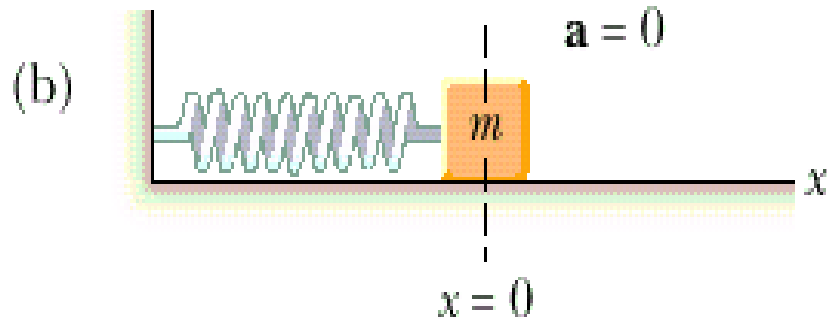
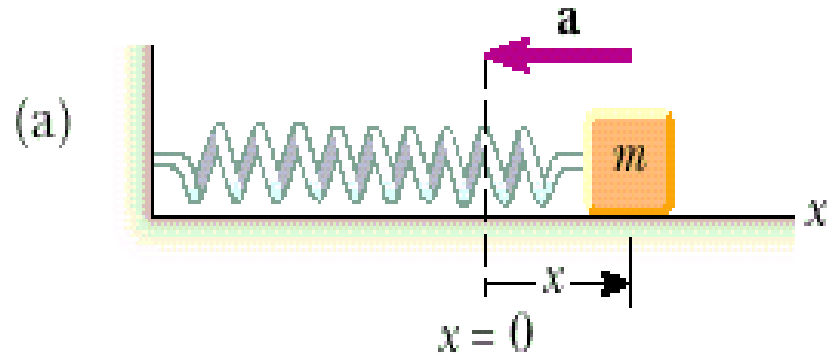
$$\frac{d^2x}{dt^2} = -\omega^2 x$$

$$x = A \cos(\omega t + \phi)$$

$$\frac{dx}{dt} = A \frac{d}{dt} \cos(\omega t + \phi) = -\omega A \sin(\omega t + \phi)$$

$$\frac{d^2x}{dt^2} = -\omega A \frac{d}{dt} \sin(\omega t + \phi) = -\omega^2 A \cos(\omega t + \phi)$$

Movimiento Armónico Simple MAS



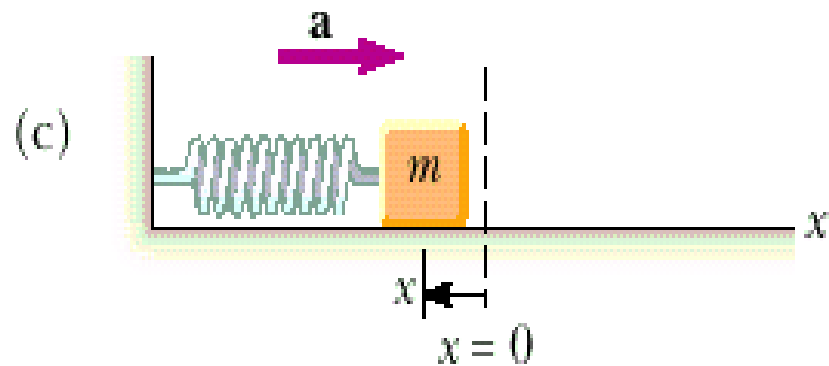
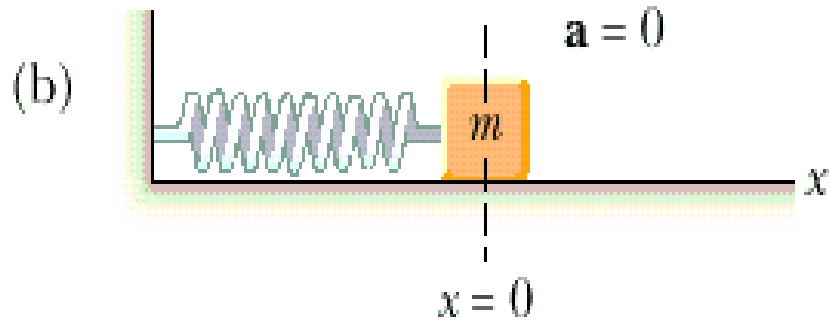
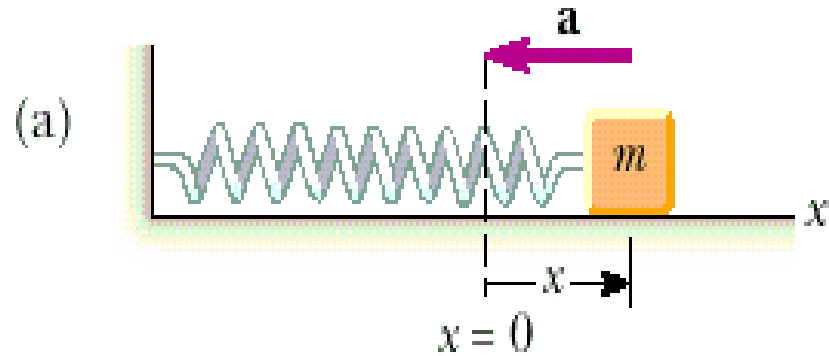
$$\frac{d^2x}{dt^2} = -\omega^2 x$$

$$x = A \cos(\omega t + \phi)$$

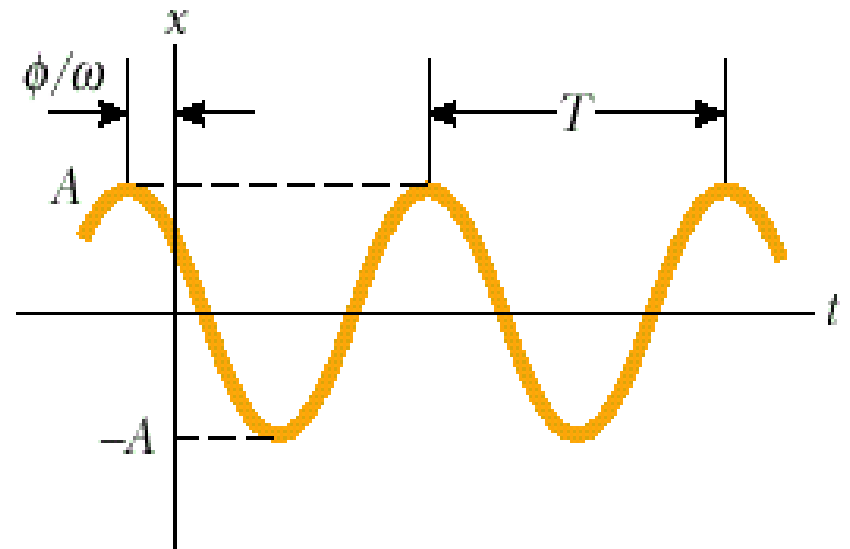
$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{m}{k}}$$

$$f = \frac{1}{T} = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$

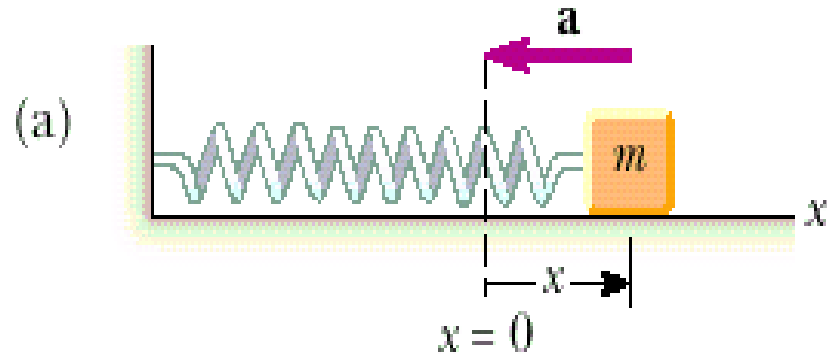
Movimiento Armónico Simple MAS



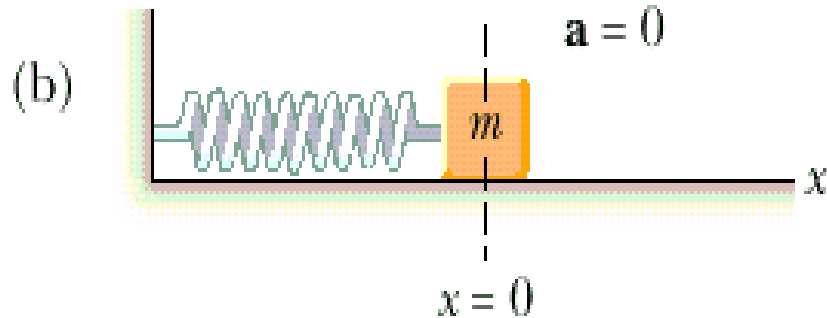
$$x = A \cos(\omega t + \phi)$$



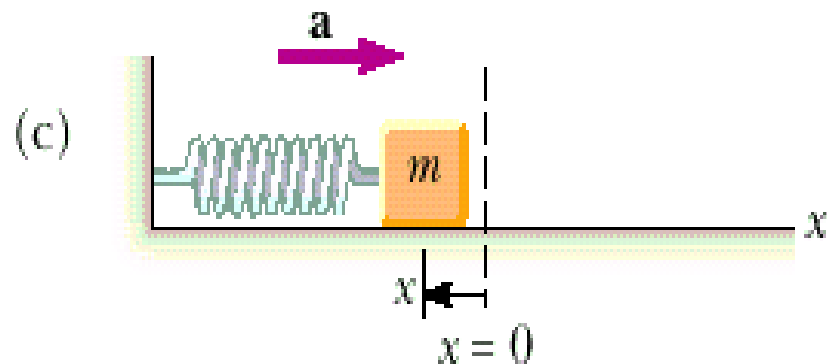
Movimiento Armónico Simple MAS



$$x = A \cos(\omega t + \phi)$$

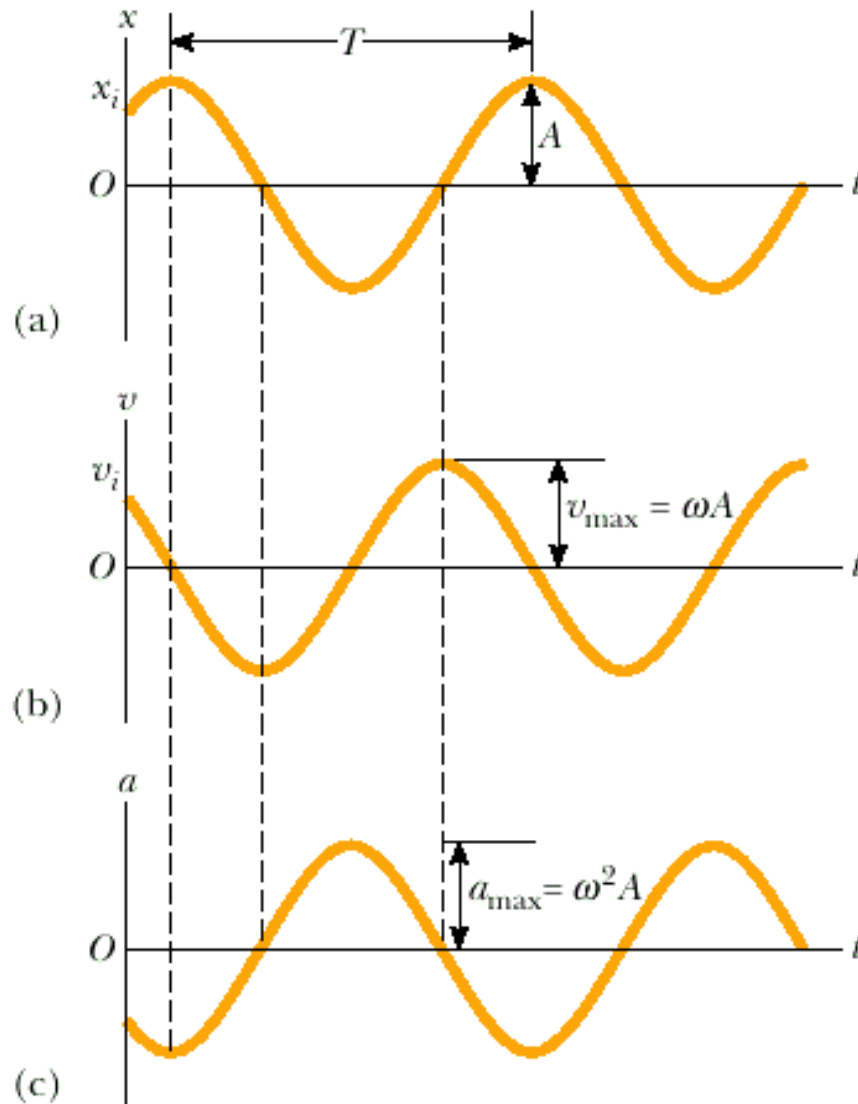


$$v = \frac{dx}{dt} = -\omega A \sin(\omega t + \phi)$$



$$a = \frac{dv}{dt} = -\omega^2 A \cos(\omega t + \phi)$$

Movimiento Armónico Simple MAS



$$x = A \cos(\omega t + \phi)$$

$$v = \frac{dx}{dt} = -\omega A \sin(\omega t + \phi)$$

$$a = \frac{dv}{dt} = -\omega^2 A \cos(\omega t + \phi)$$

Energía en el Oscilador Armónico Simple MAS

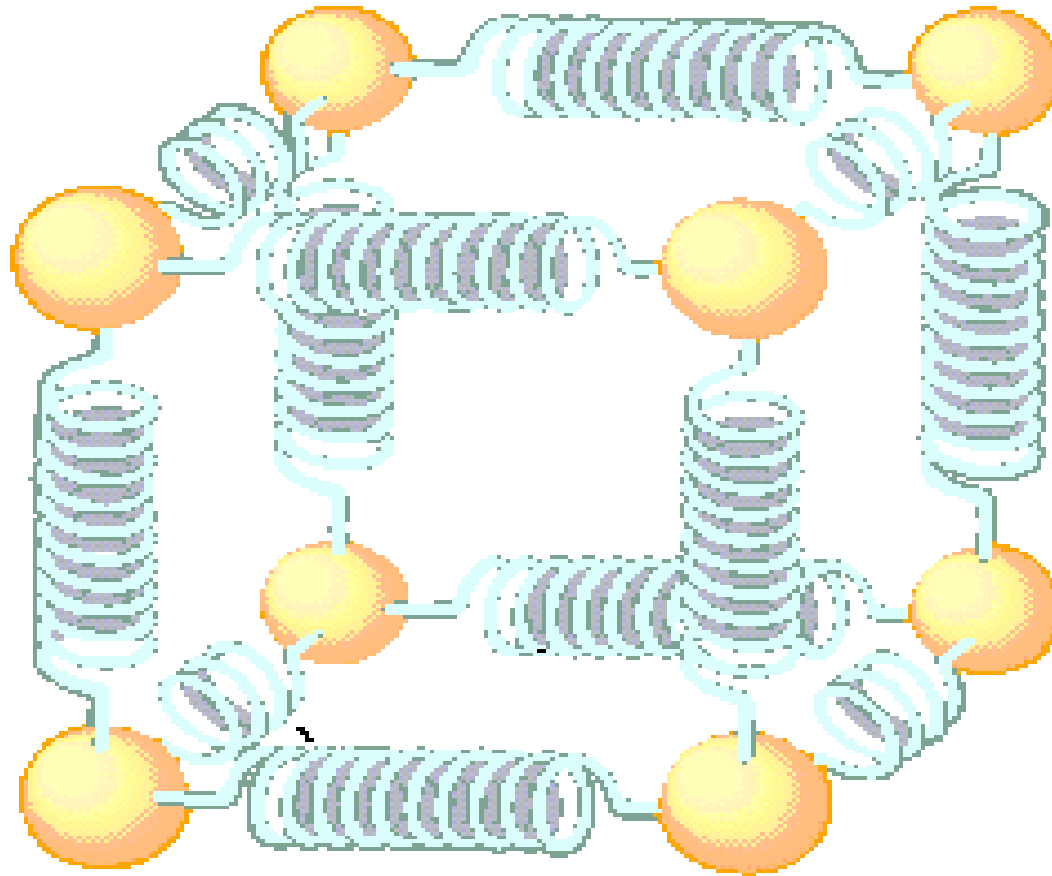
$$K = \frac{1}{2} m v^2 = \frac{1}{2} m \omega^2 A^2 \sin^2(\omega t + \phi)$$

$$U = \frac{1}{2} k x^2 = \frac{1}{2} k A^2 \cos^2(\omega t + \phi)$$

$$E = K + U = \frac{1}{2} k A^2 [\sin^2(\omega t + \phi) + \cos^2(\omega t + \phi)]$$

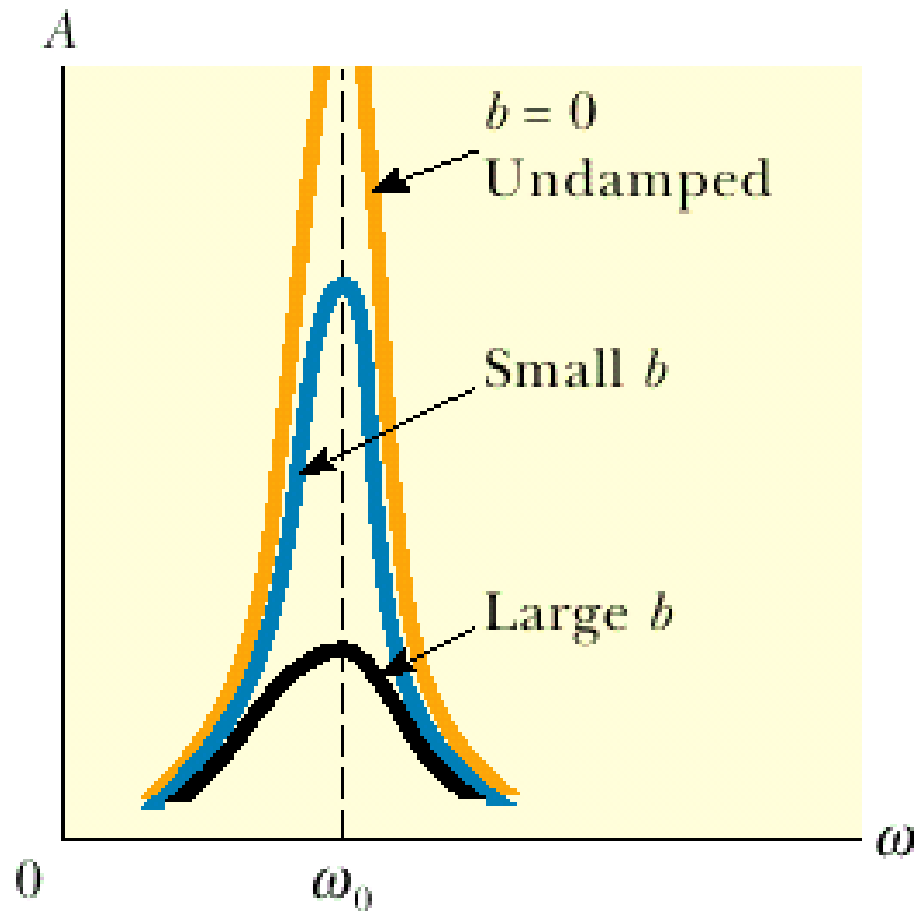
$$E = \frac{1}{2} k A^2$$

Modelo de átomos en una molécula



Oscilador Forzado Amortiguado

$$F_{\text{ext}} \cos \omega t - kx - b \frac{dx}{dt} = m \frac{d^2 x}{dt^2}$$



$$x = A \cos(\omega t + \phi)$$

$$A = \frac{F_{\text{ext}}/m}{\sqrt{(\omega^2 - \omega_0^2)^2 + \left(\frac{b\omega}{m}\right)^2}}$$