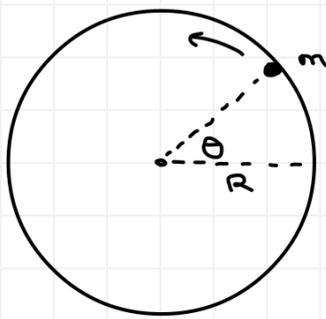


PA



- roce viscoso cuadrático coef. η
- roce cinético coef. μ
- $\eta = \mu R$

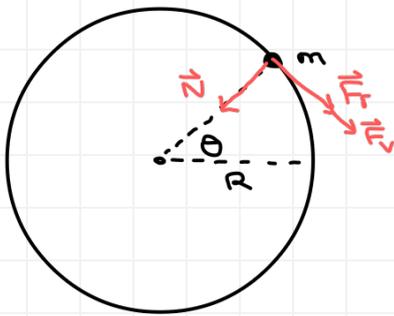
- A)
- Partícula lanzada en $t=0$ desde $\theta=0$, con vel. angular ω_0
 - Calcular W de \vec{F}_{rota} en fn. de t .

Se define el trabajo W de una fuerza \vec{F} como la integral de línea sobre la trayectoria de la partícula:

$$W = \int_C \vec{F} \cdot d\vec{r}$$

del:

fuerzas: contacto: \vec{N} y \vec{F}_r
roce visc.: \vec{F}_v



en polares:

$$\vec{N} = -N\hat{\rho} \quad \vec{F}_r = -\mu N\hat{\theta}$$

$$\vec{v} = \dot{\rho}\hat{\rho} + \rho\dot{\theta}\hat{\theta} = R\dot{\theta}\hat{\theta} \rightarrow v^2 = R^2\dot{\theta}^2$$

$$\vec{F}_v = -\eta v^2\hat{\theta} = -\eta R^2\dot{\theta}^2\hat{\theta}$$

$$\vec{F} = \vec{N} + \vec{F}_r + \vec{F}_v$$

Como queremos $W(t)$, tomamos $d\vec{r} = \vec{v} dt$:

$$\begin{aligned} W &= \int_0^t \vec{F} \cdot \vec{v} dt \\ &= \int_0^t \vec{N} \cdot \vec{v} dt + \int_0^t \vec{F}_r \cdot \vec{v} dt + \int_0^t \vec{F}_v \cdot \vec{v} dt \\ &= \int_0^t -\mu N \cdot R\dot{\theta} dt + \int_0^t -\eta R^2\dot{\theta}^2 \cdot R\dot{\theta} dt \\ &= -\mu R \int_0^t N\dot{\theta} dt - \eta R^3 \int_0^t \dot{\theta}^3 dt \end{aligned}$$

Necesitamos $N(t)$ y $\dot{\Theta}(t)$ para poder integrar. Podemos sacar info. de las ec. de mov.

$$\vec{a} = (\cancel{\dot{\rho}} - \rho \dot{\Theta}^2) \hat{\rho} + (\cancel{2\dot{\rho}\dot{\Theta}} + \rho \ddot{\Theta}) \hat{\Theta}$$

$$\vec{a} = -R\dot{\Theta}^2 \hat{\rho} + R\ddot{\Theta} \hat{\Theta}$$

Newton:

$$-mR\dot{\Theta}^2 \hat{\rho} + mR\ddot{\Theta} \hat{\Theta} = -N\hat{\rho} - \mu N\hat{\Theta} - \eta R^2 \dot{\Theta}^2 \hat{\Theta}$$

$$\bullet \hat{\rho}: \quad -mR\dot{\Theta}^2 = -N \rightarrow \underline{N = mR\dot{\Theta}^2}$$

$$\bullet \hat{\Theta}: \quad mR\ddot{\Theta} = -\mu N - \eta R^2 \dot{\Theta}^2$$

$$mR\ddot{\Theta} = -\mu mR\dot{\Theta}^2 - \frac{\eta\mu}{R} R^2 \dot{\Theta}^2$$

$$(*) \quad \ddot{\Theta} = -2\mu\dot{\Theta}^2 \quad \left| \ddot{\Theta} = \frac{d\dot{\Theta}}{dt}\right.$$

$$\frac{d\dot{\Theta}}{dt} = -2\mu\dot{\Theta}^2$$

$$\int_{\dot{\Theta}_0}^{\dot{\Theta}} \frac{1}{\dot{\Theta}^2} d\dot{\Theta} = -2\mu \int_{t=0}^t dt$$

$$-\frac{1}{\dot{\Theta}} + \frac{1}{\dot{\Theta}_0} = -2\mu t$$

$$\frac{1}{\dot{\Theta}} = \frac{1}{\dot{\Theta}_0} + 2\mu t = \frac{1 + 2\dot{\Theta}_0 \mu t}{\dot{\Theta}_0}$$

$$\underline{\dot{\Theta}(t) = \frac{\dot{\Theta}_0}{1 + 2\dot{\Theta}_0 \mu t}} \quad \rightarrow N(\dot{\Theta}(t)) = mR\dot{\Theta}^2(t)$$

$$\begin{aligned} W(t) &= -\mu R \int N \dot{\Theta} dt - \eta R^3 \int \dot{\Theta}^3 dt \\ &= -\mu R \int mR\dot{\Theta}^3 dt - \frac{\eta\mu}{R} R^3 \int \dot{\Theta}^3 dt \\ &= -2\mu m R^2 \int_0^t \dot{\Theta}^3(t) dt \end{aligned}$$

$$\begin{aligned}
\int_0^t \ddot{\theta}^3 dt &= \int_0^t \left(\frac{\omega_0}{1+2\omega_0\mu t} \right)^3 dt & \tau = 2\omega_0\mu t \rightarrow d\tau = 2\omega_0\mu dt \\
&= \omega_0^3 \int_0^{2\omega_0\mu t} \frac{1}{(1+\tau)^3} \frac{d\tau}{2\omega_0\mu} \\
&= \frac{\omega_0^2}{2\mu} \int \frac{d\tau}{(1+\tau)^3} \\
&= \frac{\omega_0^2}{2\mu} \left[-\frac{1}{2(\tau+1)^2} \right]_0^{2\omega_0\mu t} \\
&= \frac{\omega_0^2}{2\mu} \cdot \left(\frac{1}{2} - \frac{1}{2(1+2\omega_0\mu t)^2} \right) \\
&= \frac{\omega_0^2}{4\mu} \left(\frac{(1+2\omega_0\mu t)^2 - 1}{(1+2\omega_0\mu t)^2} \right) \\
&= \frac{\omega_0^2}{4\mu} \cdot \frac{4\omega_0\mu t + 4\omega_0^2\mu^2 t^2}{(1+2\omega_0\mu t)^2} \\
&= \omega_0^3 t \cdot \frac{1 + \mu\omega_0 t}{(1+2\omega_0\mu t)^2}
\end{aligned}$$

$$W(t) = -2\mu m R^2 \omega_0^3 t \cdot \frac{1 + \mu\omega_0 t}{(1+2\omega_0\mu t)^2}$$

B) Trabajo al recorrer media circ. \rightarrow trayectoria $\theta = 0$ a $\theta = \pi$

$$W = -2\mu m R^2 \int_0^t \ddot{\theta}^3(t) dt$$

$$W(\theta) = -2\mu m R^2 \int_0^\theta \ddot{\theta}^2 \frac{d\theta}{d\theta} dt$$

Necesitamos $\dot{\theta}(\theta)$. De (*):

$$\ddot{\theta} = -2\mu \dot{\theta}^2$$

$$\ddot{\theta} = \frac{d\dot{\theta}}{dt} = \frac{d\dot{\theta}}{d\theta} \cdot \dot{\theta}$$

$$\dot{\theta} d\dot{\theta} = -2\mu \dot{\theta}^2 d\theta$$

$$\frac{1}{\dot{\theta}} d\dot{\theta} = -2\mu\theta \quad \Big| \int_0^\theta$$

$$\ln \dot{\theta} / \omega_0 = -2\mu\theta$$

$$\dot{\theta} = \omega_0 e^{-2\mu\theta}$$

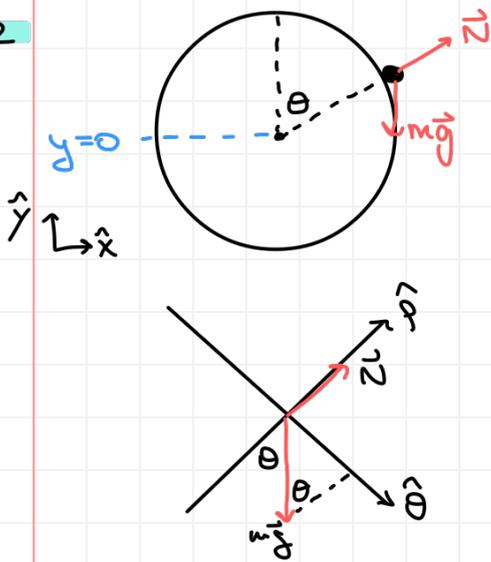
$$W(\theta) = -2\mu m R^2 \int_0^\theta \dot{\theta}^2 d\theta$$

$$= -2\mu m R^2 \int \omega_0^2 e^{-4\mu\theta} d\theta$$

$$= -2\omega_0^2 \mu m R^2 \cdot -\frac{1}{4\mu} (e^{-4\mu\theta} - 1)$$

$$= \frac{1}{2} \omega_0^2 m R^2 (e^{-4\mu\theta} - 1) \quad / \theta = \pi$$

$$W(\pi) = \frac{1}{2} \omega_0^2 m R^2 \underbrace{(e^{-4\mu\pi} - 1)}_{< 0} < 0 \quad \text{--- perda de E}$$



$$\vec{N} = N \hat{p}$$

$$m\vec{g} = mg(-\cos\theta \hat{p} + \sin\theta \hat{\theta})$$

$$\vec{a} = (\ddot{p} - p\dot{\theta}^2) \hat{p} + (2\dot{p}\dot{\theta} + p\ddot{\theta}) \hat{\theta}$$

$$m\vec{a} = \vec{F}$$

\hat{p} : $-mR\dot{\theta}^2 = N - mg\cos\theta$ — condición en $\dot{\theta}$ y θ para despegue

$$\underline{R\dot{\theta}^2 = g\cos\theta} \quad (1)$$

conservación de energía:

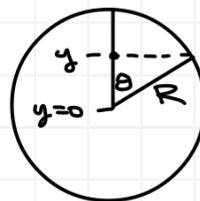
en el punto inicial, $\theta = 0$

$$K_i = \frac{1}{2}mv_i^2 \approx 0 \quad (v_i > 0 \text{ muy pequeño})$$

$$U_i = mgR$$

en el punto de despegue $v^2 = R^2\dot{\theta}^2$ ($\vec{v} = \dot{p}\hat{p} + R\dot{\theta}\hat{\theta}$)

$$K_d = \frac{1}{2}mR^2\dot{\theta}^2$$



$$\cos\theta = \frac{y}{R}$$

$$U_d = mgR\cos\theta$$

$$\Delta E = 0 \rightarrow 0 + mgR = \frac{1}{2}mR^2\dot{\theta}^2 + mgR\cos\theta$$

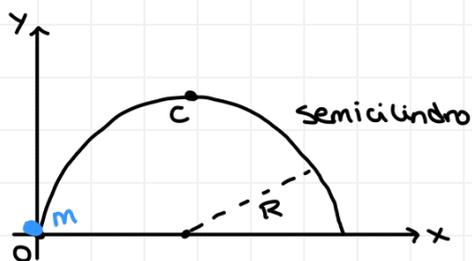
$$\underline{g(1 - \cos\theta) = R\dot{\theta}^2} \quad (2)$$

(1) = (2)

$$\frac{2g}{R}(1 - \cos\theta) = \frac{g}{R}\cos\theta$$

$$\cos\theta = \frac{2}{3} \rightarrow \theta = \frac{\pi}{3}$$

P3



- $\vec{F}_1 = -c(xy^2\hat{x} + x^2y\hat{y})$
- \vec{F}_2 permite rapidez cte en la superficie

A) \vec{F} es conservativa si y solo si

$$\oint \vec{F} \cdot d\vec{r} = 0 \quad (1)$$

$$\Leftrightarrow \vec{F} = -\nabla U \quad (2)$$

$$\Leftrightarrow \nabla \times \vec{F} = 0 \longrightarrow \begin{cases} \partial_y F_z = \partial_z F_y \\ \partial_z F_x = \partial_x F_z \\ \partial_x F_y = \partial_y F_x \end{cases} \quad (3)$$

Método (3):

$$\vec{F}_1 = -c(xy^2\hat{x} + x^2y\hat{y})$$

$$\partial_y F_{1z} = 0 = \partial_z F_{1y}$$

$$\partial_z F_{1x} = 0 = \partial_x F_{1z}$$

$$\partial_x F_{1y} = -2cxy = \partial_y F_{1x} = -2cxy \longrightarrow \vec{F}_1 \text{ es cons.}$$

Método (2):

Supongamos que existe U tal que $-\nabla U = \vec{F}_1$. Si lo encontramos, entonces bn :-

$$\vec{F}_1 = -\nabla U \longrightarrow \begin{aligned} \partial_x U = cxy^2 &\longrightarrow U = \frac{c}{2}x^2y^2 + A(y,z) \\ \partial_y U = cx^2y &\longrightarrow U = \frac{c}{2}x^2y^2 + A(z) \\ \partial_z U = 0 &\longrightarrow U \text{ cte en } z \end{aligned}$$

$$U = \frac{1}{2}cx^2y^2 + A \longrightarrow \vec{F}_1 = -\nabla U \text{ y es conservativa, asociada al pot. } U.$$

