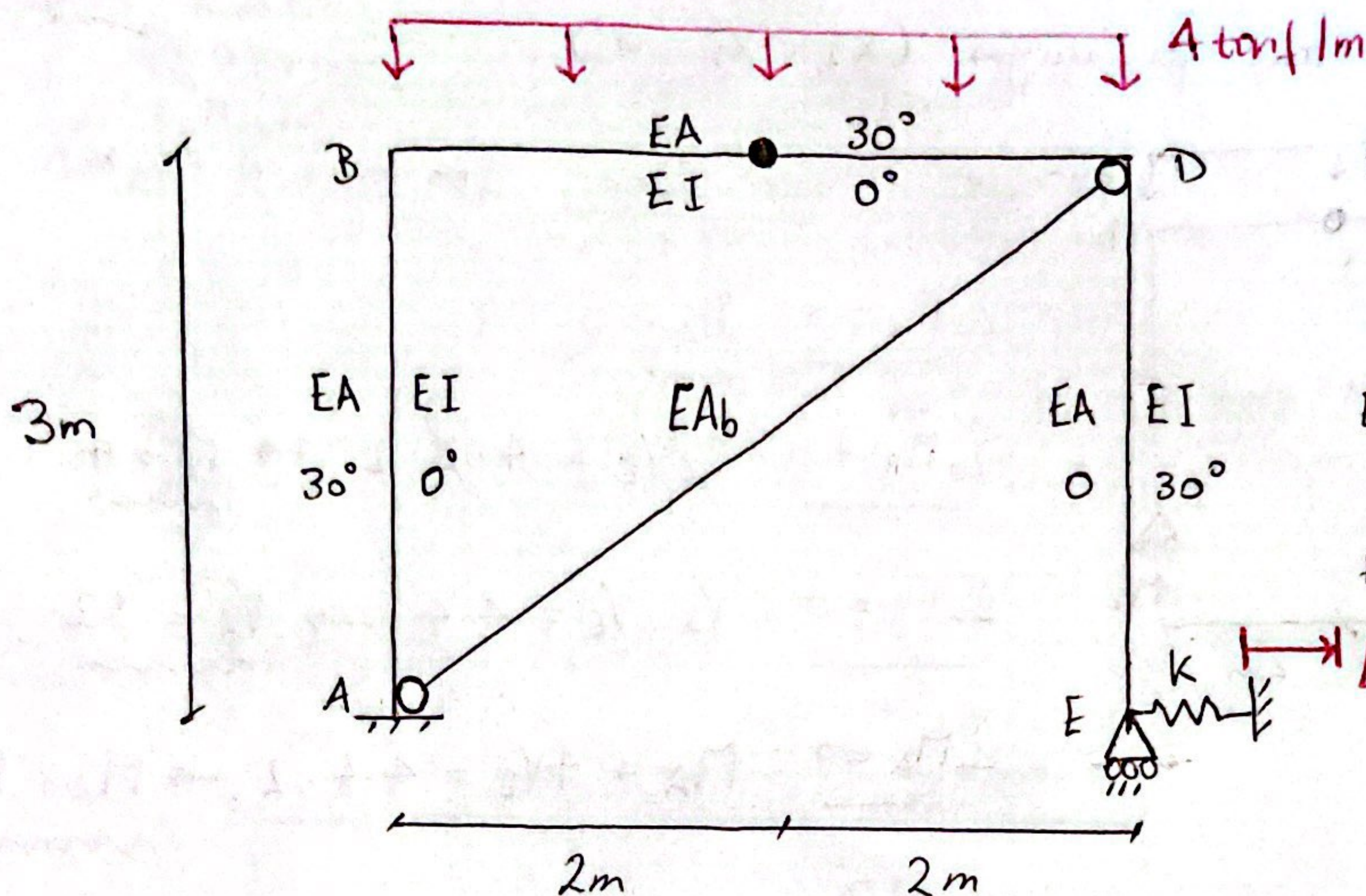


Pauta Auxiliar 2 - P1

Luis Cárcamo Del Río



$$\begin{aligned} EA &= 10000 [\text{tonf}] \\ \alpha &= 0,0001 [1/^\circ\text{C}] \\ h &= 0,3 [\text{m}] \\ EI &= 1000 [\text{tonf} \cdot \text{m}^2] \\ k &= 50 [\text{tonf}/\text{m}^2] \\ EAb &= 800 [\text{tonf}] \end{aligned}$$

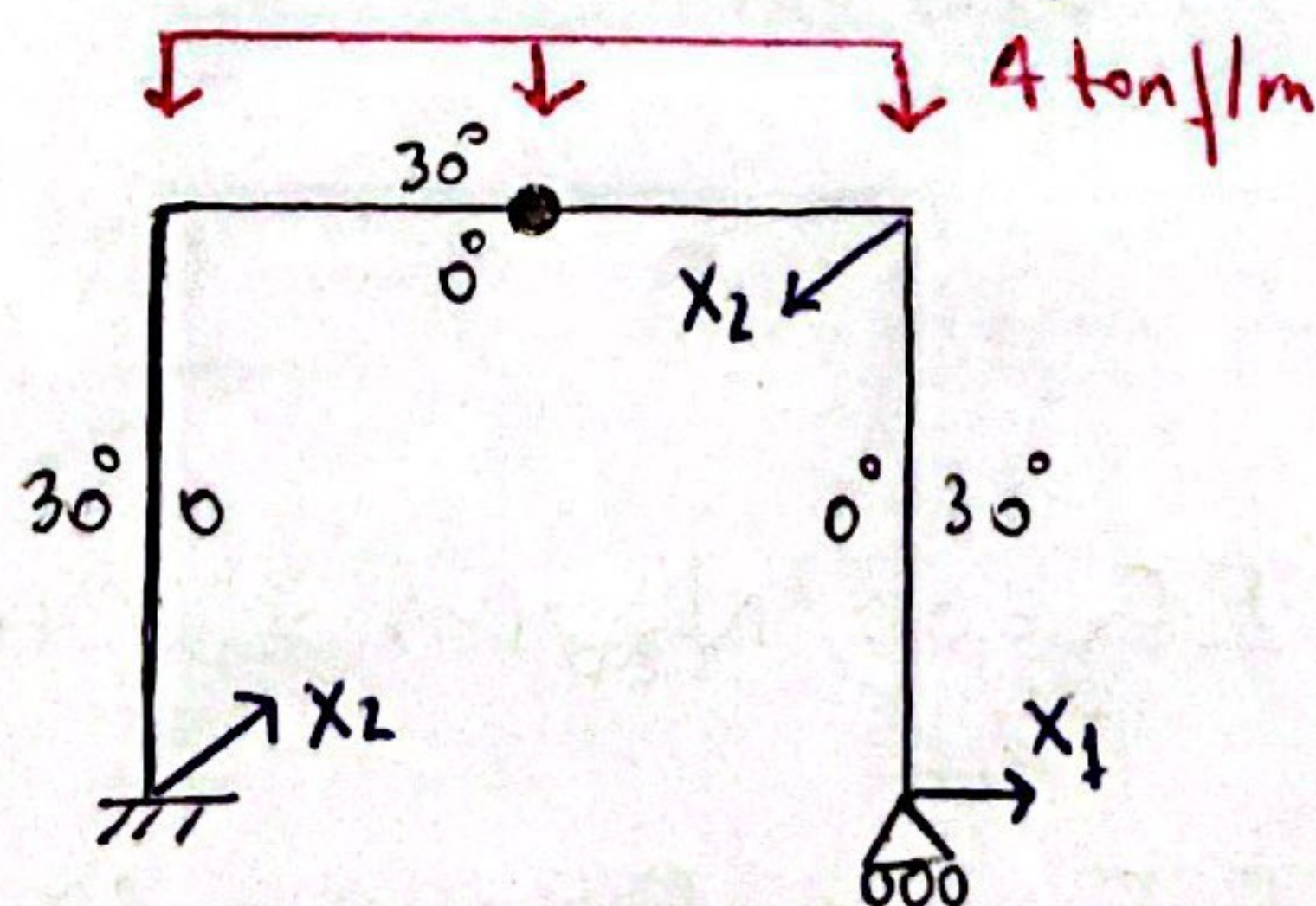
1º: Determinar GIE. (# Incógnitas - # Ecuaciones)

$$GIE = 3 + 2 + 1 - (3 + 1) = 2$$

$\uparrow$ $\uparrow$ $\uparrow$ $\uparrow$
 $\frac{1}{m}$ Δ $-\text{m}$ Δ
 3 de equilibrio
 1 de rótula

2º: Definir Estructura Isostática Fundamental (EIF)

⊛ Se recomienda liberar bielas y resortes.



⊛ Recordando que el método de flexibilidad es:

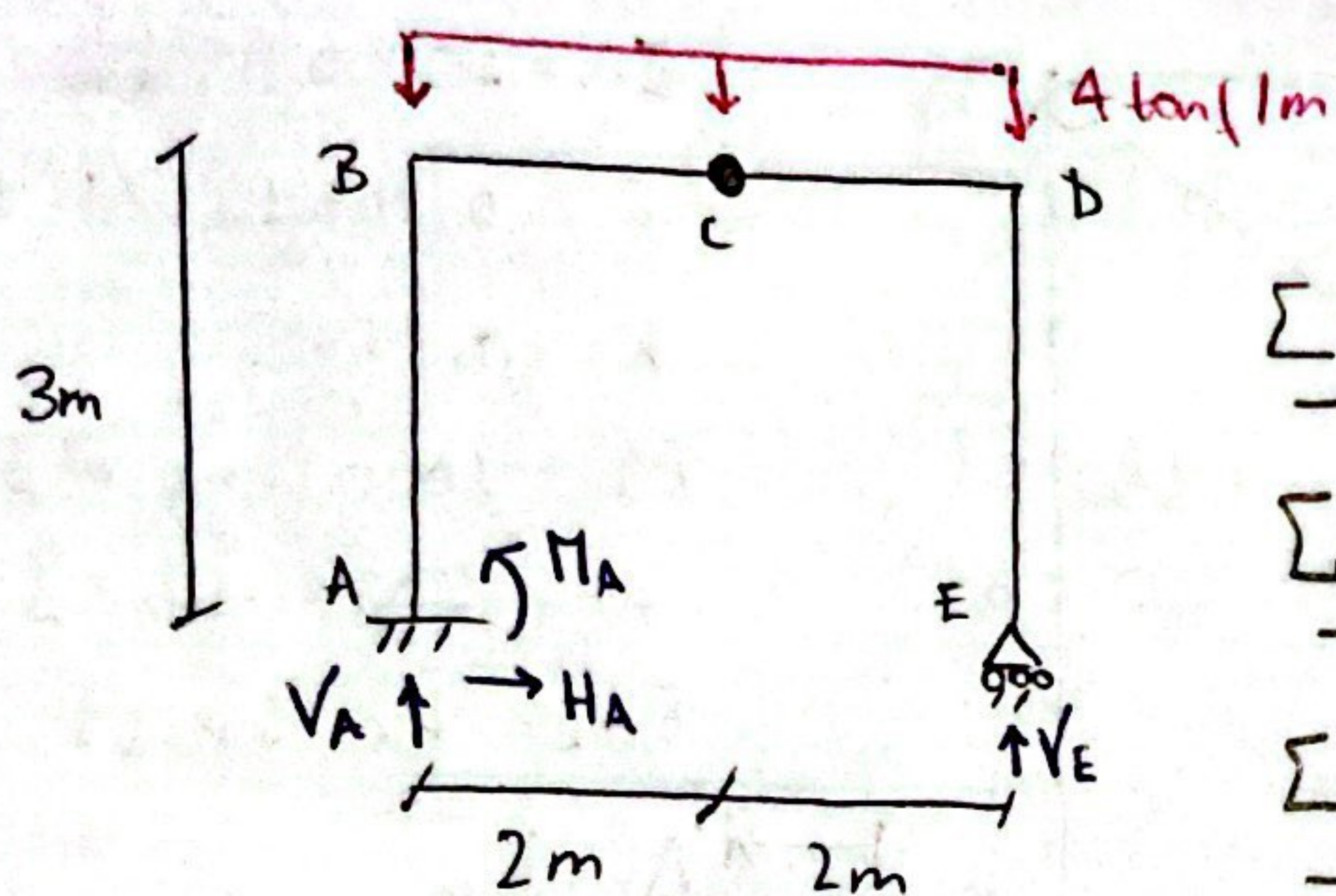
$$\{\Delta\}_H + \{\Delta\}_A = \{\Delta\}_Q + \{\Delta\}_T + \{\Delta\}_e + [F] \cdot \{R\}$$

(HIPERESTÁTICO) (ASENTAMIENTO) (CARGA) (TEMPERATURA) (ERROR DE FABR) [MATRIZ DE FLEX]

→ (REDUNDANTES)

3º: Obtención de diagramas de esfuerzos internos (EIF, X_1 , X_2)

3.1: EIF, sistema real de cargas ($X_1 = X_2 = 0$)



Reacciones: (en tonf ó tonf/m)

$$\underline{\sum F_x = 0} : H_A = 0$$

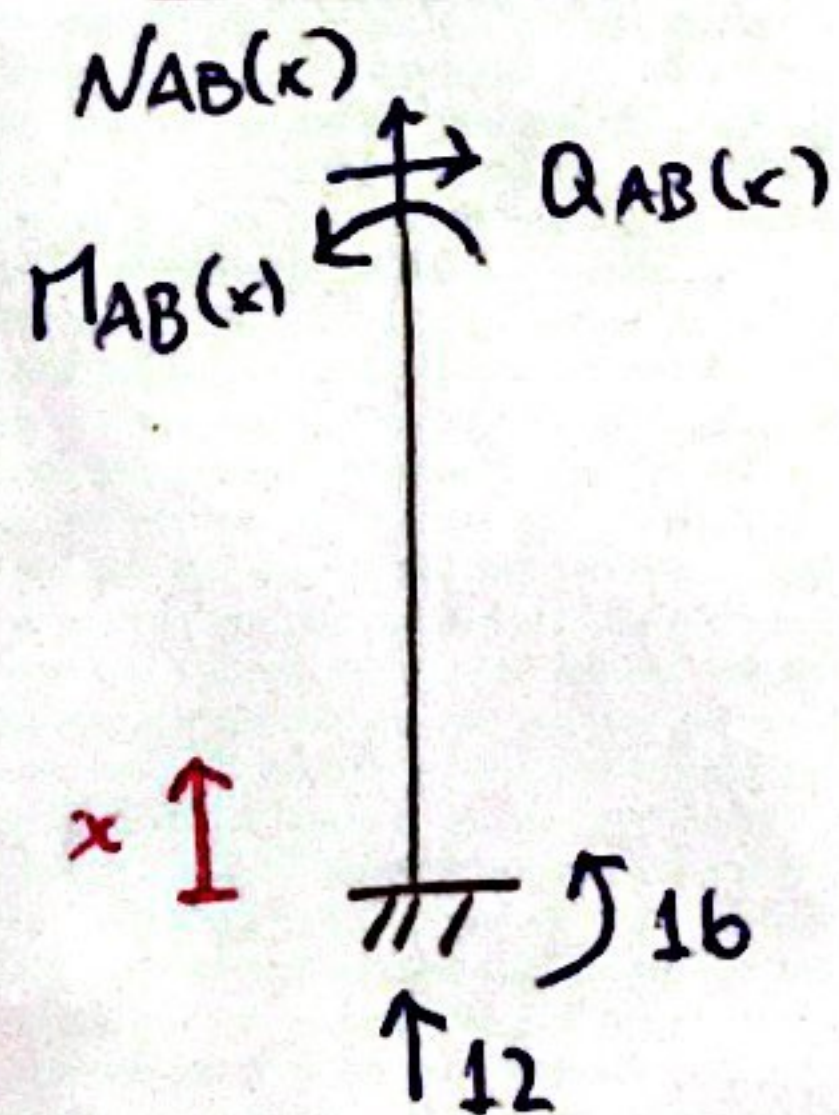
$$\underline{\sum \vec{M}_R = 0} : \cancel{2} V_E = 4 \cdot \cancel{2} \cdot 1 \rightarrow V_E = 4$$

$$\underline{\sum F_y = 0} : V_A + V_E = 4 \cdot 4 \rightarrow V_A = 12$$

$$\underline{\sum M_A = 0} : M_A + 4 V_E = 4 \cdot 4 \cdot 2 \rightarrow M_A = 16$$

D.E.I.:

- Tramo AB: $x \in [0, 3]$

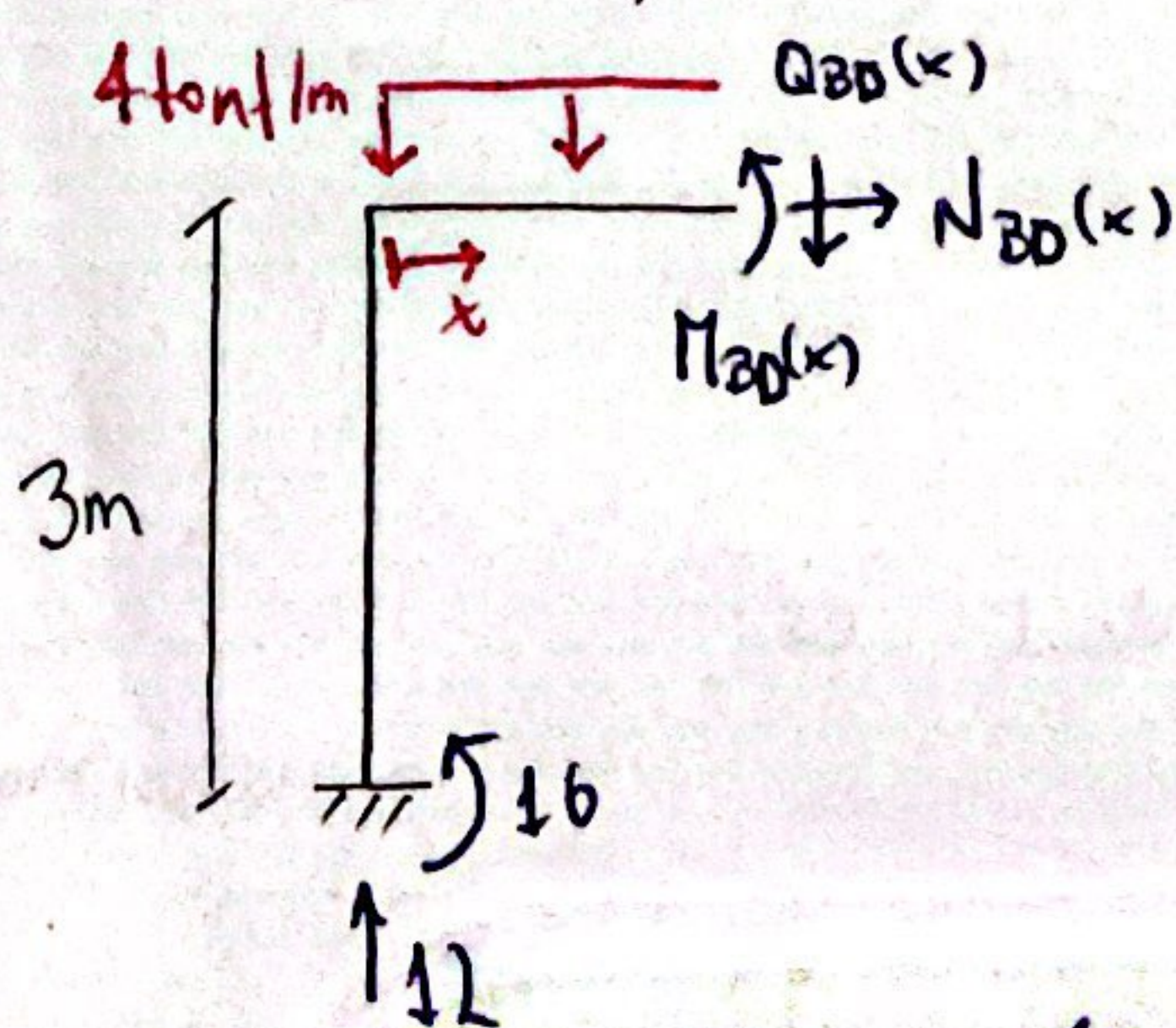


$$\underline{\sum F_y = 0} : N_{AB}(x) = -12 \text{ tonf}$$

$$\underline{\sum F_x = 0} : Q_{AB}(x) = 0 \text{ tonf}$$

$$\underline{\sum M_x = 0} : M_{AB}(x) = -16 \text{ tonf-m}$$

- Tramo BD: $x \in [0, 4]$



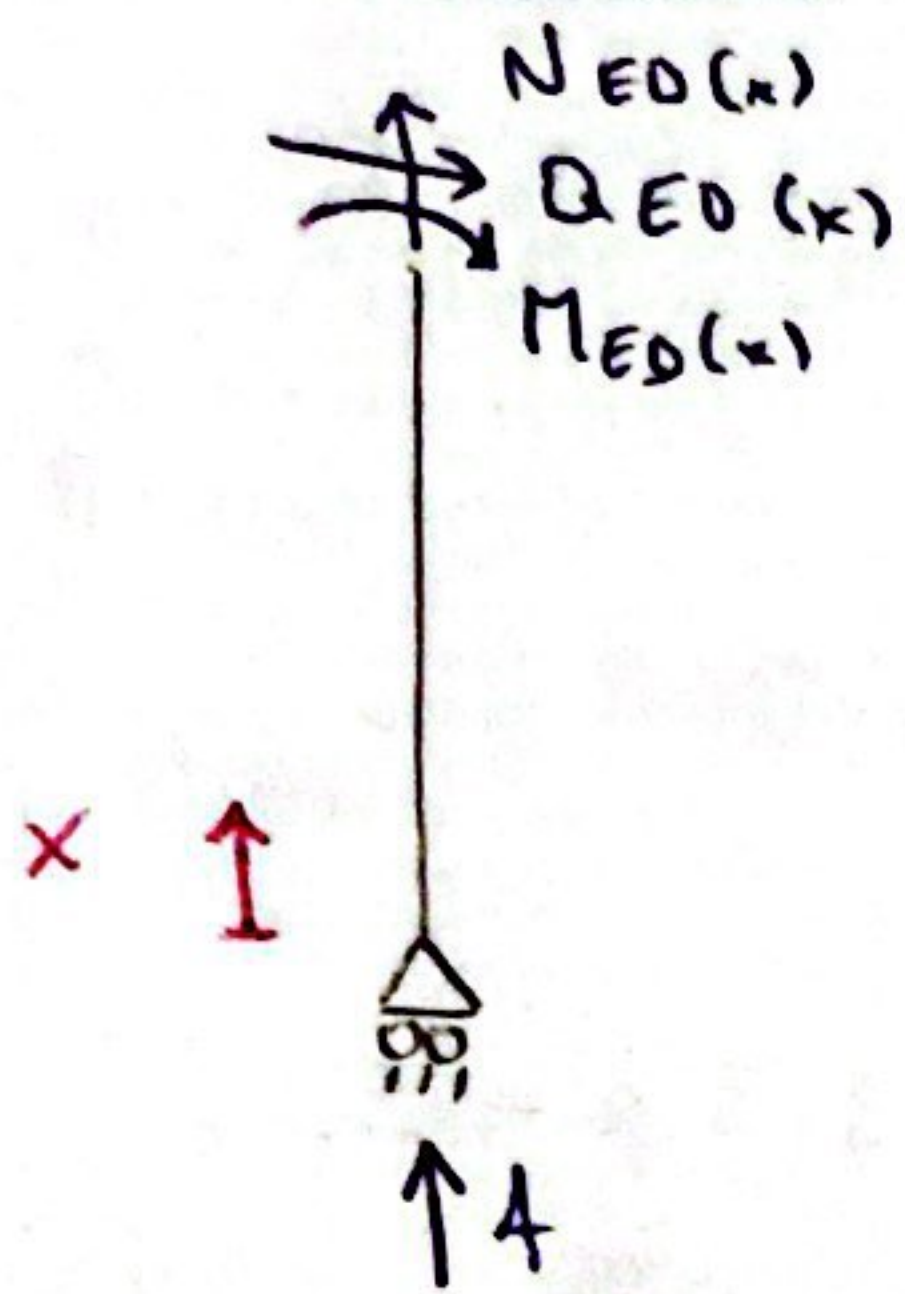
$$\underline{\sum F_x = 0} : N_{BD}(x) = 0 \text{ tonf}$$

$$\underline{\sum F_y = 0} : Q_{BD}(x) = 12 - 4x$$

$$\underline{\sum M_x = 0} : M_{BD}(x) = -16 + 12x - 2x^2$$

(Evaluar en $x=0$, $x=2$ y $x=4$)

- Tramo ED: $x \in [0,3]$

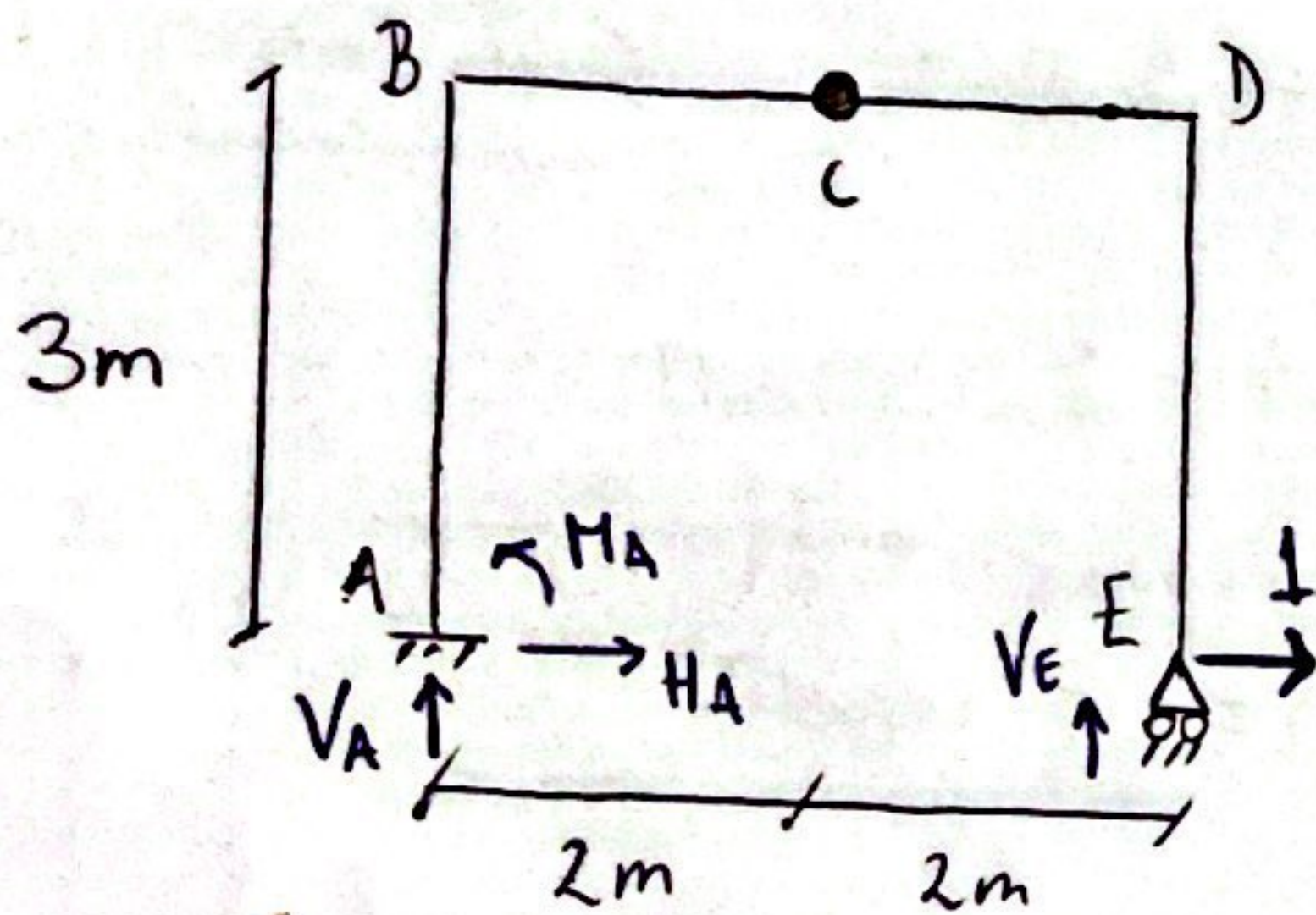


$$\sum F_y = 0 : N_{ED}(x) = -4 \text{ tonf}$$

$$\sum F_x = 0 : Q_{ED}(x) = 0 \text{ tonf}$$

$$\sum M_x = 0 : M_{ED}(x) = 0 \text{ tonf-m}$$

3.2: ($x_1 = 1 \wedge x_2 = 0$)



Reacciones:

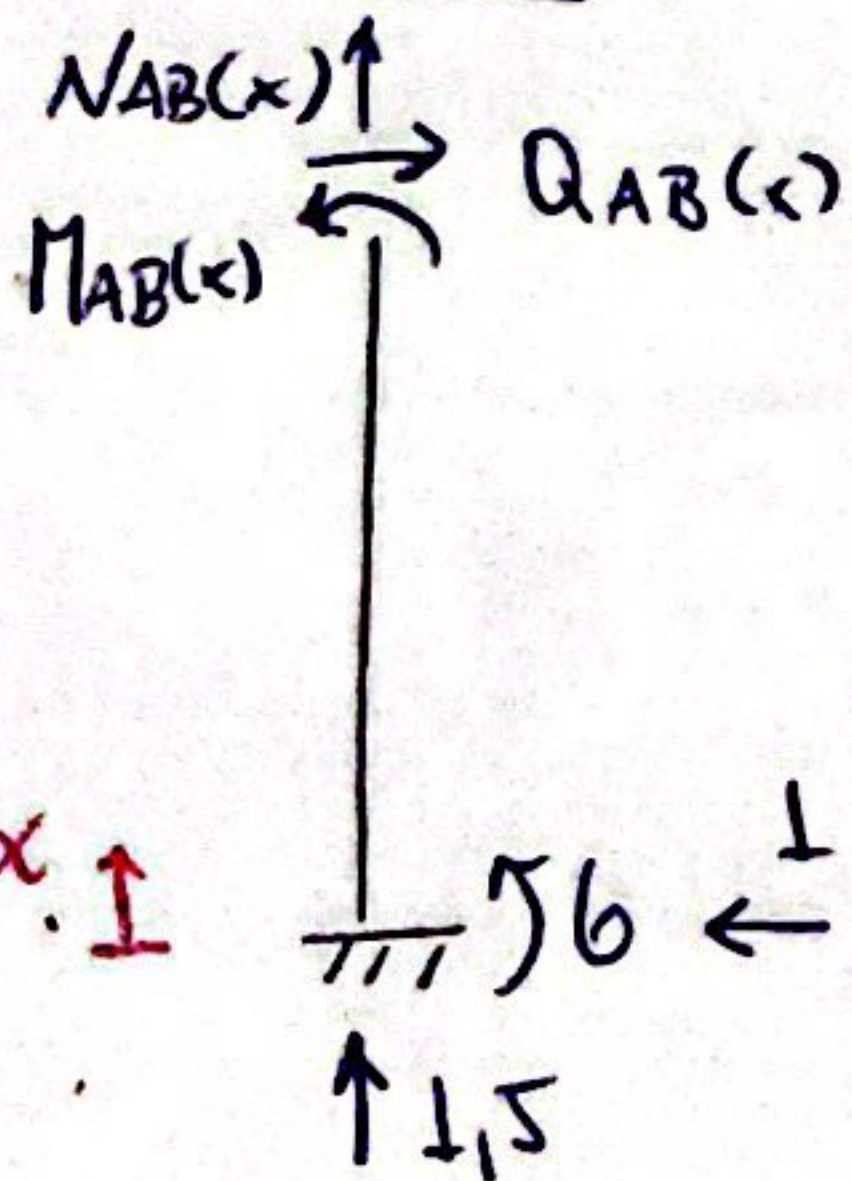
$$\sum F_x = 0 : H_A = -1$$

$$\sum \vec{M}_R = 0 : 2V_E = -1 \cdot 3 \rightarrow V_E = -1,5$$

$$\sum F_y = 0 : V_A + V_E = 0 \rightarrow V_A = 1,5$$

$$\sum M_A = 0 : M_A + 4V_E \rightarrow M_A = 6$$

- Tramo AB: $x \in [0,3]$

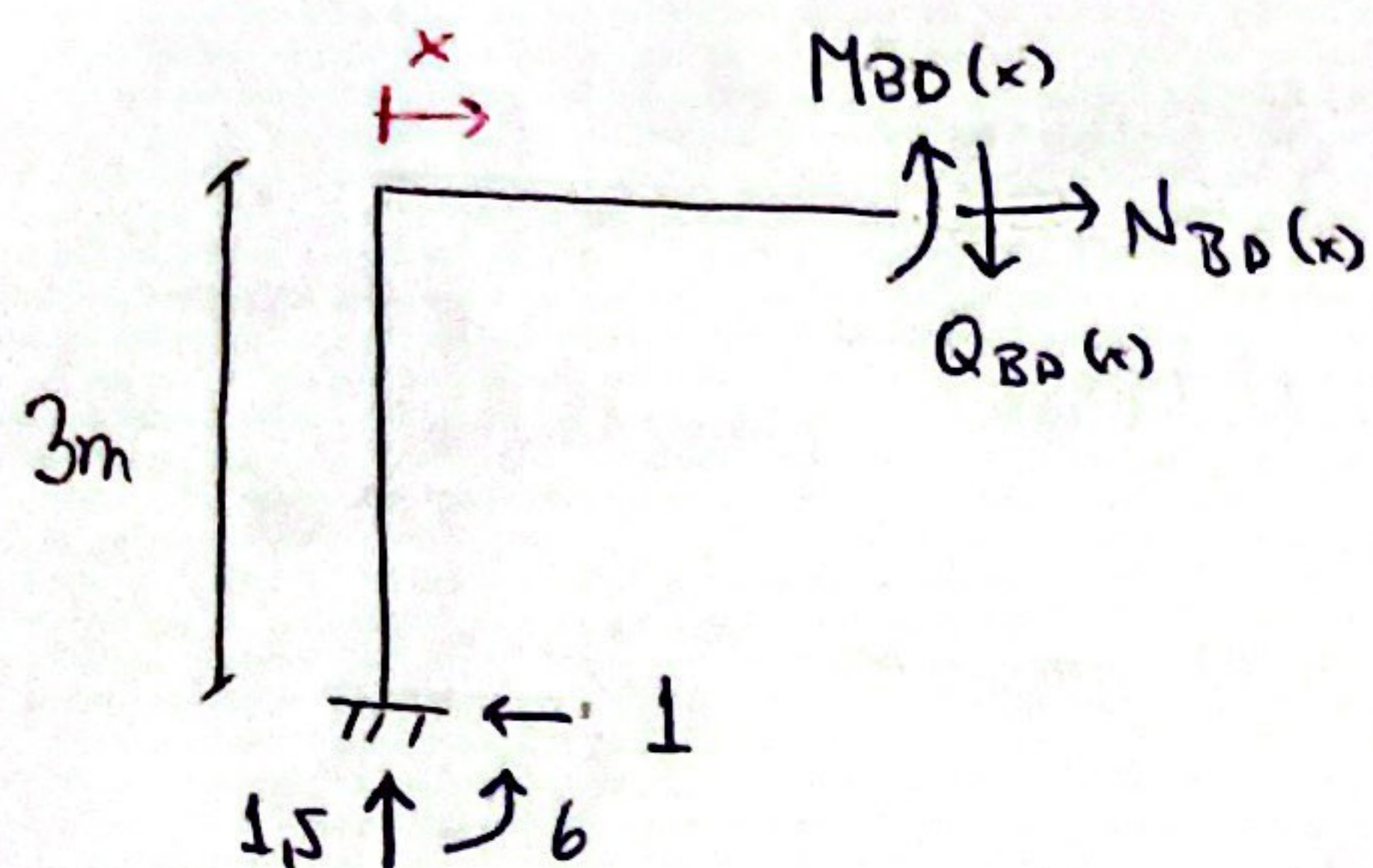


$$\sum F_y = 0 : N_{AB}(x) = -1,5$$

$$\sum F_x = 0 : Q_{AB}(x) = 1$$

$$\sum M_x = 0 : M_{AB}(x) = x - 6$$

- Tramo BD : $x \in [0, 4]$

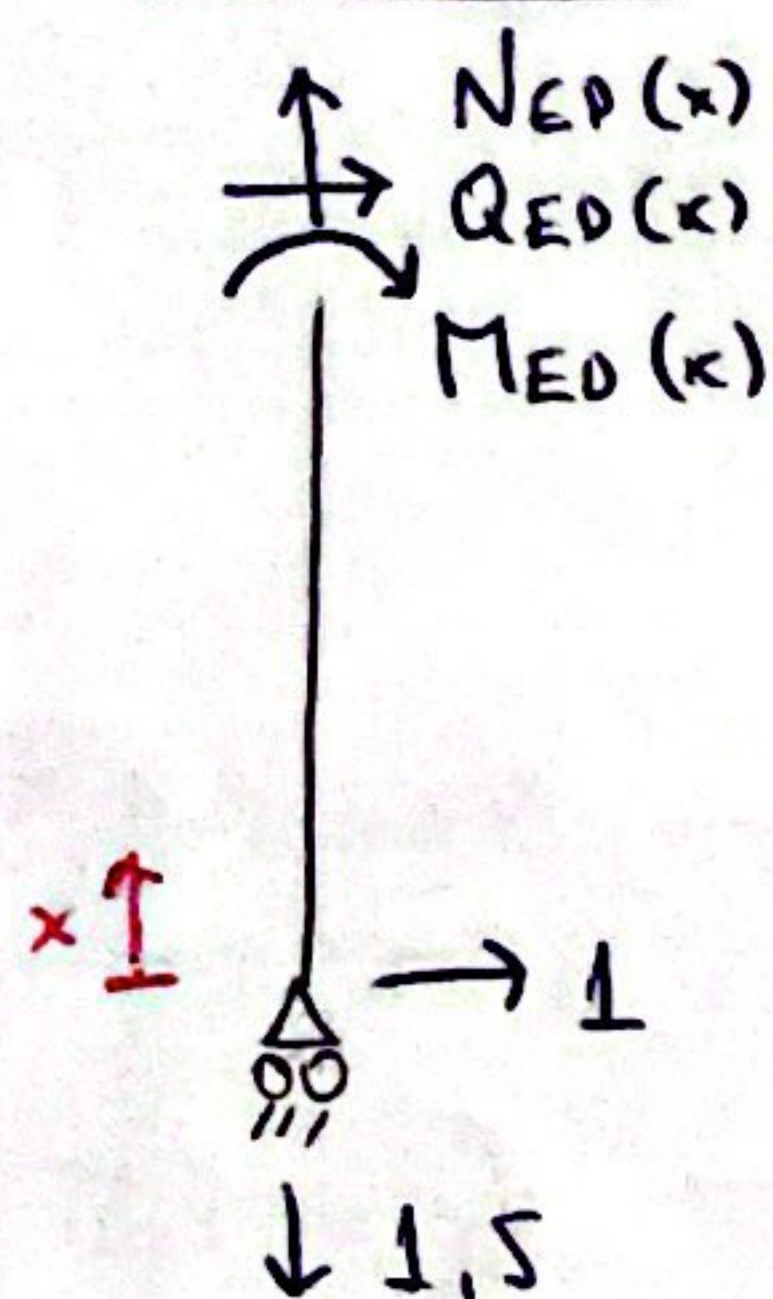


$$\sum F_x = 0 : N_{BD}(x) = 1$$

$$\sum F_y = 0 : Q_{BD}(x) = 1,5$$

$$\sum M_x = 0 : M_{BD}(x) = 1,5x - 3$$

- Tramo ED : $x \in [0, 2]$

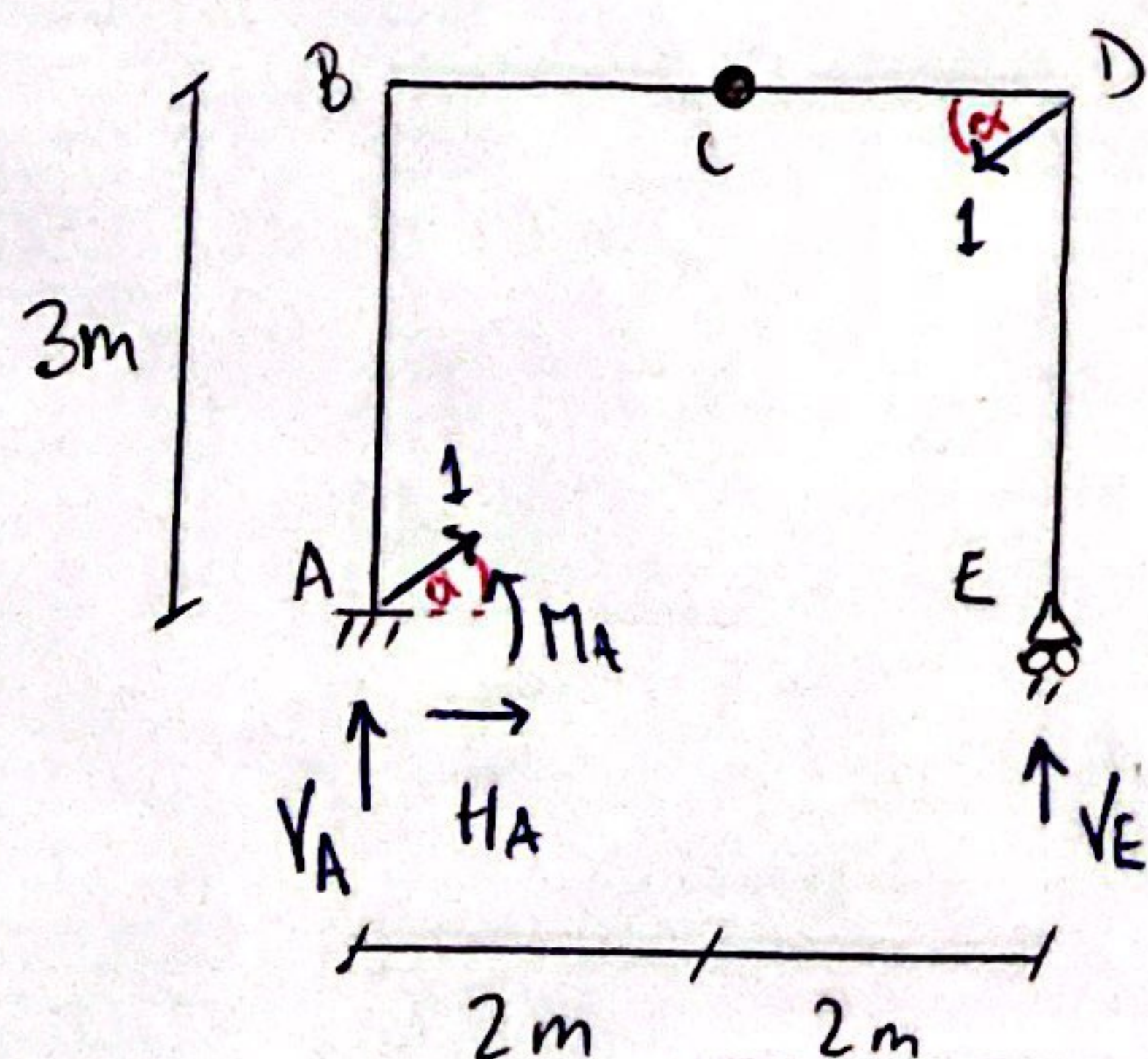


$$\sum F_y = 0 : N_{ED}(x) = 1,5$$

$$\sum F_x = 0 : Q_{ED}(x) = -1$$

$$\sum M_x = 0 : M_{ED}(x) = x$$

3.3 : ($x_1 = 0 \wedge x_2 = 1$)



Reacciones :

$$\sum F_x = 0 : H_A = 0$$

$$\sum \vec{M}_R = 0 : 2V_E = \frac{3}{5} \cdot 4 \rightarrow V_E = 0,6$$

$$\sum F_y = 0 : V_A + V_E = 0 \rightarrow V_A = -0,6$$

$$\sum M_A = 0 : M_A + 4V_E + \frac{4}{5} \cdot 3 - \frac{3}{5} \cdot 4 = 0$$

⊙ Algunas cosas :

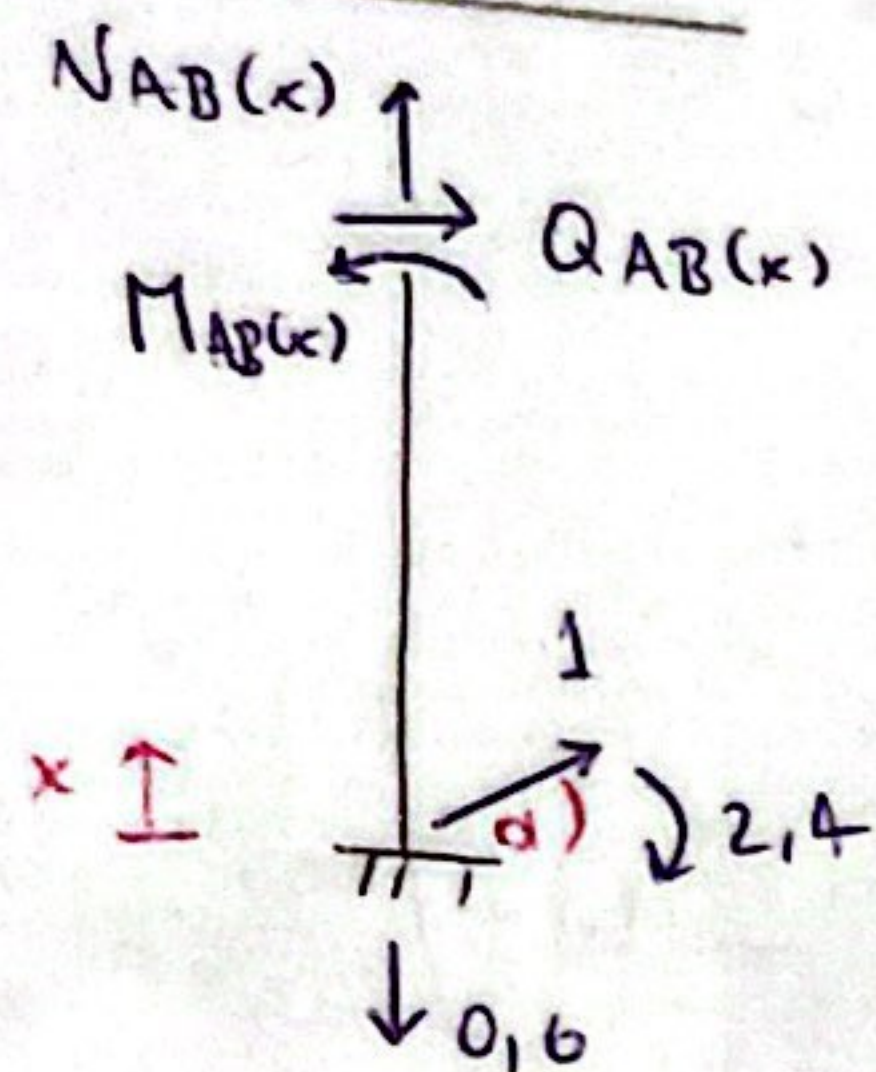
$$L_B = 5m$$

$$\sin \alpha = \frac{3}{5} ; \cos \alpha = \frac{4}{5}$$

$$\rightarrow M_A = -2,4$$

D.E.I :

- Tramo AB : $x \in [0,3]$

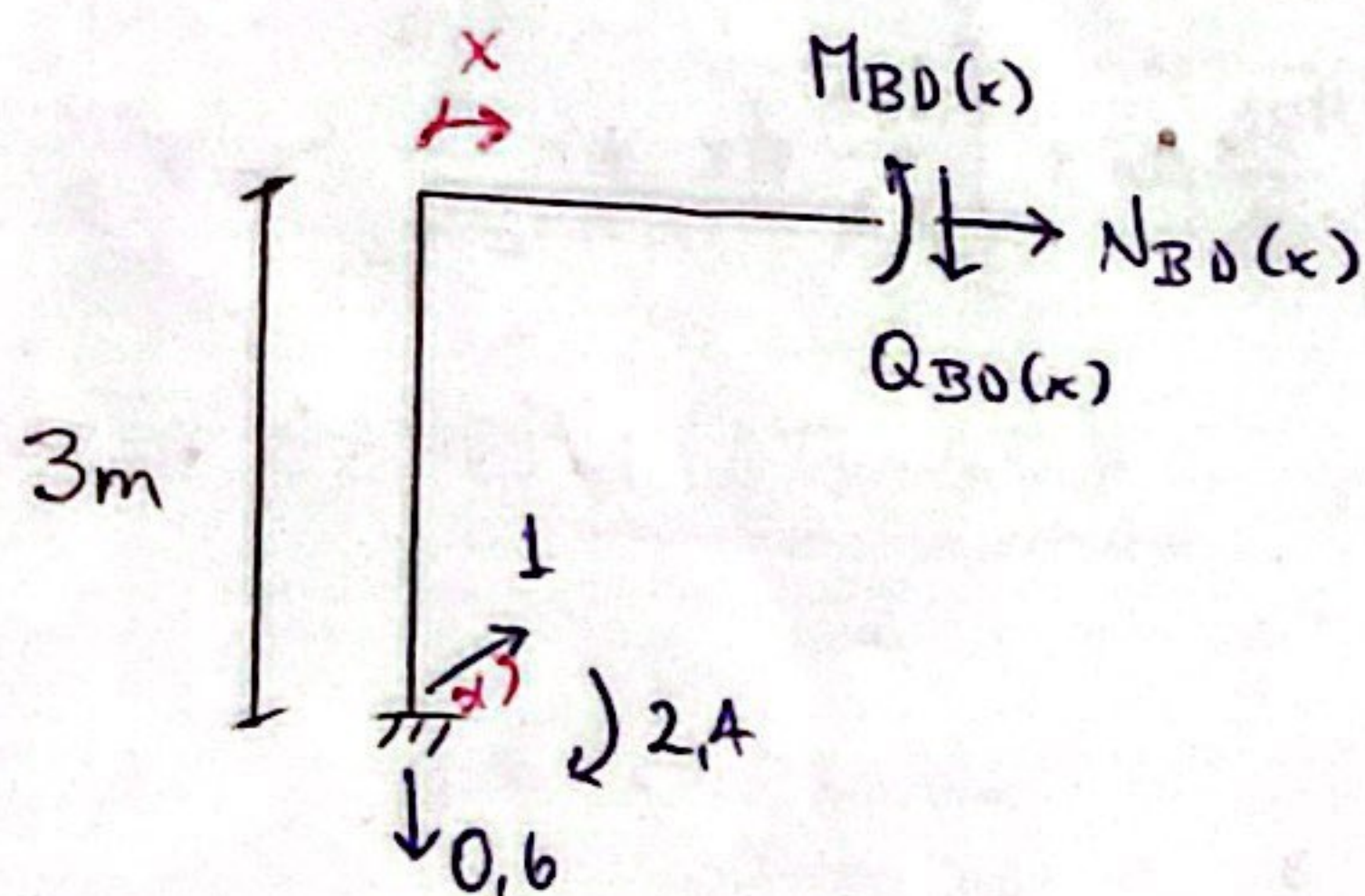


$$\underline{\sum F_y = 0} : N_{AB}(x) = 0$$

$$\underline{\sum F_x = 0} : Q_{AB}(x) = -0.8$$

$$\underline{\sum M_x = 0} : M_{AB}(x) = 2.4 - 0.8x$$

- Tramo BD : $x \in [0,4]$

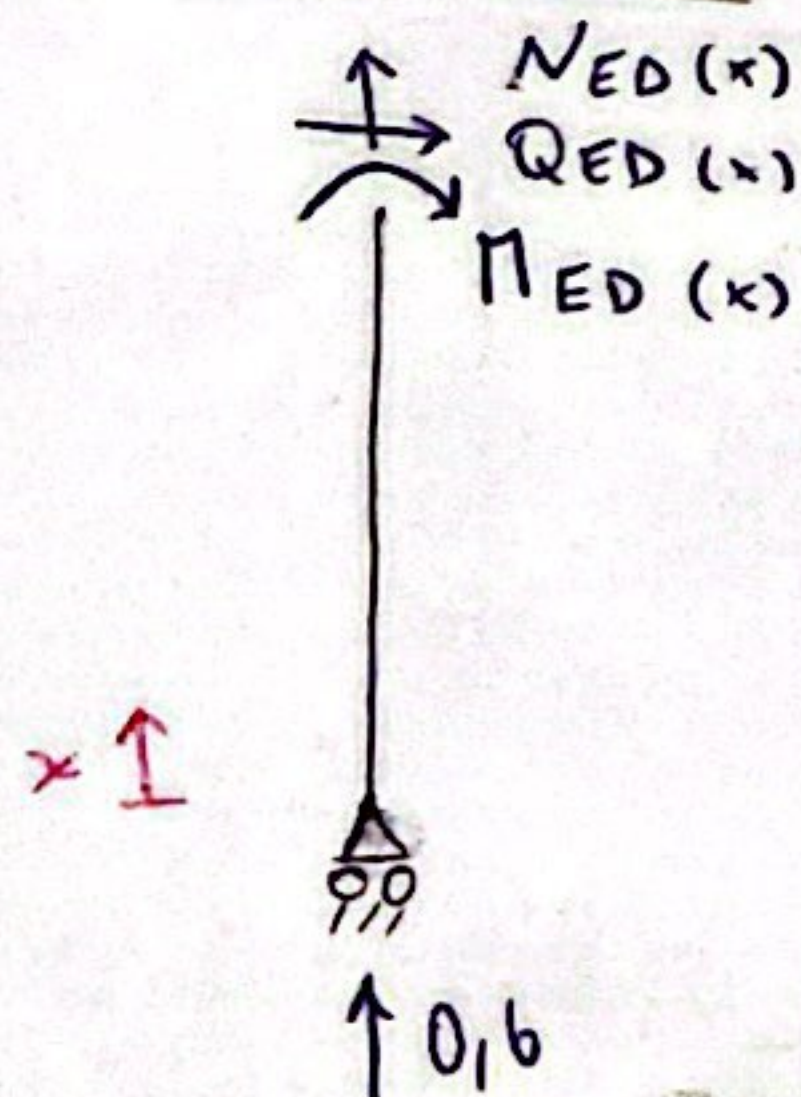


$$\underline{\sum F_x = 0} : N_{BD}(x) = -0.8$$

$$\underline{\sum F_y = 0} : Q_{BD}(x) = 0$$

$$\underline{\sum M_x = 0} : M_{BD}(x) = 0$$

- Tramo ED : $x \in [0,3]$



$$\underline{\sum F_y = 0} : N_{ED}(x) = -0.6$$

$$\underline{\sum F_x = 0} : Q_{ED}(x) = 0$$

$$\underline{\sum M_x = 0} : M_{ED}(x) = 0$$

4^{to}: Determinación de coeficientes matriz de flexibilidad $[F]$.

$$f_{ij} = \int_0^x \frac{M_i M_j}{EI} dx + \int_0^x \frac{N_i N_j}{EA} dx + \int_0^x \frac{Q_i Q_j}{GA_c} dx + \left(\sum_{i=1}^k \frac{F_i F_j}{k} \right) \quad (\text{RESORTE})$$

!!; No olvidar Bielas.

Calculamos:

$$f_{11} = \int_0^3 \frac{M_{AB}^2}{EI} dx + \int_0^4 \frac{M_{BD}^2}{EI} dx + \int_0^3 \frac{M_{DE}^2}{EI} dx + \int_0^3 \frac{N_{AB}^2}{EA} dx + \int_0^4 \frac{N_{BD}^2}{EA} dx + \int_0^3 \frac{N_{ED}^2}{EA} dx + \left(\frac{1^2}{k} \right)$$

RESORTE!!

$$\rightarrow f_{11} = 0,1058 \text{ m/tonf}$$

$$f_{22} = \int_0^3 \frac{M_{AB}^2}{EI} dx + \int_0^4 \frac{M_{BD}^2}{EI} dx + \int_0^3 \frac{M_{ED}^2}{EI} dx + \int_0^3 \frac{N_{AB}^2}{EA} dx + \int_0^4 \frac{N_{BD}^2}{EA} dx + \int_0^3 \frac{N_{ED}^2}{EA} dx + \left(\frac{1^2}{EA_b} \cdot L_b \right)$$

FUERZA BIELA!!

$$\rightarrow f_{22} = 0,0124 \text{ m/tonf}$$

$$f_{12} = f_{21} = \int_0^3 \frac{M_{AB}^{(1)} M_{AB}^{(2)}}{EI} dx + \int_0^4 \frac{N_{BD}^{(1)} N_{BD}^{(2)}}{EA} dx + \int_0^3 \frac{N_{ED}^{(1)} N_{ED}^{(2)}}{EA} dx$$

$$\rightarrow f_{12} = f_{21} = -0,0186 \text{ m/tonf}$$

5^{to}: Determinación del vector de carga $\{\Delta\}_a$

$$\Delta Q_i = \int_0^x \frac{M_a M_i}{EI} dx + \int_0^x \frac{N_a N_i}{EA} dx + \int_0^x \frac{Q_a Q_i}{GA_c} dx + \sum_{i=1}^k \frac{F_a F_i}{k}$$

¡; APLICAN BIELAS Y RESORTES!!

Calculamos: (Los terminos no considerados son xq' algún diag. = 0)

$$\Delta Q_1 = \int_0^3 \frac{M_{AB}^{EIF(1)} M_{AB}^{(1)}}{EI} dx + \int_0^4 \frac{M_{BD}^{EIF(1)} M_{BD}^{(1)}}{EI} dx + \int_0^3 \frac{N_{AB}^{EIF(1)} N_{AB}^{(1)}}{EA} dx + \int_0^3 \frac{N_{ED}^{EIF(1)} N_{ED}^{(1)}}{EA} dx$$

$$\rightarrow \boxed{\Delta Q_1 = 0,2516 \text{ m}}$$

$$\Delta Q_2 = \int_0^3 \frac{M_{AB}^{EIF(2)} M_{AB}^{(2)}}{EI} dx + \int_0^3 \frac{N_{ED}^{EIF(2)} N_{ED}^{(2)}}{EA} dx$$

$$\rightarrow \boxed{\Delta Q_2 = -0,0569 \text{ m}}$$

6^{to}: Determinación del vector de temperatura $\{\Delta\}_T$

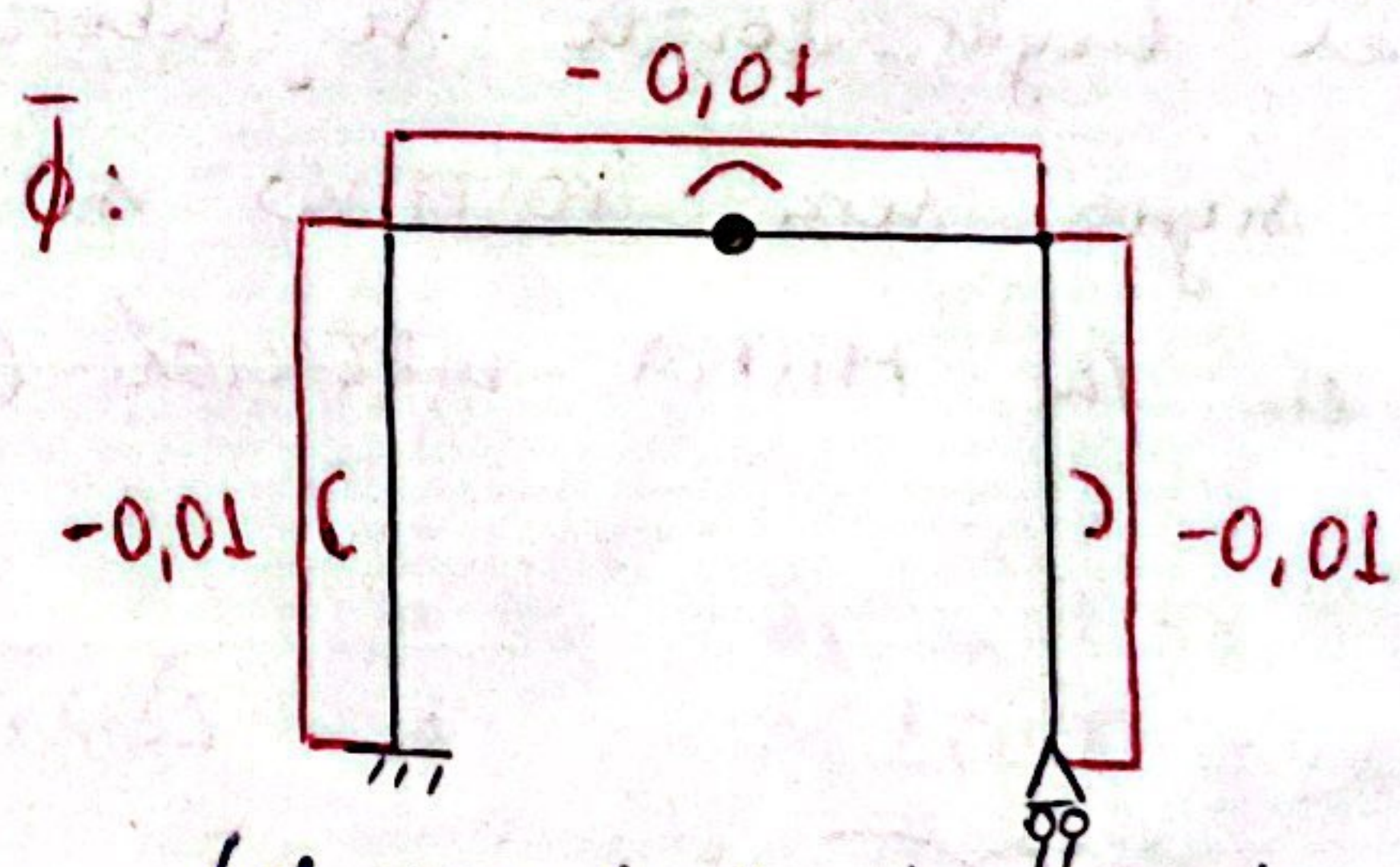
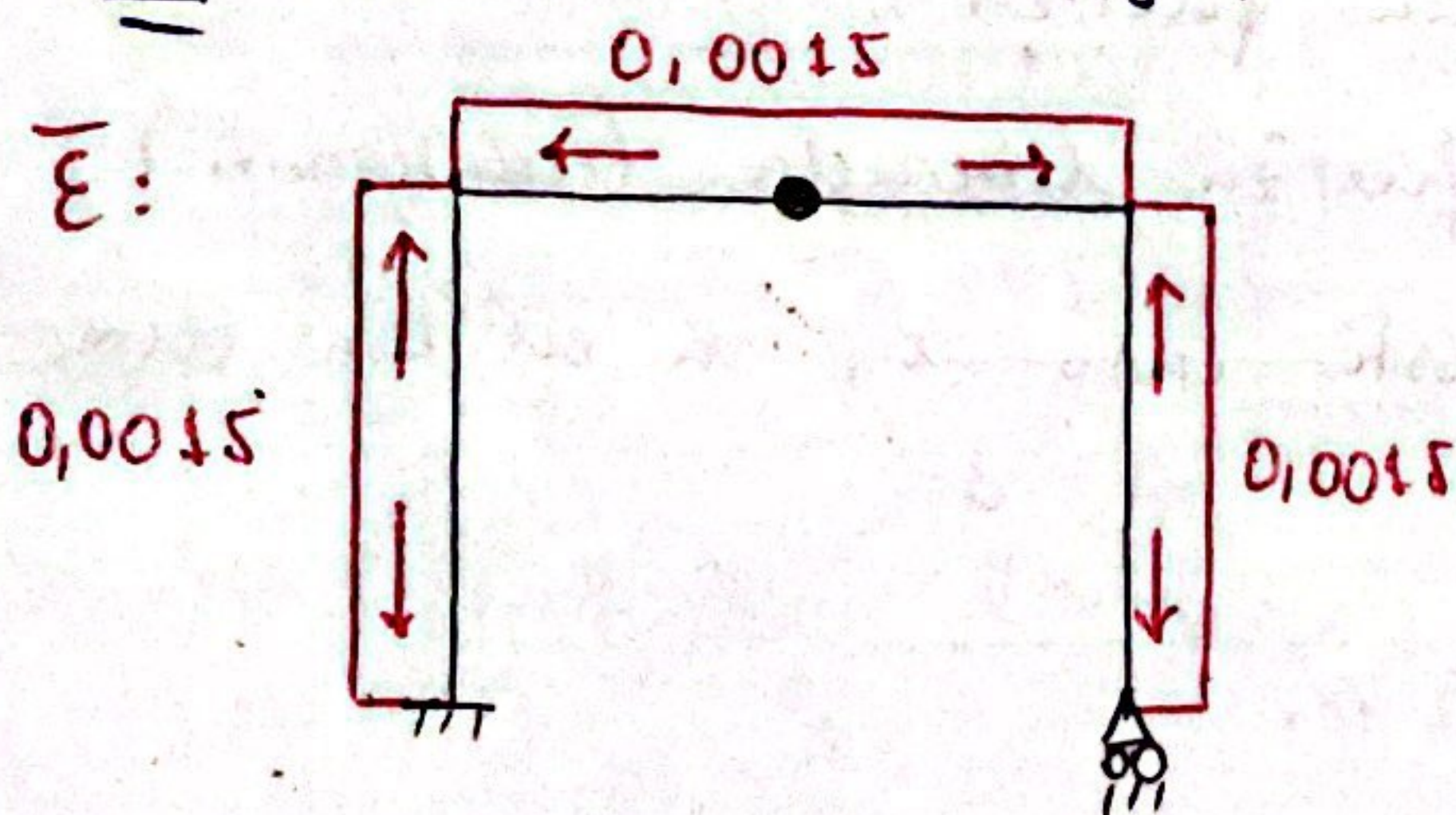
$$\bar{\epsilon} = \frac{\alpha (\Delta T_1 + \Delta T_2)}{2}$$

(Elongación)

$$\bar{\phi} = \frac{\alpha (\Delta T_2 - \Delta T_1)}{h}$$

(curvatura)

6.1: Cálculo de $\bar{\epsilon}$ y $\bar{\phi}$:



(el signo lo da la curvatura !!)

6.2: Cálculo $\{\Delta\}_T$:

$$\Delta T_i = \sum_{\text{barra}} A M_{i(x)} \cdot \bar{\phi} + \sum_{\text{barra}} A N_{i(x)} \cdot \bar{\epsilon}$$

$$\Delta T_1 = -0,01 \left[\int_0^3 M_{AB}^{(1)} dx + \int_0^4 M_{BD}^{(1)} dx + \int_0^3 M_{ED}^{(1)} dx \right] \\ + 0,0015 \left[\int_0^3 N_{AB}^{(1)} dx + \int_0^4 N_{BD}^{(1)} dx + \int_0^3 N_{ED}^{(1)} dx \right]$$

$$\rightarrow \boxed{\Delta T_1 = 0,096 \text{ m}}$$

$$\Delta T_2 = -0,01 \left[\int_0^3 M_{AB}^{(2)} dx + \int_0^4 M_{BD}^{(2)} dx + \int_0^3 M_{ED}^{(2)} dx \right] \\ + 0,0015 \left[\int_0^3 N_{AB}^{(2)} dx + \int_0^4 N_{BD}^{(2)} dx + \int_0^3 N_{ED}^{(2)} dx \right]$$

$$\rightarrow \boxed{\Delta T_2 = -0,0435 \text{ m}}$$

7^{mo}: Determinación del vector de asentamientos $\{\Delta\}_A$

Este vector es nulo, a menos que ^{haya} un asentamiento en el lugar donde se liberó una fuerza.

El signo será **POSITIVO** si la fuerza liberada (redundante), va en la **MISMA DIRECCIÓN** (en este caso x_1 va en esa direc.).

$$\Delta_{A1} = 0,01 \text{ m} \quad \wedge \quad \Delta_{A2} = 0 \text{ m}$$

¡¡ ojo las unidades !!

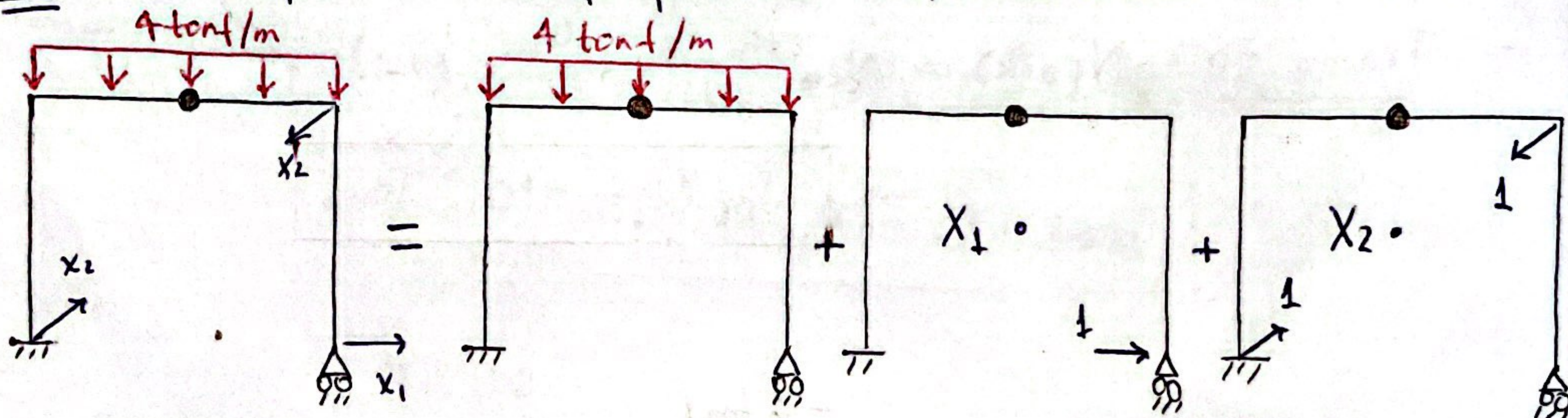
8º: Resolver el problema de flexibilidad ".

$$\{\Delta\}_A = \{\Delta\}_Q + \{\Delta\}_T + [F] \{R\}$$

$$\rightarrow \begin{Bmatrix} 0,01 \\ 0 \end{Bmatrix} = \begin{Bmatrix} 0,2156 \\ -0,0569 \end{Bmatrix} + \begin{Bmatrix} 0,096 \\ -0,0435 \end{Bmatrix} + \begin{bmatrix} 0,1058 & -0,0186 \\ -0,0186 & 0,0124 \end{bmatrix} \begin{Bmatrix} X_1 \\ X_2 \end{Bmatrix}$$

$$\therefore \begin{Bmatrix} X_1 \\ X_2 \end{Bmatrix} = \begin{Bmatrix} -2,4 \\ 4,5 \end{Bmatrix} [\text{tonf}]$$

9º: Principio de superposición $\rightarrow$ Reacciones + D.E.I



$$\text{Estructura Real} = \text{EIF} + X_1 \cdot \text{Virtual 1} + X_2 \cdot \text{Virtual 2}$$

9.1: Reacciones + FBIELA

1) $F_b = 4,5 \text{ tonf}$ (Tracción)

2) $H_E = -2,4 \text{ tonf}$

3) $V_A = V_A^{\text{EIF}} + X_1 \cdot V_A^{(1)} + X_2 \cdot V_A^{(2)}$

$\rightarrow$ $V_A = 5,7 \text{ tonf}$

4) $H_A = H_A^{\text{EIF}} + X_1 \cdot H_A^{(1)} + X_2 \cdot H_A^{(2)}$

$\rightarrow$ $H_A = 2,4 \text{ tonf}$

5) $M_A = M_A^{\text{EIF}} + X_1 \cdot M_A^{(1)} + X_2 \cdot M_A^{(2)}$

$\rightarrow$ $M_A = -9,2 \text{ tonf-m}$

6) $V_E = V_E^{\text{EIF}} + X_1 \cdot V_E^{(1)} + X_2 \cdot V_E^{(2)}$

$\rightarrow$ $V_E = 4,9 \text{ tonf}$

9.2: Diagramas

N(x)

- Tramo AB: $N_{AB}(x) = N_{AB}^{EIF} + \chi_1 \cdot N_{AB}^{(1)} + \chi_2 \cdot N_{AB}^{(2)}$

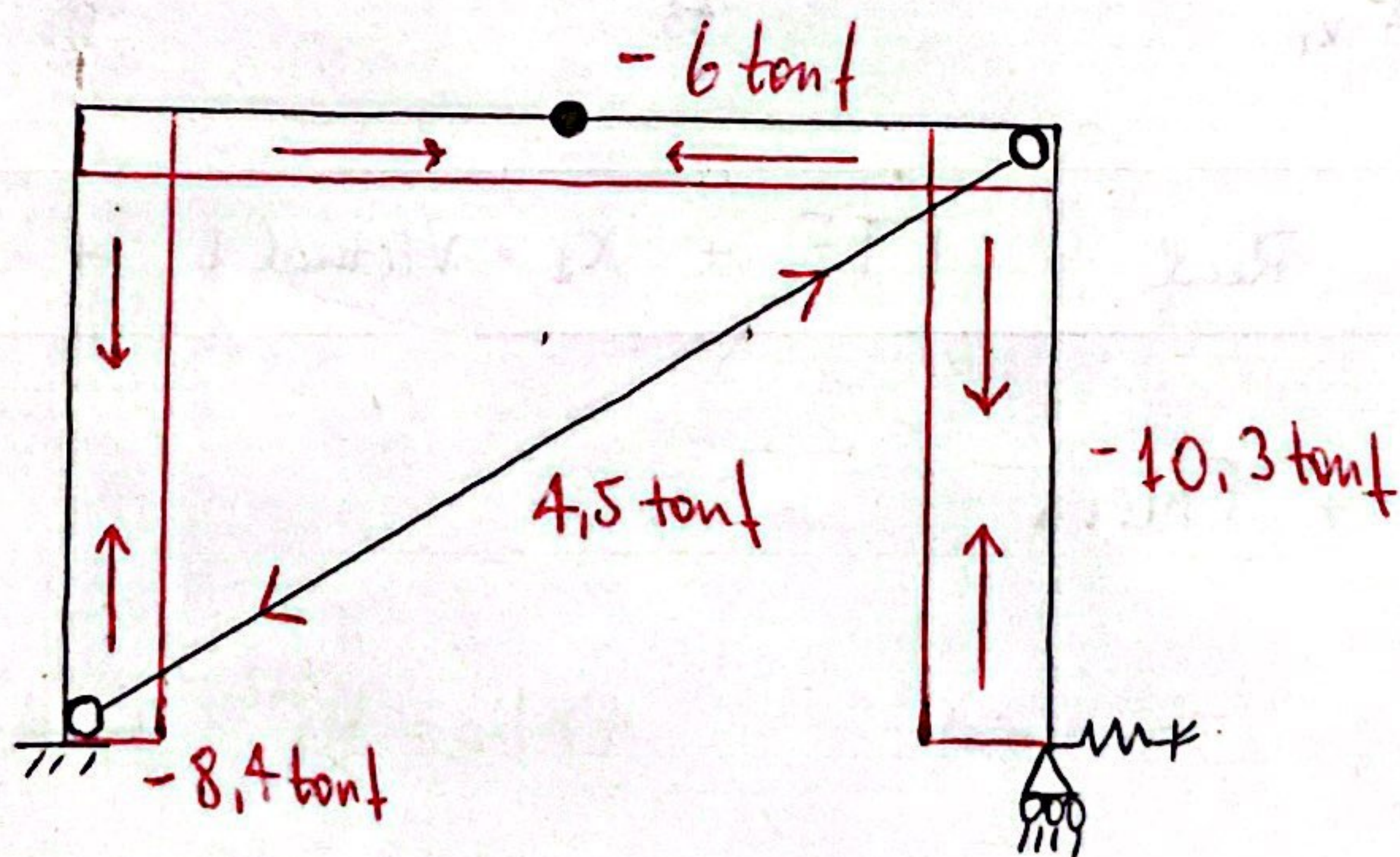
→ $N_{AB}(x) = -8,4 \text{ tonf}$

- Tramo BD: $N_{BD}(x) = N_{BD}^{EIF} + \chi_1 \cdot N_{BD}^{(1)} + \chi_2 \cdot N_{BD}^{(2)}$

→ $N_{BD}(x) = -6 \text{ tonf}$

- Tramo ED: $N_{ED}(x) = N_{ED}^{EIF} + \chi_1 \cdot N_{ED}^{(1)} + \chi_2 \cdot N_{ED}^{(2)}$

→ $N_{ED}(x) = -10,3 \text{ tonf}$



Q(x)

- Tramo AB: $Q_{AB}(x) = Q_{AB}^{EIF} + \chi_1 \cdot Q_{AB}^{(1)} + \chi_2 \cdot Q_{AB}^{(2)}$

→ $Q_{AB}(x) = -6 \text{ tonf}$

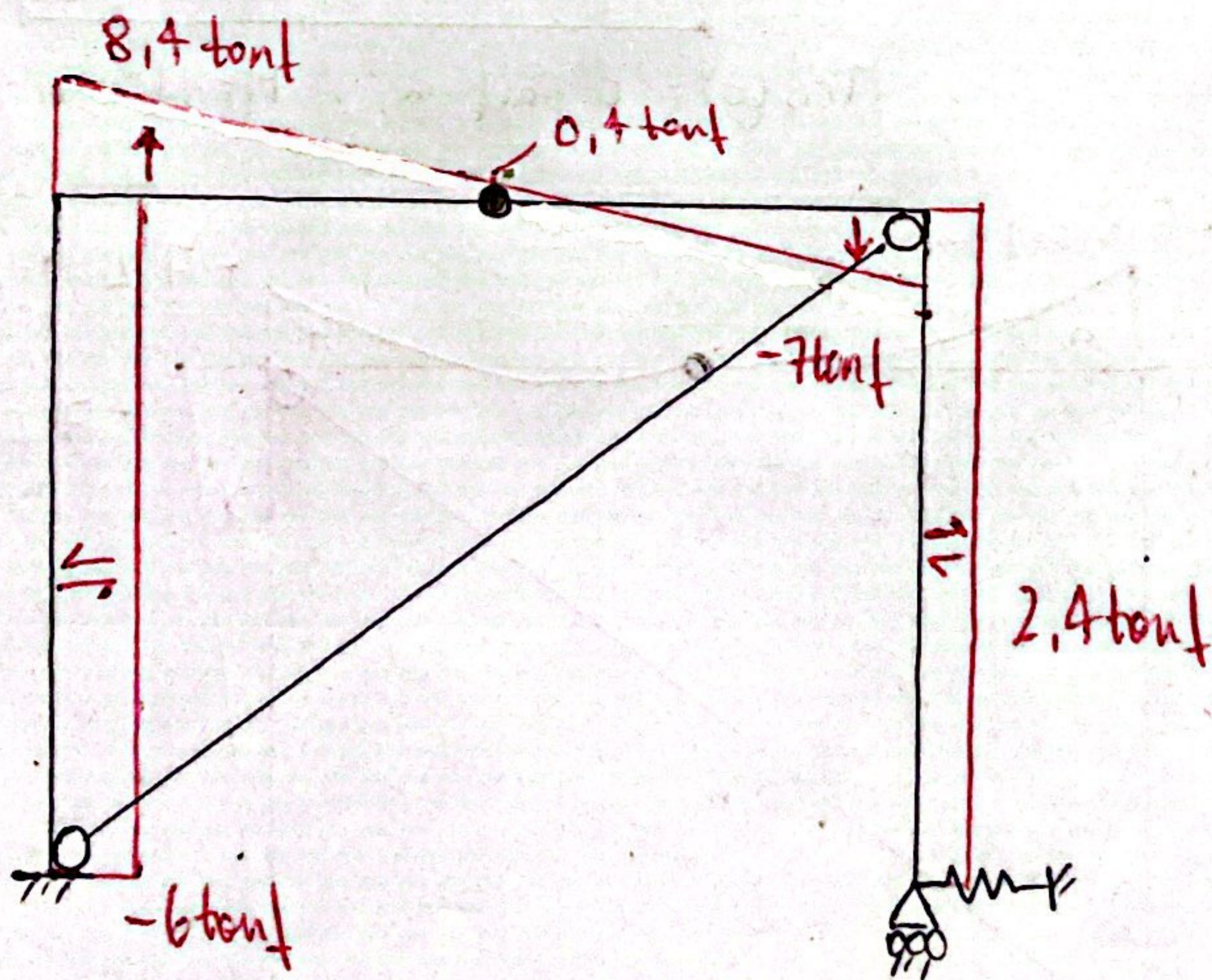
- Tramo BD: $Q_{BD}(x) = Q_{BD}^{EIF} + \chi_1 \cdot Q_{BD}^{(1)} + \chi_2 \cdot Q_{BD}^{(2)}$

→ $Q_{BD}(x) = 8,4 - 4x$

$Q_{BD}(0) = 8,4 \text{ tonf}$; $Q_{BD}(2) = 0,4 \text{ tonf}$; $Q_{BD}(4) = -7,6 \text{ tonf}$

- Tramo ED: $Q_{ED}(x) = Q_{ED}^{EIF} + \chi_1 \cdot Q_{ED}^{(1)} + \chi_2 \cdot Q_{ED}^{(2)}$

→ $Q_{ED}(x) = 2,4 \text{ tonf}$



M(x)

- Tramo AB: $M_{AB}(x) = M_{AB}^{EIF} + X_1 \cdot M_{AB}^{(1)} + X_2 \cdot M_{AB}^{(2)}$

→ $M_{AB}(x) = 9,2 - 6x$

$M_{AB}(0) = 9,2 \text{ tonf-m} ; M_{AB}(3) = -8,8 \text{ tonf-m}$

- Tramo BD: $M_{BD}(x) = M_{BD}^{EIF} + X_1 \cdot M_{BD}^{(1)} + X_2 \cdot M_{BD}^{(2)}$

→ $M_{BD}(x) = -2x^2 + 8,4x - 8,8$

$M_{BD}(0) = -8,8 \text{ tonf-m} ; M_{BD}(2) = 0 \text{ tonf-m} ; M_{BD}(4) = -7,2 \text{ tonf-m}$

- Tramo ED: $M_{ED}(x) = M_{ED}^{EIF} + X_1 \cdot M_{ED}^{(1)} + X_2 \cdot M_{ED}^{(2)}$

→ $M_{ED}(x) = -2,4x$

$M_{ED}(0) = 0 \text{ tonf-m} ; M_{ED}(3) = -7,2 \text{ tonf-m}$

