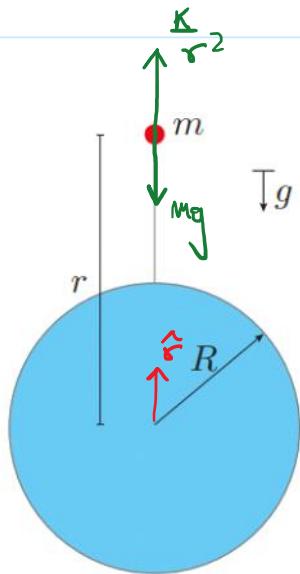


# Auxiliar 13



$$\vec{F}_{\text{neto}} = \sum \vec{F} = \left( \frac{k}{r^2} - mg \right) \hat{r} = m \ddot{r}$$

$$V_1(\vec{r}), V_2(\vec{r}), -\nabla V_i = \vec{F}_i, i=1, 2$$

$$-\nabla V_1(\vec{r}) = \frac{k}{r^2} \hat{r}$$

$$-\nabla V_2(\vec{r}) = -mg \hat{r}$$

$$\Rightarrow -\frac{\partial V_1}{\partial r} \hat{r} = \frac{k}{r^2} \hat{r} \wedge -\frac{\partial V_2}{\partial r} \hat{r} = -mg \hat{r}$$

$$\frac{\partial V_1}{\partial r} = -\frac{k}{r^2} \wedge \frac{\partial V_2}{\partial r} = mg$$

$$\int_{r_0}^r dV_1 = \int_{r_0}^r -\frac{k}{r^2} dr$$

$$\int_{r_0}^r \partial V_2 = \int_{r_0}^r mg dr$$

$$V_1(r) - V_1(r_0) = \frac{k}{r} - \frac{k}{r_0}$$

$$V_2(r) - V_2(r_0) = mg(r - r_0)$$

$$r_0 \rightarrow \infty$$

$r_0 \rightarrow 0$

$$V_2(r_0) = 0$$

$$V_1(r_0) = 0$$

$$V_1(r) = \frac{k}{r}$$

$$V_2(r) = mg r$$

$$V(r) = V_1(r) + V_2(r) = \frac{k}{r} + mg r$$

# Auxiliar 13

$$V(r) = \mu gr + \frac{K}{r} \quad \{m, g, K\}$$

punto de equilibrio  $r_e$

$$\left. \frac{\partial V}{\partial r} \right|_{r=r_e} = 0, \quad \frac{\partial V}{\partial r} = mg - \frac{K}{r^2}$$

$$\left. \frac{\partial V}{\partial r} \right|_{r=r_e} = mg - \frac{K}{r_e^2} = 0$$

$$r_e^2 = \frac{K}{mg} \Rightarrow r_e = \sqrt{\frac{K}{mg}}$$

$$\frac{\partial^2 V}{\partial r^2} = +\frac{2K}{r^3} \quad \left. \frac{\partial^2 V}{\partial r^2} \right|_{r=r_e} = \frac{2K}{\left(\frac{K}{mg}\right)^{3/2}} > 0$$

$\Rightarrow r_e$  es estable

$\Rightarrow$  existen pequeñas oscilaciones ( $\omega = \frac{2\pi}{T}$ )

$$\omega_{po}^2 = \frac{\left. \frac{\partial^2 V}{\partial r^2} \right|_{r=r_e}}{m} = \frac{2K}{m \left(\frac{K}{mg}\right)^{3/2}} = \frac{4\pi^2}{T^2}$$

$$T^2 = \frac{2\pi^2 m \left(\frac{K}{mg}\right)^{3/2}}{K}$$

# Auxiliar 13

$$V(r) = mg r + \frac{K}{r^2}$$

$$V(r_e) = mg r_e + \frac{K}{r_e^2}$$

$$\frac{\partial V}{\partial r}(r_e) = 0$$

$$\frac{\partial^2 V}{\partial r^2}(r_e) = \frac{2K}{\left(\frac{K}{mg}\right)^{3/2}}$$

$$V(r) = V(r_e) + \frac{\partial V}{\partial r}(r_e)(r - r_e) + \frac{\partial^2 V}{\partial r^2}(r_e) \frac{(r - r_e)^2}{2}$$

# Auxiliar 13

$$\Delta K = \sum w \quad \text{pq no hoy}$$

$$= \sum w_c + \cancel{\sum w_{nc}}^0 \quad \text{faz N.C.}$$

$$= -\Delta V$$

$$\cancel{\Delta K}^0 = -\Delta V \Rightarrow \Delta K + \Delta V = 0$$

$$\Delta (K + V) = 0$$

$$\Delta E = 0$$

$$\Rightarrow -\Delta V = 0 \Leftrightarrow \Delta V = 0$$

$$V = \mu g r + \frac{K}{r}$$

$$r_i = r_0$$

$$r_f = R$$

$$\Delta V = V(R) - V(r_0) = 0 \Rightarrow V(R) = V(r_0)$$

$$= \mu g R + \frac{K}{R} \left( -\mu g r_0 + \frac{K}{r_0} \right) = 0$$

$$\Rightarrow \mu g R r_0 + \frac{K}{R} r_0 - \mu g r_0^2 - K = 0$$

$$\mu g r_0^2 - r_0 \left( \mu g R - \frac{K}{R} \right) + K = 0$$

# Auxiliar 13

$$\cancel{mg r_0^2} \cancel{- m_0} \left( mgR + \frac{K}{R} \right) + K = 0$$
$$\cancel{mg R^2} - \cancel{mg R^2} - \cancel{\frac{R \cdot K}{R}} + K$$

$$mg(r_0 - R) = (r_0 - R) \frac{K}{r_0 R}$$

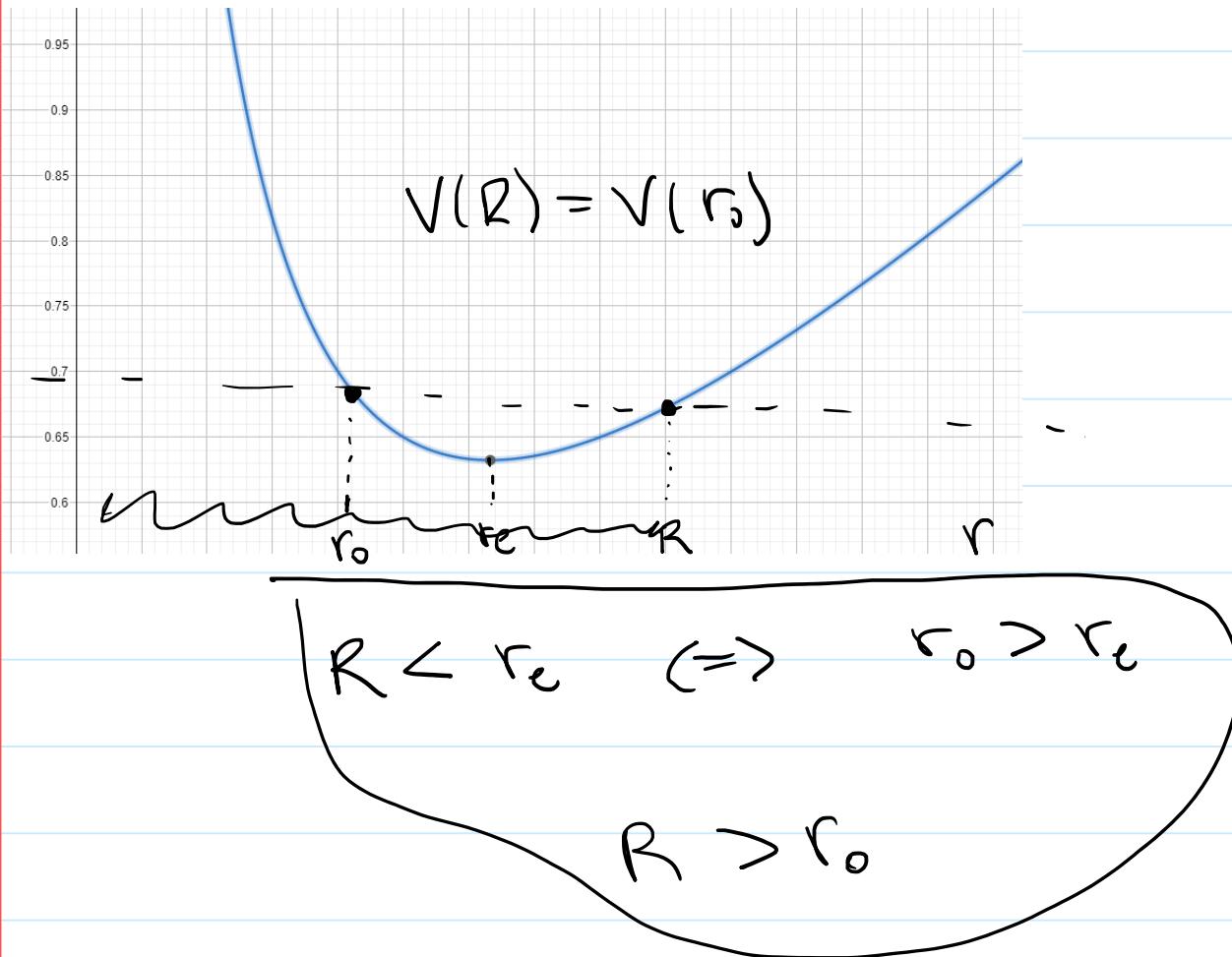
$$r_0 \neq R$$

$$mg = \frac{K}{r_0 R}$$

$$V(x) = \frac{1}{2} K x^2$$

$$r_0 = \frac{K}{mgR}$$

# Auxiliar 13



# Auxiliar 13

$$\text{L.G.V. : } \vec{F}_g = -\frac{G M m}{r^2} \hat{r}$$

$$V_g(r) = -\frac{G M m}{r}$$

completo  $-\nabla V_g = \vec{F}_g$

$$E = \frac{1}{2} m v^2 - \frac{G M m}{r}$$

$$E_1 = \frac{1}{2} m v_s^2 - \frac{G M m}{R_0}$$

$$E_2 = \frac{1}{2} m (\alpha v_0)^2 - \frac{G M m}{R_0}$$

$$E_3 = 0$$

$$\frac{1}{2} m (\alpha v_0)^2 - \frac{G M m}{R_0} = 0$$

$$\boxed{\alpha^2 = \frac{2GM}{v_0^2 R_0}} = \frac{2GM}{Gm} = 2$$

# Auxiliar 13

$$+ \frac{GM\alpha}{R^2} = + \cancel{\alpha} \frac{V_0^2}{R_0}$$

$$\boxed{GM = V_0^2 R_0}$$

$$\Rightarrow \alpha \leq \sqrt{2}$$

# Auxiliar 13

$$\mu = \frac{1}{r(\theta)}$$

$$-m\bar{v}^2\bar{\mu}^2 \left( \frac{d^2\bar{\mu}}{d\theta^2} + \bar{\mu} \right) = -F(\bar{\mu}^t)$$

$$h = \frac{L}{m} = \frac{m \cdot \alpha v_0 \cdot R_0}{m} = \alpha v_0 R_0$$

$$\bar{h}^2 = \alpha^2 v_0^2 R_0^2 \leftarrow$$

$$F(r) = -\frac{G M M}{r^2} \Leftrightarrow F(\bar{v}^t) = -G M M \bar{\mu}^2$$

$$+ m \alpha^2 v_0^2 R_0^2 \bar{\mu}^2 \left( \frac{d^2\bar{\mu}}{d\theta^2} + \bar{\mu} \right) = + G M M \bar{\mu}^2$$

$$\frac{d^2\bar{\mu}}{d\theta^2} + \bar{\mu} = \frac{GM}{\alpha^2 v_0^2 R_0^2} = \frac{GM}{\alpha^2 R_0 (v_0^2 R_0)} \cancel{GM}$$

$$\frac{d^2\bar{\mu}}{d\theta^2} + \bar{\mu} = \frac{1}{\alpha^2 R_0}$$

$$\bar{\mu} = A \cos(\theta + \delta) + \frac{1}{\alpha^2 R_0}$$

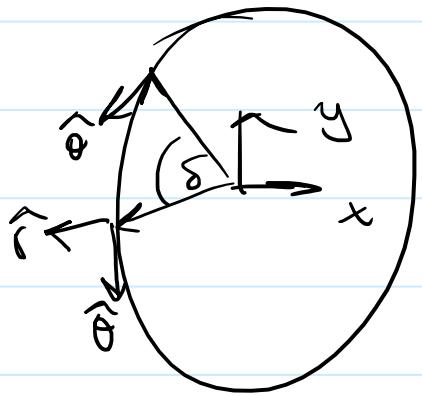
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ctos de integración

# Auxiliar 13

$$u(\theta) = A \cos(\theta + \delta) + \frac{1}{\alpha^2 R_0}$$

$$\delta = 0$$

$$\frac{1}{r(\theta)} = A \cos(\theta) + \frac{1}{\alpha^2 R_0}$$



$$r(\theta) = \frac{1}{\frac{1}{\alpha^2 R_0} + A \cos(\theta)}$$

$$r(\theta=0) = R_0$$

$$\frac{1}{\frac{1}{\alpha^2 R_0} + A} = R_0 \Rightarrow A = \frac{\alpha^2 - 1}{\alpha^2 R_0} > 0$$

$$= A > 0 \qquad \qquad \alpha > 1$$

# Auxiliar 13

$$r(\theta) = \frac{1}{\frac{1}{\alpha^2 R_0} + A \cos(\theta)} \quad , \quad A = \frac{\alpha^2 - 1}{\alpha^2 R_0} > 0$$

$$R_+ = r(\theta^*)$$

$$\frac{1}{\alpha^2 R_0} + A \cos(\theta^*)$$

↓  
see below more preferable  
possible

$$\theta^* = \pi \Rightarrow \cos(\theta^* = \pi) = -1$$

$$r(\pi) = R_+ = \frac{1}{\frac{1}{\alpha^2 R_0} - \left( \frac{\alpha^2 - 1}{\alpha^2 R_0} \right)}$$

$$R_+ = \frac{1}{\frac{1 - \alpha^2 + 1}{\alpha^2 R_0}}$$

$$\frac{R_+}{R_0} = \frac{\alpha^2}{2 - \alpha^2}$$

# Auxiliar 13

