

Auxiliar 1

CINEMATICA

$$\vec{r}(t), \vec{v}(t), \vec{a}(t)$$

$$\left. \begin{aligned} \vec{v} &= \frac{d\vec{r}(t)}{dt} \\ \vec{a} &= \frac{d\vec{v}(t)}{dt} \end{aligned} \right\} \quad \vec{a}(t) = \frac{d^2\vec{r}(t)}{dt^2}$$

$$\vec{F} = m \vec{a}$$
$$= m \frac{d^2\vec{x}}{dt^2}$$

$$\boxed{\begin{aligned} x(t_0) &= x_0 \\ v(t_0) &= v_0 \end{aligned}}$$

$$x(t) = -\frac{g}{e} \sin(\theta(t))$$



$$\frac{d\dot{\theta}}{dt} = \frac{d^2\theta}{dt^2}$$

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$$a(t) = v(t) \cdot t$$

↓

$$\frac{dv(t)}{dt} = v(t) \cdot t \iff \frac{dv(t)}{v(t)} = t \cdot dt$$

$$\int_{\underset{\underset{v_0}{||}}{v(t_0)}}^{v(t)} \frac{dv(t)}{v(t)} = \int_{t_0=0}^t t \, dt$$

$$\ln(v(t)) \Big|_{v_0}^{v(t)} = \frac{t^2}{2} \Big|_0^t$$

$$\ln(v(t)) - \ln(v_0) = \frac{t^2}{2}$$

$$\ln\left(\frac{v(t)}{v_0}\right) = \frac{t^2}{2}$$

$$\frac{v(t)}{v_0} = e^{t^2/2} \Rightarrow v(t) = v_0 e^{t^2/2}$$

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$$\frac{dx(t)}{dt} = v_0 e^{t^2/2}$$

$$dx(t) = v_0 e^{t^2/2} \cdot dt$$

$$\int_{\substack{x(t) \\ x(t_0) \\ x_0}} dx(t) = v_0 \int_{t_0=0}^t e^{t^2/2} dt$$

$$x(t) - x_0 = v_0 \int_0^t e^{t^2/2} dt$$

$$x(t) = x_0 + v_0 \int_0^t e^{t^2/2} \widehat{dt}$$

$$[dv] = \frac{L}{T}$$

$$[dt] = T$$

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$$Q(t) = -\beta x^2(t)$$

$$\frac{dv(t)}{dt} = -\beta x^2(t)$$

Truco de mec.
↑

$$\frac{dv(t)}{dt} \cdot \frac{dx(t)}{dx(t)} = \frac{dv(t)}{dx} \cdot \frac{dx(t)}{dt} = \boxed{\frac{dv(x)}{dx} v(x) = a}$$

$$\frac{dv(x)}{dx} \cdot v(x) = -\beta x^2$$
$$\int_{v(x_0)}^{v(x)} v \cdot dv = -\beta \int_{x_0}^x x^2 dx$$

$\underbrace{v(x_0)}_{v_0}$

$$\frac{v^2}{2} \Big|_{v_0}^{v(x)} = -\beta \frac{x^3}{3} \Big|_{x_0}^x$$

$$(v^2(x) - v_0^2) = -\frac{2\beta}{3} (x^3 - x_0^3)$$

$$v(x) = \sqrt{v_0^2 - \frac{2\beta}{3} (x^3 - x_0^3)}$$

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$$a(t) = -2\gamma v(t) - \omega_0^2 x(t)$$

$$\frac{dv(t)}{dt} = \frac{d^2 x(t)}{dt^2} = -2\gamma \frac{dx(t)}{dt} - \omega_0^2 x(t)$$

$$\frac{d^2 x(t)}{dt^2} + 2\gamma \frac{dx(t)}{dt} + \omega_0^2 x(t) = 0$$

$$\text{Ansatz: } x(t) = e^{\lambda t} \rightarrow \frac{dx(t)}{dt} = \lambda e^{\lambda t} \rightarrow \frac{d^2 x(t)}{dt^2} = \lambda^2 e^{\lambda t}$$

$$\cancel{\lambda^2 e^{\lambda t}} + 2\gamma \cancel{\lambda e^{\lambda t}} + \omega_0^2 \cancel{e^{\lambda t}} = 0$$

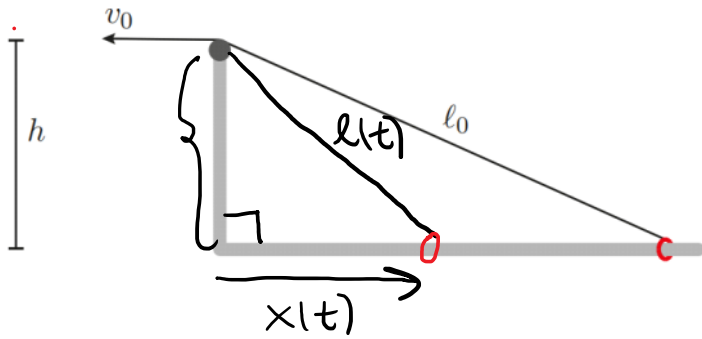
$$\lambda^2 + 2\gamma \lambda + \omega_0^2 = 0 \Rightarrow \lambda = \frac{-2\gamma \pm \sqrt{(4\gamma^2 - 4\omega_0^2)}}{2}$$

$$\lambda = -\gamma \pm \sqrt{\gamma^2 - \omega_0^2} \begin{cases} \lambda_+ = -\gamma + \sqrt{\gamma^2 - \omega_0^2} \\ \lambda_- = -\gamma - \sqrt{\gamma^2 - \omega_0^2} \end{cases}$$

$$x(t) = A_+ e^{\lambda_+ t} + A_- e^{\lambda_- t}$$

$$x(t) = A_+ e^{(-\gamma + \sqrt{\gamma^2 - \omega_0^2})t} + A_- e^{(-\gamma - \sqrt{\gamma^2 - \omega_0^2})t}$$

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Pitágoras: $h^2 + x^2(t) = l^2(t)$

$$x^2(t) = l^2(t) - h^2$$

$$x^2(t) = (l_0 - v_0 t)^2 - h^2$$

$$x(t) = \sqrt{(l_0 - v_0 t)^2 - h^2}$$

$$\frac{dl(t)}{dt} = \dot{l}(t) = -v_0$$

$$\frac{dl}{dt} = -v_0$$

$$\int_{l_0}^{l(t)} dl = - \int_0^t v_0 \cdot dt$$

$$l(t) - l_0 = -v_0 t$$

$$l(t) = l_0 - v_0 t$$

$$\frac{dx}{dt} \stackrel{!}{< 0} \rightarrow +$$