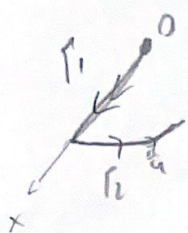


P1 $F = \rho^2 \hat{e} + r \rho \hat{\rho}$

Sección 1



$$\Gamma_1 = \Gamma_1(t) = (t, 0, 0) \quad t \in [0, R]$$

$$\Gamma_2 = \Gamma_2(\theta) = (R \cos \theta, R \sin \theta, 0) = R \hat{\rho} \quad \theta \in [2\pi]$$

$$\frac{d\Gamma_1}{dt} = (1, 0, 0)$$

$$\frac{d\Gamma_2}{d\theta} = (-R \sin \theta, R \cos \theta, 0) = R \hat{\theta}$$

Γ_1 $\int_0^R \begin{pmatrix} 0 \cdot \rho \cos \theta \\ 0 \cdot \rho \sin \theta \\ \rho^2 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} dt = 0$

Γ_2 $\int_0^{2\pi} \underbrace{(R^2 \hat{e} + 0 R \hat{\rho})}_{0} \cdot R \hat{\theta} d\theta = 0 \quad (\text{Se puede hacer en cartesianas})$

Sección 2



$$\Gamma_3 = \Gamma_3(z) = (0, 0, H-z) \quad z \in [0, H]$$

$$\frac{d\Gamma_3}{dz} = (0, 0, -1)$$

$$\Gamma_4: \Gamma_4(z) = (R \cos(\pi/4), R \sin(\pi/4), z) \quad z \in [0, H]$$

$$\frac{d\Gamma_4}{dz} = (0, 0, 1)$$

Γ_3 $\int_0^H (0 \hat{e} + 0 \hat{\rho}) \cdot (-\hat{e}) dz = 0$

$$\int_0^H (R^2 \hat{e} + z R \hat{\rho}) \cdot (\hat{e}) dz = \boxed{R^2 H}$$

Section 3
 Γ_s

$$\Gamma_s: \Gamma_s(t) = (0, R-t, H) \quad t \in [0, R]$$

$$\frac{d\Gamma_s(t)}{dt} = (0, -1, 0)$$

$$\Gamma_6: \Gamma_6(\sigma) = (R \cos \sigma, R \sin \sigma, H) \quad \sigma \in \left[\frac{\pi}{4}, \frac{\pi}{2}\right]$$

$$= R \hat{\rho} + H \hat{z}$$

$$\frac{d\Gamma_6}{d\sigma} = (-R \sin \sigma, R \cos \sigma, 0)$$

$$= R \hat{\theta}$$

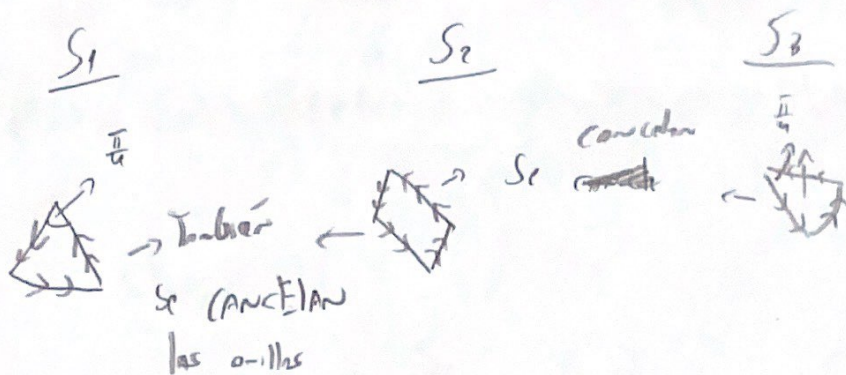
$$\boxed{\Gamma_s} \quad \int_0^R \left[H \cdot (R-t) \cos\left(\frac{\pi}{2}\right) \hat{\rho} + H(R-t) \frac{\sin\left(\frac{\pi}{2}\right)}{1} \hat{s} + (R-t)^2 \hat{z} \right] \cdot [0 \hat{r} - \hat{s} + 0 \hat{z}] dt$$

$$= \int_0^R H(t-R) dt = H \left[\frac{t-R}{2} \right]_0^R = -\frac{HR^2}{2}$$

$$\boxed{\Gamma_6} \quad \int_0^R (R^2 \hat{z} + HR \hat{\rho}) \cdot (R \hat{\theta}) d\sigma = 0$$

$$\Rightarrow \text{Trabajo} \quad \text{es} \quad \boxed{\frac{HR^2}{2}}$$

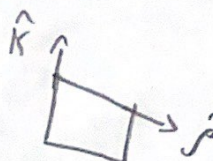
b) Con Stokes se usara sobre 3 superficies.



Normal on S_1 y S_3 es $\hat{k}$

Calculando el $\text{rot}(F) = \frac{1}{r} \begin{vmatrix} \hat{\rho} & \rho \hat{\phi} & \hat{k} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ \frac{1}{r} & 0 & \rho^2 \end{vmatrix} = -\rho \hat{\phi}$

$$\Rightarrow \iint_{S_1} \text{rot}(F) \cdot \hat{n} dS = \iint_{S_3} \text{rot}(F) \cdot \hat{n} dS = 0$$

Notar que  por lo que el normal es $\hat{\phi}$

pero como apunta para afuera es $-\hat{\phi}$

$$\Rightarrow \iint_{S_2} \text{rot}(F) \cdot \hat{n} dS = \int_0^R \int_0^H \rho dz d\rho = H \int_0^R \rho d\rho = \frac{HR^2}{2}$$

P2 a) $\text{rot}(F) = \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \hat{i} + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \hat{j} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \hat{k}$
 $= (0 - 0) \hat{i} + \underbrace{(-3 + e^x \cos(t) - e^x \cos(t) + 3)}_0 \hat{j} + (2x - 3x^2) \hat{k}$

b) $\vec{r}$ es simple

$$\vec{r}(t_1) = \vec{r}(t_2) \Rightarrow \sin(t_1) = \sin(t_2)$$

$$\Rightarrow \boxed{t_1 = t_2} \quad \text{o} \quad t_1 = \pi - t_2$$

L.s.)

Si $\pi - t_2 = t_1 \quad \sim \quad \cos(t_1) = \cos(t_2)$
 $\Rightarrow \cos(t_1) = \cos(\pi - t_1)$

Pero esta es falsa para todo t_1 , por gráfico tico

$$\Rightarrow \cos(0) = \cos(\pi) \quad \text{falso}$$

$$\Rightarrow \boxed{t_1 = t_2}$$

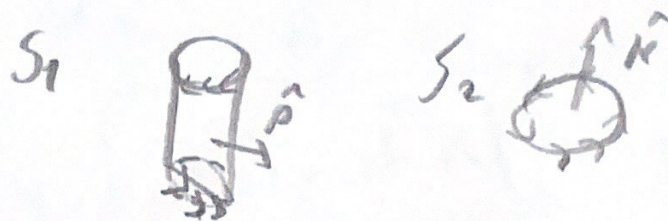
$\vec{r}$ es simple : No tener que $\cos(t)$ y $\sin(t)$ son

C'

$\vec{r}$ regular $\frac{d\vec{r}}{dt} = (-\sin(t), \cos(t), -\sin(t))$

$\left\| \frac{d\vec{r}}{dt} \right\| = \sqrt{1 + \sin^2(t)} \geq 1 > 0$ es regular

Por Stokes



Con esas orientaciones se
cancela Γ y se cancela la unión

$$\oint_{\Gamma} \vec{F} \cdot d\vec{r} = \iint_{S_1} \text{rot}(\vec{F}) \cdot \hat{n} \, ds + \iint_{S_2} \text{rot}(\vec{F}) \cdot \hat{n} \, ds$$

pues $\text{rot}(\vec{F})$
solo $\hat{k}$

$$\begin{aligned} &= \int_0^1 \int_0^{2\pi} [2\rho \cos(\theta) - 3\rho^2 \cos(\theta)] \rho \, d\theta \, d\rho \\ &= \int_0^1 \left(-\frac{3}{2} \right) \rho^3 (1 + \cos(2\theta)) \, d\theta \, d\rho = \left(-\frac{3}{2} \right) \int_0^1 (2\pi) \rho^3 \, d\rho \\ &= \boxed{\left(-\frac{3}{4} \right) \pi} \end{aligned}$$

P3) $\text{rot}(F) = \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \hat{k}$

el normal al plano XY es $\hat{k}$

Por Stokes

$$\begin{aligned} \int_S F \cdot d\vec{r} &= \boxed{\int F_1 dx + F_2 dy} \\ &= \int \text{rot}(F) \cdot \hat{k} dS \\ &= \boxed{\int \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dS} \end{aligned}$$

Con lo que se obtiene Green

b) Sea $F(x, y) = (-y, x) \Rightarrow \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} = 2$

$$\Rightarrow 2 \text{Area}(S) = \int_S x dy - y dx$$

c) Propuesta verificar hipótesis: Usando b)

$$\text{Area}(S) = \frac{1}{2} \int_0^{2\pi} a \cos^2(t) dy - a \sin^2(t) dx$$

$$\begin{aligned} dx &= 3a \cos^2(t) (-\sin t) dt \\ &= -3a \cos^2(t) \sin t dt \\ dy &= 3a \sin^2(t) \cos t dt \\ &= 3a \sin^2(t) \cos t dt \end{aligned}$$

b) Si uno quisiera usar Stokes $\text{rot}(F) = 0$

el problema es que F no es C^1 , por lo que no se puede.

Por def $\frac{d\gamma}{d\sigma} = \left(-\left(\frac{\sigma+h}{h}\right) \sin \sigma + \frac{\cos \sigma}{h}, \left(\frac{\sigma+h}{h}\right) \cos \sigma + \frac{\sin \sigma}{h}, 1 \right)$

$$= \int_{\frac{\pi}{6}}^{\frac{\pi}{3}} \left[-\frac{\sin \sigma}{\cos \sigma} + (\sigma+h) \right] + \left[\frac{\cos \sigma}{\sin \sigma} + (\sigma+h) \right] + \frac{1}{\sigma+h} d\sigma$$

$$= \cancel{\int_{\frac{\pi}{6}}^{\frac{\pi}{3}} \left(-\frac{\sin \sigma}{\cos \sigma} + \frac{\cos \sigma}{\sin \sigma} \right) d\sigma}$$

$$= \ln(\cos(\sigma)) + \ln(\sigma+h) + \ln(\sin \sigma) + \ln(\sigma+h) + \ln(\sigma+h) \Big|_{\frac{\pi}{6}}^{\frac{\pi}{3}}$$

$$= \ln(\cos(\sigma) \sin(\sigma) \cdot (\sigma+h)^3) \Big|_{\frac{\pi}{6}}^{\frac{\pi}{3}}$$

$$= \ln \left(\frac{\cos(\frac{\pi}{3}) \sin(\frac{\pi}{3}) (\frac{\pi}{3}+h)^3}{\cos(\frac{\pi}{6}) \sin(\frac{\pi}{6}) (\frac{\pi}{6}+h)^3} \right)$$

$$= \boxed{\ln \left(\frac{2 \cos(\pi/3) (\pi/3+h)^3}{(\pi/6+h)^3} \right)}$$

* Esto es más feo que algo clásico no dar muchos créditos

$$Area(S) = \frac{1}{2} \int_0^{2\pi} 3a^2 \cos^4(t) \sin^2(t) + 3a^2 \sin^4(t) \cos^2(t) dt$$

$$= \frac{3a^2}{2} \int_0^{2\pi} \cos^2(t) \sin^2(t) dt$$

$$\sin(2t) = 2 \sin(t) \cos(t)$$

$$= \frac{3a^2}{8} \int_0^{2\pi} \sin(2t)^2 dt$$

$$= \frac{3a^2}{16} \int_0^{2\pi} (1 - \cos(4t)) dt$$

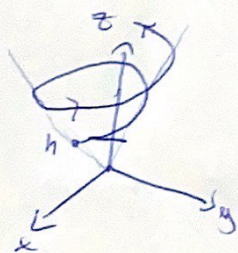
$$= \frac{3a^2}{16} \cdot 2\pi = \boxed{\frac{3a^2\pi}{8}}$$

Propuesto a) Con $\begin{cases} z(\theta) = 1 \\ z(\theta) = h \end{cases} \Rightarrow z(\theta) = \sigma + h$

$$\Rightarrow \begin{cases} x(\theta) = p(\theta) \cos(\theta) \\ y(\theta) = p(\theta) \sin(\theta) \end{cases} \quad \text{y} \quad p(\theta)^2 = \frac{(\sigma+h)^2}{h^2} \Rightarrow p(\theta) = \frac{\sigma+h}{h}$$

Finalmt. $\rho: \Gamma(\theta) = \left(\frac{\sigma+h}{h} \cos \theta, \frac{\sigma+h}{h} \sin \theta, \sigma+h \right)$

Basquejo gira y sube



es como una espiral sobre un cono