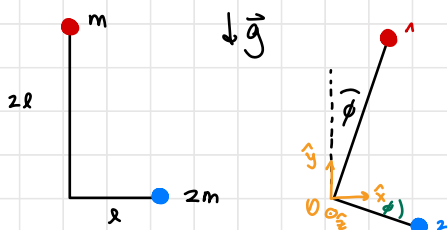


Pauta Aux 17

P11



para no tener
que usar la normal

$$\vec{r}_1 = 2l (\sin \phi, \cos \phi)$$

$$\vec{r}_2 = l (\cos \phi, -\sin \phi)$$

$$\vec{r}_{CM} = \frac{1}{3m} (m \vec{r}_1 + 2m \vec{r}_2)$$

$$= \frac{1}{3} (2l (\sin \phi, \cos \phi) + 2l (\cos \phi, -\sin \phi))$$

$$= \frac{2l}{3} (\sin \phi + \cos \phi, \cos \phi - \sin \phi)$$

Sabemos que $\frac{d\vec{L}_O^{CM}}{dt} = \vec{\tau}_{ext}$

veamos $\vec{L}_O^{CM} = \vec{r}_{CM} \times M \vec{v}_{CM}$

$$= \frac{2l}{3} (\sin \phi + \cos \phi, \cos \phi - \sin \phi) \times 3m \frac{2l}{3} \dot{\phi} (\cos \phi - \sin \phi, -\sin \phi - \cos \phi)$$

$$= \frac{4l^2}{3} m \dot{\phi} [(\sin \phi + \cos \phi)(-\sin \phi - \cos \phi) - (\cos \phi - \sin \phi)(\cos \phi - \sin \phi)] \hat{z}$$

$$= \frac{4l^2}{3} m \dot{\phi} [-\sin^2 \phi - \sin \phi \cos \phi - \cos \phi \sin \phi - \cos^2 \phi - \cos^2 \phi + \cos \phi \sin \phi + \sin \phi \cos \phi - \sin^2 \phi] \hat{z}$$

$$= \frac{4l^2}{3} m \dot{\phi} [-2] \hat{z}$$

$$\frac{d}{dt} \rightarrow -\frac{8}{3} m l^2 \ddot{\phi} \hat{z}$$

y veamos los $\vec{\tau}_{ext}$



$$\vec{\tau}_1 = \vec{r}_1 \times mg(-\hat{y}) = 2l (\sin \phi \hat{x} + \cos \phi \hat{y}) \times mg(-\hat{y})$$

$$= -2mgl \sin \phi \hat{z}$$

$$\vec{\tau}_2 = \vec{r}_2 \times 2mg(-\hat{y}) = l (\cos \phi \hat{x} - \sin \phi \hat{y}) \times 2mg(-\hat{y})$$

$$= -2mgl \cos \phi \hat{z}$$

$$\therefore \text{tenemos } -\frac{8}{3} m l^2 \ddot{\phi} \hat{z} = -2mgl (\sin \phi + \cos \phi) \hat{z}$$

$$4 \ddot{\phi} = 3 g/l (\sin \phi + \cos \phi)$$

Weg

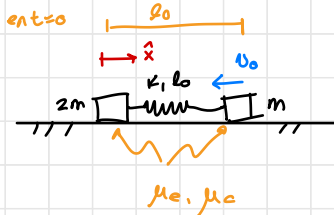
$$4 \dot{\phi} \frac{d\dot{\phi}}{d\phi} = \frac{3g}{l} (\cos\phi + \sin\phi) \quad / \int_0^\phi d\phi$$

$$4 \int_0^\phi \dot{\phi}' d\phi' = \frac{3g}{l} \int_0^\phi (\cos\phi' + \sin\phi') d\phi'$$

$$4 \frac{\dot{\phi}^2}{2} = \frac{3g}{l} (\sin\phi'|_0^\phi - \cos\phi'|_0^\phi)$$

$$\dot{\phi}^2 = \frac{3}{2} \frac{g}{l} (\sin\phi + 1 - \cos\phi)$$

P2



a) si yo tiro mi masa m con vel. v_0 hacia la masa $2m$ se acercará a una distancia mínima Δ de $2m$, en este punto, la F_e será máxima.

Para que $2m$ no se mueva

$$|\mu_c N| \geq |k(l_0 - \Delta)|$$

en el límite $\mu_c 2mg = k(l_0 - \Delta)$

Calculemos Δ en función de v_0

ecuación de m (con $2m$ fijo): $m\ddot{x} = -k(x - l_0) + \mu_c N$

$$m\ddot{y} = N - mg \quad \downarrow = mg$$

se tiene

$$m\ddot{x} = -k(x - l_0) + \mu_c mg$$

$$m \dot{x} \frac{d\dot{x}}{dx} = -k(x - l_0) + \mu_c mg \quad \bigg| \int_{l_0}^{\Delta} dx$$

buscamos el punto más cercano (llega con vel = 0)

parte con vel. v_0

$$m \int_{-v_0}^0 \dot{x} d\dot{x} = -k \int_{l_0}^{\Delta} dx (x - l_0) + \mu_c mg \int_{l_0}^{\Delta} dx$$

$$m \left. \frac{\dot{x}^2}{2} \right|_{-v_0}^0 = -k \left(\frac{x^2}{2} \Big|_{l_0}^{\Delta} - l_0(\Delta - l_0) \right) + \mu_c mg (\Delta - l_0)$$

$$-\frac{m}{2} v_0^2 = -k \left(\frac{\Delta^2}{2} - \frac{l_0^2}{2} - l_0\Delta + l_0^2 \right) + \mu_c mg \Delta - \mu_c mg l_0$$

$$0 = -\frac{k}{2} \Delta^2 + \Delta(k l_0 + \mu_c mg) - k \frac{l_0^2}{2} - \mu_c mg l_0 + \frac{m}{2} v_0^2$$

$$\Rightarrow \Delta = \frac{-\mu_c mg - k l_0 \pm \sqrt{(k l_0 + \mu_c mg)^2 - 4 \frac{k}{2} \left(\frac{k l_0^2}{2} + \mu_c mg l_0 - \frac{m}{2} v_0^2 \right)}}{-k}$$

$$= l_0 + \frac{\mu_c mg}{k} \mp \frac{1}{k} \sqrt{\cancel{k l_0^2} + \mu_c^2 m^2 g^2 + \cancel{2 k l_0 \mu_c mg} - \cancel{k^2 l_0^2} - \cancel{2 k \mu_c mg l_0} + k m v_0^2}$$

$$= l_0 + \frac{\mu_c mg}{k} \mp \frac{1}{k} \sqrt{k m v_0^2 + \mu_c^2 m^2 g^2}$$

Luego, tenemos:

$$\mu_c 2mg = k(l_0 - \Delta)$$

$$= \cancel{k} \left(-\frac{\mu_c mg}{\cancel{k}} + \frac{1}{\cancel{k}} \sqrt{k m v_0^2 + \mu_c^2 m^2 g^2} \right)$$

$$(2\mu_c + \mu_c) mg = \sqrt{k m v_0^2 + \mu_c^2 m^2 g^2} \quad / ()^2$$

$$(4\mu_c^2 + \cancel{\mu_c^2} + 4\mu_c \mu_c) m^2 g^2 = k m v_0^2 + \cancel{\mu_c^2 m^2 g^2}$$

$$(4\mu_c^2 + 4\mu_e\mu_c) m^2 g^2 = k m v_0^2$$

$$v_0^2 = \frac{4mg^2 \mu_e (\mu_e + \mu_c)}{k}$$

b) $\mu_e = \mu_c = 0$

Usaremos

$$K = \frac{1}{2} M v_{cm}^2 + \frac{1}{2} \sum_i m_i \dot{r}_i^2$$

viene de

$$K = \frac{1}{2} \sum_i m_i v_i^2, \text{ pero}$$

$$\vec{r}_i = \vec{r}_{cm} + \vec{r}_i \quad \bigg/ \frac{d}{dt}$$

$$\vec{v}_i = \vec{v}_{cm} + \dot{\vec{r}}_i$$

$$= \frac{1}{2} \sum_i m_i (\underbrace{\vec{v}_{cm} + \dot{\vec{r}}_i}_{v_{cm}^2 + \dot{r}_i^2 + 2\vec{v}_{cm} \cdot \dot{\vec{r}}_i})^2$$

$$= \frac{1}{2} \left[\underbrace{\sum_i m_i v_{cm}^2}_M + \sum_i m_i \dot{r}_i^2 + \sum_i m_i 2\vec{v}_{cm} \cdot \dot{\vec{r}}_i \right]$$

$$= \frac{1}{2} M \vec{v}_{cm}^2 + \frac{1}{2} \sum_i m_i \dot{r}_i^2 + \vec{v}_{cm} \cdot \sum_i m_i \dot{\vec{r}}_i$$

es la velocidad del CM c/r al CM, tiene que ser cero

Veamos $\vec{v}_{cm}$, sabemos que

$$M \vec{a}_{cm} = \vec{F}^{ext} = -2mg \hat{z} + \underbrace{N_{2m}}_{2mg} \hat{z} - mg \hat{z} + \underbrace{N_m}_{mg} \hat{z}$$

$$= 0$$

$$\Rightarrow \vec{v}_{cm} = cte = \vec{v}_{cm}(t=0) = \frac{1}{M} \sum_i m_i v_i$$

$$= \frac{1}{3m} (2m \cdot 0 - m v_0 \hat{x})$$

$$= -\frac{v_0}{3} \hat{x}$$

Por lo que

$$K = \frac{1}{2} 3m \frac{v_0^2}{9} + \frac{1}{2} \sum_i m_i \dot{r}_i^2$$

$$\hookrightarrow E = \frac{1}{2} 3m \frac{v_0^2}{9} + \frac{1}{2} \sum_i m_i \dot{r}_i^2 + \frac{1}{2} k (\underbrace{l - l_0}_s)^2$$

en el tiempo inicial

$$K_i = \frac{1}{2} m v_0^2 \text{ y } U_i = 0 \Rightarrow E_i = \frac{1}{2} m v_0^2$$

y cuando l es mínimo (máxima compresión) $\dot{r}_i = 0$, si no se seguiría comprimiendo

$$E_f = \frac{1}{2} 3m \frac{v_0^2}{9} + \frac{1}{2} k s_{min}^2 = \frac{1}{2} m v_0^2 \quad \leftarrow E_i$$

$$s^2 = (l - l_0)^2 / \Gamma$$

$$|s^2| = |l - l_0|$$

$$k s_{min}^2 = m v_0^2 (1 - \frac{1}{3})$$

$$|l_{min} - l_0| = \sqrt{\frac{2}{3} \frac{m v_0^2}{k}} \quad //$$

$$l_{min} = l_0 - \sqrt{\frac{2m v_0^2}{3k}}$$