

MA2002-3 Cálculo Avanzado y Aplicaciones**Profesor:** Alexis Fuentes**Auxiliares:** Vicente Salinas**Dudas:** vicentesalinas@ing.uchile.cl**Auxiliar 2: Campos Conservativos e Integrales de Trabajo**

31 de agosto de 2021

P1. [Campos Conservativos]

a) Verifique si los siguientes campos son conservativos.

$$1) \vec{F}(x, y, z) = (y^2 \cos(x) + z^3)\hat{i} + (2y \sin(x) - 4)\hat{j} + (3xz^2 + 2z)\hat{k}$$

$$2) \vec{G}(\rho, \theta, z) = \frac{\rho z}{(\rho^2 + z^2)^{3/2}}\hat{\rho} - \frac{\rho^2}{(\rho^2 + z^2)^{3/2}}\hat{k}$$

P2. Considere que esta en el campo $F(x, y) = (\sin(x)y, \sin(y) - \cos(x))$ ¿Cuanto es el trabajo realizado por desplazarse por $\Gamma_1 \cup \Gamma_2$ con $\Gamma_1 = (\pi(1 - \cos(t)), \pi(\sin(t)))$, para $t \in [0, \pi]$ y $\Gamma_2 = (\pi(2 - \sin(t)), \pi(\cos(t) - 1))$ para $t \in [\pi, 2\pi]$

P3. a) Calcule el gradiente en coordenadas cartesianas de

$$f(x, y, z) = \frac{z}{x^2 + y^2 + z^2}$$

¿Calcúlelo en coordenadas esféricas? ¿Como se relacionan estos cálculos?

b) Se definen las coordenadas parabólicas (ϵ, η, ϕ) , tal que $x = \epsilon\eta \cos(\phi)$, $y = \epsilon\eta \sin(\phi)$ y $z = \frac{1}{2}(\eta^2 - \epsilon^2)$. Calcule el gradiente y el laplaciano en estas coordenadas. ($\eta, \epsilon > 0$ y $\phi \in [0, 2\pi]$)

P4. Sea ψ un campo escalar y F, G campos vectoriales suficientemente diferenciables. Demuestre las siguientes identidades:

$$a) \operatorname{div}(\psi \nabla \psi) = \|\nabla \psi\|^2 + \psi \Delta \psi$$

$$b) \Delta G = \nabla(\operatorname{div}(G)) - \operatorname{rot}(\operatorname{rot}(G))$$

Propuestos

P1. Coordenadas bipolares (σ, τ) , con $\sigma \in (0, 2\pi)$ y $\tau \in (-\infty, \infty)$. La a es una constante, estas coordenadas cumplen que:

$$x = a \frac{\sinh(\tau)}{\cosh(\tau) - \cos(\sigma)} \text{ e } y = a \frac{\sin(\sigma)}{\cosh(\tau) - \cos(\sigma)}$$

a) Pruebe que el gradiente en estas coordenadas es: $\nabla f = \frac{(\cosh(\tau) - \cos(\sigma))}{a} \left(\frac{\partial f}{\partial \sigma} \hat{\sigma} + \frac{\partial f}{\partial \tau} \hat{\tau} \right)$

b) Pruebe que la formula para el laplaciano es: $\Delta f = \frac{(\cosh(\tau) - \cos(\sigma))^2}{a^2} \left(\frac{\partial^2 f}{\partial \sigma^2} + \frac{\partial^2 f}{\partial \tau^2} \right)$

Indicación: Pruebe que $h_\sigma = h_\tau = \frac{a}{\cosh(\tau) - \cos(\sigma)}$

P2. Pruebe las siguientes identidades:

a) $\Delta(fg) = f\Delta g + g\Delta f + 2\nabla f \cdot \nabla g$

b) $\text{rot}(F) = F \text{div}(G) - G \text{div}(F) + (G \cdot \nabla)F - (F \cdot \nabla)G$

Resumen

Integral de trabajo de un campo $\vec{F}$ sobre una curva:

Sea Γ una curva simple y regular en $\mathbb{R}^3$, y sea $\vec{F} : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ una función continua. Se define la integral de F sobre la curva Γ , donde $\vec{r} : [a, b] \rightarrow \mathbb{R}^3$ es una parametrización regular de Γ . mediante:

$$W = \int_{\Gamma} \vec{F} \cdot d\vec{r} := \int_a^b \vec{F}(\vec{r}(t)) \cdot \frac{d\vec{r}(t)}{dt} dt$$

Coordenadas Cilíndricas: $T(\rho, \theta, k) = (\rho \cos(\theta), \rho \sin(\theta), k)$ y los factores $h_\rho = 1$, $h_\theta = \rho$ y $h_k = 1$

Coordenadas Esféricas: $T(r, \phi, \theta) = (r \cos(\theta) \sin(\phi), r \sin(\theta) \sin(\phi), r \cos(\phi))$ y los factores $h_r = 1$, $h_\theta = r \sin(\phi)$ y $h_\phi = r$.

$$\nabla f = \frac{1}{h_u} \frac{\partial f}{\partial u} \hat{u} + \frac{1}{h_v} \frac{\partial f}{\partial v} \hat{v} + \frac{1}{h_w} \frac{\partial f}{\partial w} \hat{w}$$

$$\Delta \phi = \frac{1}{h_1 h_2 h_3} \sum_{j=1}^3 \frac{\partial}{\partial w_j} \left[\frac{h_1 h_2 h_3}{h_j^2} \left(\frac{\partial \phi}{\partial w_j} \right) \right]$$

P1. [Campos Conservativos]

a) Verifique si los siguientes campos son conservativos.

$$1) \vec{F}(x, y, z) = (y^2 \cos(x) + z^3)\hat{i} + (2y \sin(x) - 4)\hat{j} + (3xz^2 + 2z)\hat{k}$$

$$2) \vec{G}(\rho, \theta, z) = \frac{\rho z}{(\rho^2 + z^2)^{3/2}}\hat{\rho} - \frac{\rho^2}{(\rho^2 + z^2)^{3/2}}\hat{k}$$

$$\boxed{\text{Si } \nabla g = F}$$

$$\frac{\partial g}{\partial x} = y^2 \cos(x) + z^3 \quad (1)$$

$$\frac{\partial g}{\partial y} = 2y \sin(x) - 4 \quad (2)$$

$$\frac{\partial g}{\partial z} = 3xz^2 + 2z \quad (3)$$

$$\begin{aligned} (1) \Rightarrow \tilde{g}(x, y, z) &= \int y^2 \cos(x) + z^3 dx \\ &+ C(y, z) \quad (\text{No olvidar}) \\ &= y^2 \sin(x) + z^3 x + C(y, z) \end{aligned}$$

$$\frac{\partial \tilde{g}}{\partial y} = 2y \sin(x) + \frac{\partial C(y, z)}{\partial y}$$

$$\text{imposer (2)} \Rightarrow 2y \sin(x) - 4 = \frac{\partial \tilde{g}}{\partial y}$$

$$\Rightarrow \frac{\partial C(y, z)}{\partial y} = -4 \quad / \int dy$$

$$C(y, z) = -4y + C(z)$$

Recomposons

$$\tilde{g}(x, y, z) = y^2 \sin(x) + z^3 x - 4y + C(z)$$

$$\frac{\partial \tilde{g}}{\partial z} = 3z^2 x + \frac{\partial C(z)}{\partial z} \stackrel{(3)}{=} 3xz^2 + 2z$$

$$\Rightarrow \frac{\partial C(z)}{\partial z} = 2z \Rightarrow C(z) = z^2 + C$$

$$g(x, y, z) = y^2 \sin(x) + z^3 x - 4y + z^2 + C$$

$$2) \vec{G}(\rho, \theta, z) = \frac{\rho z}{(\rho^2 + z^2)^{3/2}} \hat{\rho} - \frac{\rho^2}{(\rho^2 + z^2)^{3/2}} \hat{k} + \frac{\rho}{5} \theta \hat{\theta}$$

obs : ∇f en coordonnées cylindriques = $\frac{\partial f}{\partial \rho} \hat{\rho} + \frac{1}{\rho} \frac{\partial f}{\partial \theta} \hat{\theta} + \frac{\partial f}{\partial z} \hat{k}$

$$\cancel{\frac{1}{\rho}} \frac{\partial f}{\partial \theta} = \frac{\rho^2 \theta}{5}$$

$$2) \vec{G}(\rho, \theta, z) = \frac{\rho z}{(\rho^2 + z^2)^{3/2}} \hat{\rho} - \frac{\rho^2}{(\rho^2 + z^2)^{3/2}} \hat{k}$$

$$\frac{\partial f}{\partial \rho} = \frac{\rho z}{(\rho^2 + z^2)^{3/2}} \quad (1)$$

$$\frac{1}{\rho} \frac{\partial f}{\partial \theta} = 0 \Rightarrow \frac{\partial f}{\partial \theta} = 0 \quad (2)$$

$$\frac{\partial f}{\partial z} = - \frac{\rho^2}{(\rho^2 + z^2)^{3/2}} \quad (3)$$

$$(3) \Rightarrow \int \frac{\rho^2}{(\rho^2 + z^2)^{\frac{3}{2}}} dz$$

$$(1) \Rightarrow \int \frac{z}{(\rho^2 + z^2)^{\frac{3}{2}}} \rho d\rho + C(0, z) = \tilde{g}$$

$$C.V = u = \rho^2 + z^2$$

$$\frac{du}{2} = z \rho d\rho$$

$$\frac{z}{2} \int u^{-\frac{3}{2}} du + C(0, z) = \tilde{g}$$

$$\frac{z}{2} (-2) u^{-\frac{1}{2}} + C(0, z) = \tilde{g}$$

Rechenplan

$$\tilde{g} = \frac{-z}{\sqrt{\rho^2 + z^2}} + C(\theta, z)$$

$$(2) \quad \frac{\partial \tilde{g}}{\partial \theta} = 0 = \frac{\partial C(\theta, z)}{\partial \theta}$$

$$C(\theta, z) = C(z) \Rightarrow \tilde{g} = \frac{-z}{\sqrt{\rho^2 + z^2}} + C(z)$$

Usm (3)

$$\frac{\partial g}{\partial z} = \frac{-\rho^2}{(\rho^2 + z^2)^{\frac{3}{2}}}$$

$$\frac{\partial \tilde{g}}{\partial z} = - \left(\frac{1/\sqrt{\rho^2 + z^2} - \frac{z^2}{\sqrt{\rho^2 + z^2}}}{\rho^2 + z^2} \right) + \frac{\partial C(z)}{\partial z}$$

$$\frac{\partial \tilde{g}}{\partial z} = - \left(\frac{\rho^2 + z^2 - z^2}{(\rho^2 + z^2)^{\frac{3}{2}}} \right) + \frac{\partial C(z)}{\partial z}$$

$$= - \frac{\rho^2}{(\rho^2 + z^2)^{\frac{3}{2}}} + \frac{\partial C(z)}{\partial z}$$

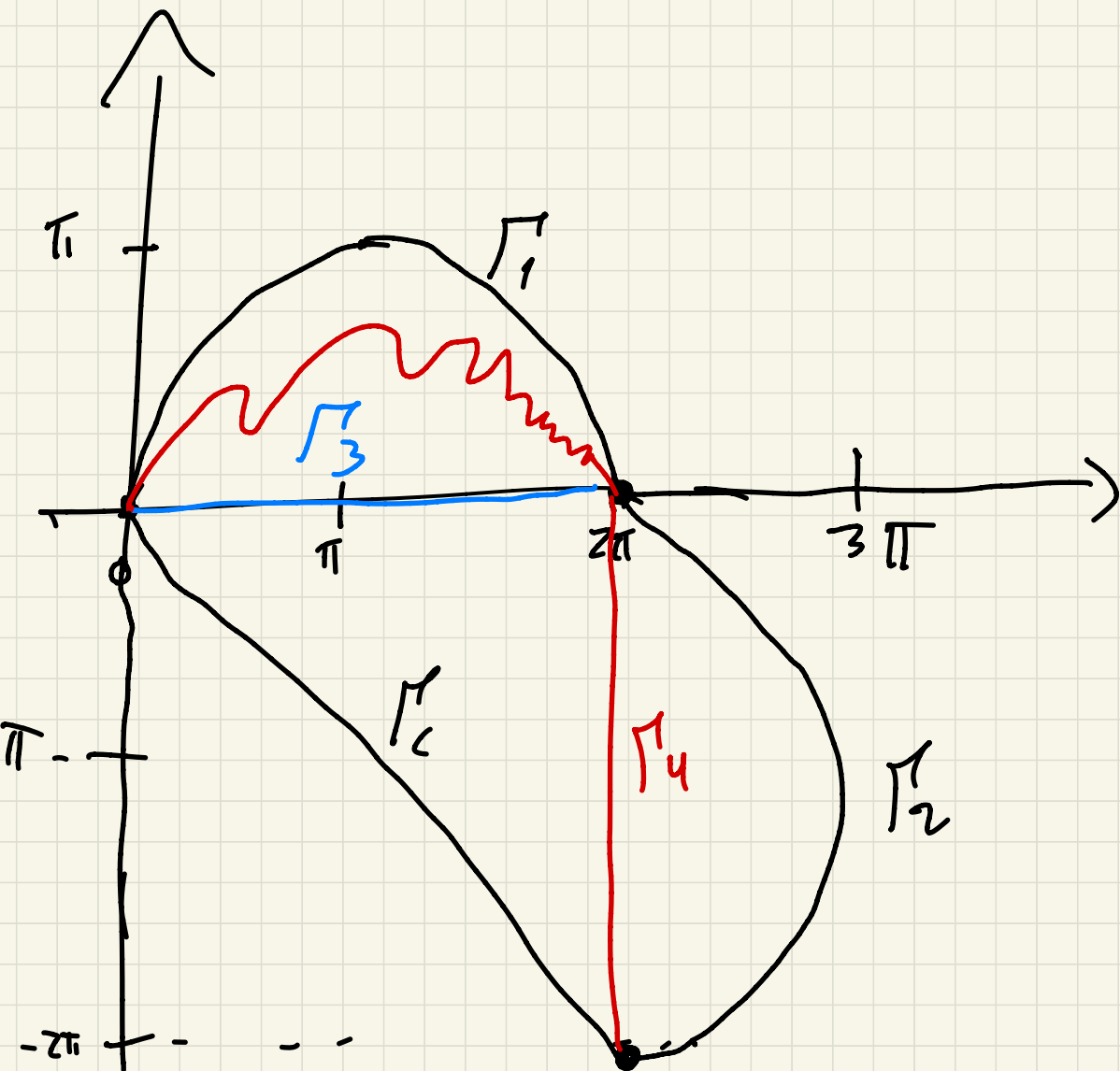
Como queremos que se anule (z)

$$\Rightarrow \frac{\partial C(z)}{\partial z} = 0 \Rightarrow C(z) = C$$

$$g = - \frac{z}{\sqrt{\rho^2 + z^2}}$$

Completo Tod.

P2. Considere que esta en el campo $F(x, y) = (\sin(x)y, \sin(y) - \cos(x))$ ¿Cuanto es el trabajo realizado por desplazarse por $\Gamma_1 \cup \Gamma_2$ con $\Gamma_1 = (\pi(1 - \cos(t)), \pi(\sin(t)))$, para $t \in [0, \pi]$ y $\Gamma_2 = (\pi(2 - \sin(t)), \pi(\cos(t) - 1))$ para $t \in [\pi, 2\pi]$



$$W = \int_{\Gamma_1} F(\Gamma(t)) \cdot \frac{d\Gamma}{dt} + \int_{\Gamma_2} F(\Gamma(t)) \cdot \frac{d\Gamma}{dt}.$$

$$= \int_0^{\pi} \left(\sin(\pi(1-\cos(t))) (\pi \sin(t)) \right) \cdot \frac{d\gamma}{dt} dt$$

$$= \int_0^{\pi} \sin(\pi \sin(t)) \cdot \cos(\pi(1-\cos(t))) \cdot \pi \sin(t) dt$$

Si F es conservativo

Puede leerse $\gamma^{\text{cc}} W = \int_{\gamma_1} F = \int_{\gamma_3} F$

$$\tilde{\gamma}(t) = (2t, 0) \quad t \in [0, \pi]$$

$$\gamma_3 \Rightarrow \frac{d\gamma}{dt} = (2, 0)$$

$$W_1 = \int_{\Gamma_1} = \int_{\Gamma_3} = \int_0^\pi (\sin(2t) \cdot 0, \sin(0) - \cos(2t)) \cdot (2, 0)$$

$$= \int_0^\pi 0 \, dt = 0$$

$$F(x, y) = (\sin(x)y, \sin(y) - \cos(x))$$

$$g(x, y) = -\cos(x)y - \cos(y) \quad (\text{Veripath})$$

$\Rightarrow F$ conservative

$$\vec{r}_c = (t, -t)$$

$$t \in [0, 2\pi]$$

$$\frac{d\vec{r}_c}{dt} = (1, -1)$$

$$\begin{aligned}
 W &= \int_0^{2\pi} \left(\sin(t)t, -\sin(t) - \cos(t) \right) \cdot (1, 1) \\
 &= \int_0^{2\pi} \underbrace{-\sin(t) \cdot t + \sin(t)}_{\cancel{\sin(t)}} + \underbrace{\cos(t)}_{\cancel{\cos(t)}} dt
 \end{aligned}$$

$$= \boxed{-2\pi}$$

Por partes usar
 $du = -\sin(t) dt$
 $u = t$

$$\boxed{W = -2\pi}$$

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b) Se definen las coordenadas parabólicas (ϵ, η, ϕ) , tal que $x = \epsilon\eta \cos(\phi)$, $y = \epsilon\eta \sin(\phi)$ y $z = \frac{1}{2}(\eta^2 - \epsilon^2)$.

Calcule el gradiente y el laplaciano en estas coordenadas. ($\eta, \epsilon > 0$ y $\phi \in [0, 2\pi]$)

$$a) \nabla f = \left(\frac{-2xz}{(x^2 + y^2 + z^2)^2}, \frac{-2yz}{(x^2 + y^2 + z^2)^2}, \frac{x^2 + y^2 - z^2}{(x^2 + y^2 + z^2)^2} \right)$$

$$x = r \cos \theta \sin \phi$$

$$y = r \sin \theta \sin \phi$$

$$z = r \cos(\phi)$$

$$f(r, \theta, \phi) = \frac{r \cos \phi}{r^2} = \frac{\cos \phi}{r}$$

$$\nabla g(r, \theta, \phi) = \frac{\partial g}{\partial r} \hat{r} + \frac{1}{r \sin \phi} \frac{\partial g}{\partial \theta} \hat{\theta} + \frac{1}{r} \frac{\partial g}{\partial \phi} \hat{\phi}$$

$$\nabla f(r, \theta, \phi) = -\frac{r^2 \cos \phi}{r^4} \hat{r} - \frac{r^2 \sin \phi}{r^4} \hat{\phi}$$

$$\vec{r} = (\cos \theta \hat{r} + \sin \theta \hat{\phi}) \quad \left(\begin{array}{l} \text{Mol} \\ \text{isto} \\ \text{no ms} \end{array} \right)$$

b) $r(\xi, \eta, \phi) \rightarrow (x, y, z)$

$$J_r = \begin{bmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial x}{\partial \eta} & \frac{\partial x}{\partial \phi} \\ \frac{\partial y}{\partial \xi} & \frac{\partial y}{\partial \eta} & \frac{\partial y}{\partial \phi} \\ \frac{\partial z}{\partial \xi} & \frac{\partial z}{\partial \eta} & \frac{\partial z}{\partial \phi} \end{bmatrix}$$

where $x = \epsilon \eta \cos(\phi)$, $y = \epsilon \eta \sin(\phi)$ and $z = \frac{1}{2}(\eta^2 - \epsilon^2)$.
for $\epsilon > 0$ and $\phi \in [0, 2\pi)$

$$= \begin{bmatrix} \eta \cos(\phi) & \xi \cos(\phi) & -\xi \eta \sin \phi \\ \eta \sin(\phi) & \xi \sin(\phi) & \xi \eta \cos \phi \\ -\xi & \eta & 0 \end{bmatrix}$$

$$\begin{bmatrix} \vec{\xi} & \vdots & \vec{\eta} & \vdots & \vec{\phi} \end{bmatrix}$$

$$h_{\xi} = \|\vec{\xi}\| = \sqrt{\eta^2 + \xi^2}$$

$$h_{\eta} = \|\vec{\eta}\| = \sqrt{\eta^2 + \xi^2}$$

$$h_{\phi} = \|\vec{\phi}\| = \xi \eta$$

$$\nabla f = \frac{1}{h_u} \frac{\partial f}{\partial u} \hat{u} + \frac{1}{h_v} \frac{\partial f}{\partial v} \hat{v} + \frac{1}{h_w} \frac{\partial f}{\partial w} \hat{w}$$

$$\Delta \phi = \frac{1}{h_1 h_2 h_3} \sum_{j=1}^3 \frac{\partial}{\partial w_j} \left[\frac{h_1 h_2 h_3}{h_j^2} \left(\frac{\partial \phi}{\partial w_j} \right) \right]$$

$$\nabla f = \frac{1}{\sqrt{\eta^2 + \xi^2}} \left(\frac{\partial f}{\partial \xi} \hat{\xi} + \frac{\partial f}{\partial \eta} \hat{\eta} \right) + \frac{1}{\xi \eta} \frac{\partial f}{\partial \phi} \hat{\phi}$$

$$\Delta f = \frac{1}{(\eta^2 + \xi^2) \xi \eta} \left[\frac{\partial}{\partial \xi} \left(\xi \eta \frac{\partial f}{\partial \xi} \right) + \frac{\partial}{\partial \eta} \left(\xi \eta \frac{\partial f}{\partial \eta} \right) + \frac{\partial}{\partial \phi} \left(\frac{\xi \eta^2}{\xi \eta} \frac{\partial f}{\partial \phi} \right) \right]$$

P4. Sea ψ un campo escalar y F, G campos vectoriales suficientemente diferenciables. Demuestre las siguientes identidades:

a) $\operatorname{div}(\psi \nabla \psi) = \|\nabla \psi\|^2 + \psi \Delta \psi$

b) $\Delta G = \nabla(\operatorname{div}(G)) - \operatorname{rot}(\operatorname{rot}(G))$

$$\Delta \psi = \left(\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} \right) \hat{i} + \left(\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} \right) \hat{j} + \left(\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} \right) \hat{k}$$

a) $\psi \nabla \psi = \psi \frac{\partial \psi}{\partial x} \hat{i} + \psi \frac{\partial \psi}{\partial y} \hat{j} + \psi \frac{\partial \psi}{\partial z} \hat{k}$

$$\operatorname{div}(\psi \nabla \psi) = \frac{\partial}{\partial x} \left(\psi \frac{\partial \psi}{\partial x} \right) + \frac{\partial}{\partial y} \left(\psi \frac{\partial \psi}{\partial y} \right) + \frac{\partial}{\partial z} \left(\psi \frac{\partial \psi}{\partial z} \right)$$

$$\begin{aligned}
 &= \left(\frac{\partial \varphi}{\partial x} \right)^2 + \varphi \frac{\partial^2 \varphi}{\partial x^2} + \left(\frac{\partial \varphi}{\partial y} \right)^2 + \varphi \frac{\partial^2 \varphi}{\partial y^2} \\
 &\quad + \left(\frac{\partial \varphi}{\partial z} \right)^2 + \varphi \left(\frac{\partial^2 \varphi}{\partial z^2} \right) \\
 &= \|\nabla \varphi\|^2 + \varphi \Delta \varphi
 \end{aligned}$$

b)

$$\Delta G = \nabla(\operatorname{div}(G)) - \operatorname{rot}(\operatorname{rot}(G))$$

$$\nabla \cdot (\mathbf{G}) = \left(\frac{\partial G_3}{\partial y} - \frac{\partial G_2}{\partial z} \right) \hat{i}$$

$$+ \left(\frac{\partial G_1}{\partial z} - \frac{\partial G_3}{\partial x} \right) \hat{j}$$

$$+ \left(\frac{\partial G_2}{\partial x} - \frac{\partial G_1}{\partial y} \right) \hat{k}$$

$$\nabla \cdot (\nabla \cdot (\mathbf{G})) = \left(\frac{\partial}{\partial y} \left(\frac{\partial G_2}{\partial x} - \frac{\partial G_1}{\partial y} \right) - \frac{\partial}{\partial z} \left(\frac{\partial G_1}{\partial z} - \frac{\partial G_3}{\partial x} \right) \right) \hat{i}$$

$$+ \left(\frac{\partial}{\partial z} \left(\frac{\partial G_3}{\partial y} - \frac{\partial G_2}{\partial z} \right) - \frac{\partial}{\partial x} \left(\frac{\partial G_2}{\partial x} - \frac{\partial G_1}{\partial y} \right) \right) \hat{j}$$

$$+ \left(\frac{\partial}{\partial x} \left(\frac{\partial G_1}{\partial z} - \frac{\partial G_3}{\partial x} \right) - \frac{\partial}{\partial y} \left(\frac{\partial G_3}{\partial y} - \frac{\partial G_2}{\partial z} \right) \right) \hat{k}$$

$$= \left(-\frac{\partial^2 G_1}{\partial y^2} - \frac{\partial^2 G_1}{\partial z^2} + \frac{\partial^2 G_2}{\partial x \partial y} + \frac{\partial^2 G_3}{\partial x \partial z} \right) \hat{i}$$

$$+ \left(-\frac{\partial^2 G_2}{\partial x^2} - \frac{\partial^2 G_2}{\partial z^2} + \frac{\partial^2 G_1}{\partial x \partial y} + \frac{\partial^2 G_3}{\partial y \partial z} \right) \hat{j}$$

$$+ \left(-\frac{\partial^2 G_3}{\partial x^2} - \frac{\partial^2 G_3}{\partial y^2} + \frac{\partial^2 G_1}{\partial x \partial z} + \frac{\partial^2 G_2}{\partial y \partial z} \right) \hat{k}$$

$$\begin{aligned} \nabla(\text{Div}(G)) &= \nabla \left(\frac{\partial G_1}{\partial x} + \frac{\partial G_2}{\partial y} + \frac{\partial G_3}{\partial z} \right) \\ &= \left(\frac{\partial^2 G_1}{\partial x^2} + \frac{\partial^2 G_2}{\partial x \partial y} + \frac{\partial^2 G_3}{\partial x \partial z} \right) \hat{i} \\ &\quad + \left(\frac{\partial^2 G_2}{\partial y^2} + \frac{\partial^2 G_1}{\partial x \partial y} + \frac{\partial^2 G_3}{\partial y \partial z} \right) \hat{j} \\ &\quad + \left(\frac{\partial^2 G_3}{\partial z^2} + \frac{\partial^2 G_1}{\partial x \partial z} + \frac{\partial^2 G_2}{\partial y \partial z} \right) \hat{k} \end{aligned}$$

$$\begin{aligned} \nabla(\text{Div}(G)) - \text{rot}(\text{rot}(G)) &= \left(\frac{\partial^2 G_1}{\partial x^2} + \frac{\partial^2 G_1}{\partial y^2} + \frac{\partial^2 G_1}{\partial z^2} \right) \hat{i} \\ &\quad + \left(\frac{\partial^2 G_2}{\partial x^2} + \frac{\partial^2 G_2}{\partial y^2} + \frac{\partial^2 G_2}{\partial z^2} \right) \hat{j} \\ &\quad + \left(\frac{\partial^2 G_3}{\partial x^2} + \frac{\partial^2 G_3}{\partial y^2} + \frac{\partial^2 G_3}{\partial z^2} \right) \hat{k} \end{aligned}$$

P1. Coordenadas bipolares (σ, τ) , con $\sigma \in (0, 2\pi)$ y $\tau \in (-\infty, \infty)$. La a es una constante, estas coordenadas cumplen que:

$$x = a \frac{\sinh(\tau)}{\cosh(\tau) - \cos(\sigma)} \text{ e } y = a \frac{\sin(\sigma)}{\cosh(\tau) - \cos(\sigma)}$$

a) Pruebe que el gradiente en estas coordenadas es: $\nabla f = \frac{(\cosh(\tau) - \cos(\sigma))}{a} \left(\frac{\partial f}{\partial \sigma} \hat{\sigma} + \frac{\partial f}{\partial \tau} \hat{\tau} \right)$

b) Pruebe que la formula para el laplaciano es: $\Delta f = \frac{(\cosh(\tau) - \cos(\sigma))^2}{a^2} \left(\frac{\partial^2 f}{\partial \sigma^2} + \frac{\partial^2 f}{\partial \tau^2} \right)$

Indicación: Pruebe que $h_\sigma = h_\tau = \frac{a}{\cosh(\tau) - \cos(\sigma)}$

P2. Pruebe las siguientes identidades:

$$\frac{\partial x}{\partial \sigma} = \frac{a \sinh(\tau)}{(\cosh(\tau) - \cos(\sigma))^2} \sin \sigma$$

$$\frac{\partial y}{\partial \sigma} = a \left(\frac{\cos \sigma (\cosh(\tau) - \cos \sigma) - \sin^2 \sigma}{(\cosh(\tau) - \cos(\sigma))^2} \right).$$

$$= a \frac{(\cosh(\tau) \cos \sigma - 1)}{(\cosh \tau - \cos(\sigma))^2}$$

$$h_\sigma^2 = \frac{a^2}{(\cosh(\tau) - \cos \sigma)^4} \left(\sinh^2(\tau) \sin^2 \sigma + \cosh^2(\tau) \cos^2 \sigma - 2 \cosh \tau \cos \sigma + 1 \right)$$

$$\cosh(\tau)^2 - 2 \cosh \tau \cosh \sigma + \cosh \sigma^2 \quad \text{also } \text{same}$$

$$= \frac{a^2}{(\quad)^4} \left(\cancel{1} + \cosh^2 \tau - 1 \right) (1 - \cosh^2 \sigma) + \cosh^2 \tau \cosh^2 \sigma - 2 \cosh \tau \cosh \sigma$$

$$= \frac{a^2}{(\quad)^4} \left(\cancel{1} + \cosh^2 \tau + \cosh^2 \sigma - \cosh^2 \tau \cosh^2 \sigma + \cosh^2 \tau \cosh^2 \sigma - 2 \cosh \tau \cosh \sigma + \cancel{1} \right)$$

$$= \frac{a^2}{(\quad)^4} (\quad)^2 = \frac{a^2}{(\quad)^2}$$

$$h_\sigma = \frac{a}{(\cosh \tau - \cosh \sigma)}$$

$$h_\tau = \frac{a}{(\cosh \tau - \cosh \sigma)}$$

Caso 2 Variables

$$\nabla f = \frac{1}{h_u} \frac{\partial f}{\partial u} \hat{u} + \frac{1}{h_v} \frac{\partial f}{\partial v} \hat{v} + \text{[scribbled out]}$$

$$\Delta \phi = \frac{1}{h_1 h_2} \sum_{j=1}^2 \frac{\partial}{\partial w_j} \left[\frac{h_1 h_2}{h_j^2} \left(\frac{\partial \phi}{\partial w_j} \right) \right]$$

P2. Pruebe las siguientes identidades:

a) $\Delta(fg) = f\Delta g + g\Delta f + 2\nabla f \cdot \nabla g$

b) $\text{rot}(F) = F \text{div}(G) - G \text{div}(F) + (G \cdot \nabla)F - (F \cdot \nabla)G$

$$\Delta(fg) = \frac{\partial^2}{\partial x^2}(fg) + \frac{\partial^2}{\partial y^2}(fg) + \frac{\partial^2}{\partial z^2}(fg)$$

$$= \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial x} \cdot g + \frac{\partial g}{\partial x} f \right) + \dots$$

$$= \frac{\partial^2 f}{\partial x^2} g + 2 \frac{\partial f}{\partial x} \frac{\partial g}{\partial x} + \frac{\partial^2 g}{\partial x^2} f$$

$$+ \frac{\partial^2 f}{\partial y^2} g + 2 \frac{\partial f}{\partial y} \frac{\partial g}{\partial y} + \frac{\partial^2 g}{\partial y^2} f$$

$$+ \frac{\partial^2 f}{\partial z^2} g + 2 \frac{\partial f}{\partial z} \frac{\partial g}{\partial z} + \frac{\partial^2 g}{\partial z^2} f$$

$$\nabla f \cdot \nabla g = \begin{pmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{pmatrix} \cdot \begin{pmatrix} \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} & \frac{\partial g}{\partial z} \end{pmatrix}$$

$$b) (F \cdot \nabla) G = F \cdot (\nabla G_1) \hat{i} + F \cdot (\nabla G_2) \hat{j} + F \cdot (\nabla G_3) \hat{k}$$

P2. Pruebe las siguientes identidades:

$$a) \Delta(fg) = f\Delta g + g\Delta f + 2\nabla f \cdot \nabla g$$

$$b) \operatorname{rot}(F) = F \operatorname{div}(G) - G \operatorname{div}(F) + (G \cdot \nabla)F - (F \cdot \nabla)G$$

$$\begin{aligned} \operatorname{rot}(F) &= \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \hat{i} \\ &+ \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \hat{j} \\ &+ \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \hat{k} \end{aligned}$$

$$\begin{aligned}
 (G \cdot \nabla) F = & \left(G_1 \cdot \frac{\partial F_1}{\partial x} + G_2 \cdot \frac{\partial F_1}{\partial y} + G_3 \frac{\partial F_1}{\partial z} \right) \hat{i} \\
 & + \left(G_1 \cdot \frac{\partial F_2}{\partial x} + G_2 \cdot \frac{\partial F_2}{\partial y} + G_3 \frac{\partial F_2}{\partial z} \right) \hat{j} \\
 & + \left(G_1 \cdot \frac{\partial F_3}{\partial x} + G_2 \cdot \frac{\partial F_3}{\partial y} + G_3 \frac{\partial F_3}{\partial z} \right) \hat{k}
 \end{aligned}$$

(Iguarala est nla as an)

$\Gamma \alpha (F \times G)$