

$$\vec{a} = \begin{pmatrix} \ddot{r} - r\dot{\theta}^2 - r\sin^2(\theta)\dot{\varphi}^2 \\ r\ddot{\theta} + 2\dot{r}\dot{\theta} - r\sin(\theta)\cos(\theta)\dot{\varphi}^2 \\ r\sin(\theta)\ddot{\varphi} + 2\dot{r}\dot{\varphi}\sin(\theta) + 2r\dot{\theta}\dot{\varphi}\cos(\theta) \end{pmatrix} \begin{pmatrix} \hat{u}_r \\ \hat{u}_\theta \\ \hat{u}_\varphi \end{pmatrix}$$

$$m\vec{g} = -mg\cos\theta\hat{r} + mg\sin\theta\hat{\theta}$$

$$\vec{N} = -N\hat{\theta}$$

Escribimos las ec de m.b.v.

Como

$$\hat{r} \quad m(\ddot{r} - r\dot{\theta}^2 - r\sin^2\theta\dot{\varphi}^2) = -mg\cos\theta$$

$$\hat{\theta} \quad m(r\ddot{\theta} + 2\dot{r}\dot{\theta} - r\sin\theta\cos\theta\dot{\varphi}^2) = -N + mg\sin\theta$$

$$\varphi \quad m(r\sin\theta\ddot{\varphi} + 2\dot{r}\dot{\varphi}\sin\theta + 2r\dot{\theta}\dot{\varphi}\cos\theta) = 0$$

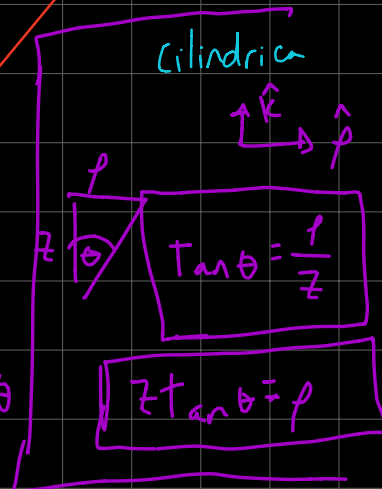
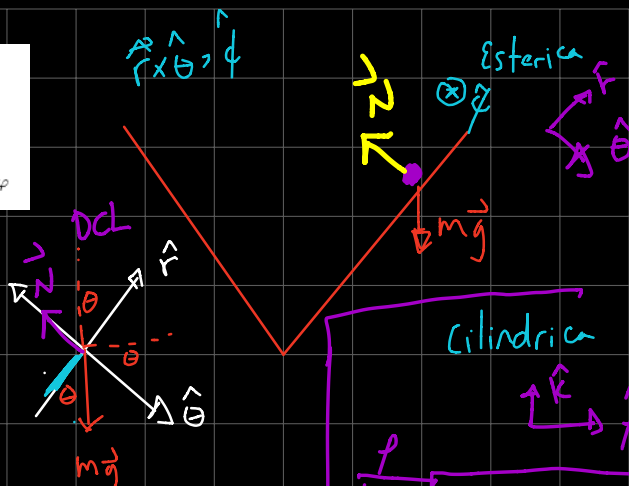
Como no hay fzas en φ , escribo ap como

$$(3) \quad m \frac{1}{r\sin\theta} \frac{d}{dt}(r^2\sin^2\theta\dot{\varphi}) = 0 \quad / \text{Cons. momento angular}$$

$$(1) \quad m(\ddot{r} - r\sin^2\theta\dot{\varphi}^2) = -mg\cos\theta \quad \checkmark \quad \checkmark (\text{Ec de M.b.v})$$

$$(2) \quad -m r \sin\theta \cos\theta \dot{\varphi}^2 = -N + mg\sin\theta \quad \checkmark$$

Condición mov circular vel $V_0 \leftarrow \text{conocido} \Rightarrow \dot{r} = \ddot{r} = 0$



Def: $\cancel{+ m r \sin^2 \theta \dot{\varphi}^2} = \cancel{+ m g \cos \theta}$ (4)

¿Como escribo V_0 en estas cas?

$$\dot{\varphi} = \begin{bmatrix} 1 & 15 \end{bmatrix}$$

$$\vec{V}_0 = \cancel{\dot{r}} \hat{r} + r \dot{\varphi} \sin \theta \hat{\varphi} + r \dot{\theta} \hat{\theta}$$

$$V_0 = r \dot{\varphi} \sin \theta \quad (5)$$

(5) en (4) $\Rightarrow$ $\frac{V_0^2}{r} = g \cos \theta \Rightarrow r_0 = \frac{V_0^2}{g \cos \theta}$

Perturbamos radialmente

$$(3) \quad m \frac{1}{r \sin \theta} \cdot \underbrace{\frac{d}{dt} (r^2 \sin^2 \theta \dot{\varphi})}_{=0} = 0 \quad \boxed{\dot{\varphi}}$$

$$(2) \quad m (\ddot{r} - r \sin^2 \theta \dot{\varphi}^2) = -mg \cos \theta \quad \checkmark$$

Si perturbamos, pasan 2 cosas r deja de ser cte y $\dot{\varphi}$ deja de ser cte

$$\Rightarrow r^2 \sin^2 \theta \dot{\varphi} = C$$

$$r \sin \theta \cdot (r \sin \theta \dot{\varphi}) = C$$

/ Usaremos la CI para
acontrar C

/ CI $\Rightarrow r=r_0 \quad r \sin \theta \dot{\varphi} = V_0$

$$r_0 \sin \theta \cdot V_0 = C \Rightarrow C \text{ es conocido}$$

$$\dot{\varphi} = \frac{C}{r^2 \sin^2 \theta}, \text{ lo reemplazo en mi ec en } \hat{r}$$

$$m(\ddot{r} - r \sin^2 \theta \dot{\varphi}^2) = -mg \cos \theta \checkmark$$

$$\ddot{r} - r \sin^2 \theta \cdot \frac{C^2}{r^4 \sin^4 \theta} = -g \cos \theta$$

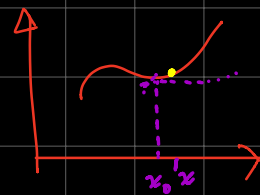
$$\hat{r} \left[\ddot{r} - \frac{1}{r^3} \cdot \frac{C^2}{\sin^2 \theta} = -g \cos \theta \right] \leftarrow \text{Desplaza el pto de eq,}$$

$$\ddot{r} + \ddot{r} \omega^2 = 0$$

$$r = r_0 + \epsilon \Rightarrow \ddot{r} = \ddot{\epsilon}$$

$$f(x) \sim f(x_0) + (x - x_0) \cdot f'(x) \Big|_{x_0} + \frac{(x - x_0)^2}{2} f''(x)$$

$$f(x) = \frac{1}{x^3} \quad f'(x) = -3 \frac{1}{x^4}$$



$$\frac{1}{r^3} = \frac{1}{r_0^3} + (r_0 + \epsilon - r_0) \cdot \left(-3 \cdot \frac{1}{x^4} \Big|_{r_0} \right)$$

$$= \frac{1}{r_0^3} - \epsilon \cdot \frac{3}{r_0^4} //$$

Nuestra nueva ec será

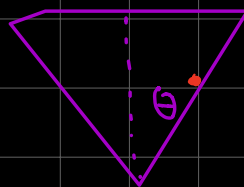
$$\ddot{\epsilon} - \left(\frac{1}{r_0^3} - \epsilon \cdot \frac{3}{r_0^4} \right) \cdot \frac{C^2}{\sin^2 \theta} = -g \cos \theta$$

$$\ddot{\epsilon} + \epsilon \cdot \frac{3C^2}{r_0^4 \sin^2 \theta} = \frac{1}{r_0^3} \frac{C^2}{\sin^2 \theta} - g \cos \theta$$

$$\omega^2 = \frac{3C^2}{r_0^4 \sin^2 \theta}$$

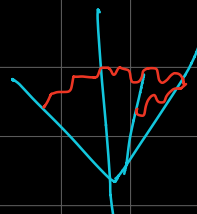
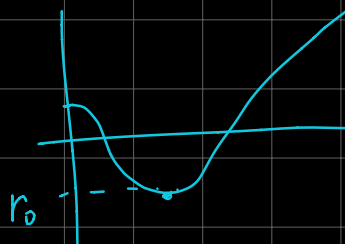
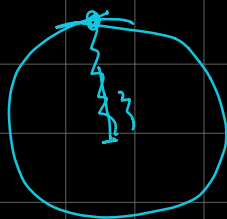
$$C = r_0 \sin \theta V_0$$

$$\omega^2 = \frac{3 \cdot V_0^2}{r_0^2}$$



$$\left. \frac{dU_{\text{eff}}}{dr} \right|_{V=V_0} = 0 \quad \leftarrow \text{Condición para } \underline{r_0}$$

$$V_0 = r_0 \sin \theta \dot{\varphi}$$



$$\omega_{p_0} = \sqrt{\frac{U''_{\text{eff}}(r_0)}{\beta}}$$

usualmente es la masa

$$E(q, \dot{q}) = \left[\frac{1}{2} B \dot{q}^2 + U_{\text{eff}}(q) \right]$$

q es coordenada
 $r, \dot{r}$
 $\theta, \dot{\theta}$

$$V_{\text{est}} = \dot{r} \hat{r} + r \dot{\theta} \hat{\theta} + r \sin \theta \dot{\varphi} \hat{\varphi}$$

$$E = \frac{1}{2} m \dot{r}^2 + \frac{1}{2} m (r \dot{\theta})^2 + \frac{1}{2} m (r \sin \theta \dot{\varphi})^2 + U$$

$\underbrace{\hspace{10em}}_{U_{\text{eff}}}$

$$V_{\text{cl}} = \dot{r} \hat{r} + r \dot{\theta} \hat{\theta}$$

P2] $F(\rho) = -K\rho$

Ecu de N.O.V Cilindricas

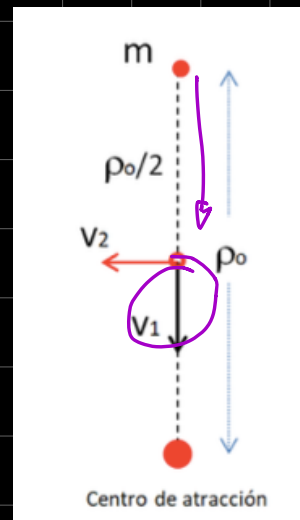
$$m(\ddot{\rho} - \rho \dot{\theta}^2) = -K\rho$$

Que en linea recta $\Rightarrow \dot{\theta} = 0$

$$m \ddot{\rho} = -K\rho \quad / \quad \ddot{\rho} = \dot{\rho} \frac{d\dot{\rho}}{d\rho}$$

$$\int_0^{\dot{\rho}} \dot{\rho} \frac{d\dot{\rho}}{d\rho} d\rho = -\frac{K}{m} \int_{\rho_0}^{\rho} \rho d\rho$$

$$\frac{\dot{\rho}^2}{2} = -\frac{K}{m} \left[\frac{\rho^2}{2} \right]_{\rho_0}^{\rho} = -\frac{K}{m} \left[\frac{\rho^2}{2} - \frac{\rho_0^2}{2} \right]$$



$$\frac{1}{2} = \frac{1}{m} \left[\frac{1}{2} \rho_0^2 \dot{\theta}^2 \right] = \frac{1}{m} \left[\frac{1}{4} \rho_0^2 \dot{\theta}^2 \right]$$

$$\dot{\rho}^2 = + \frac{k}{m} \left[+ \frac{3}{4} \rho_0^2 \right]$$

$$V_1 = \rho_0 \sqrt{\frac{k}{m}} \cdot \frac{\sqrt{3}}{2} \leftarrow \text{Velocidad en } \rho_0/2$$

$$V_2 = \frac{1}{\sqrt{3}} V_1 = \rho_0 \sqrt{\frac{k}{m}} \cdot \frac{1}{2}$$

Como encuentro la velocidad maxima y la distancia minima? Para responder esto, sera util pensar en terminos de Energía, para ello veamos el potencial asociado a la fuerza del problema

$$F = -\nabla U$$

$$+k\rho = +\nabla U = \frac{d}{d\rho} U \quad / \int \frac{d}{d\rho} U \cdot d\rho = \int k\rho d\rho$$

$$U = \frac{1}{2} k \rho^2$$

$$U = k \frac{\rho^2}{2}$$

Mientras mas pequeño sea rho, mas pequeño es el potencial, tenemos tambien que E=K+U, por lo que habra mas energia cinetica (velocidad) mientras mas cerca estemos.

Entonces el rho_min y v_max ocurren simultaneamente.

Para encontrarlos usaremos, conservacion de energia y conservacion de momento angular (ausencia de fuerzas en phi_tongo)

Notamos que en p_min la velocidad es solo tangencial.

$$\text{Por en } \hat{\theta} \left[m(\rho \ddot{\theta} + 2\dot{\rho} \dot{\theta}) = 0 \right]$$

$$\frac{1}{\rho} \frac{d}{dt} (\rho^2 \dot{\theta}) = 0$$

$$\rho^2 \dot{\theta} = C$$

Necesitamos encontrar C, usamos instante

① $\rho V_T = C$ inicial / En cualquier momento $\rho = \frac{\rho_0}{2}$ y $V_1 = V_2$

$$C = \frac{\rho_0}{2} \cdot \rho_0 \sqrt{\frac{k}{m}} \cdot \frac{1}{2} = \frac{\rho_0^2}{4} \sqrt{\frac{k}{m}} //$$

② $E_i = E_f$ $U = \frac{1}{2} k \rho^2$

$$E_i = \frac{1}{2} m V_1^2 + \frac{1}{2} m V_2^2 + \frac{1}{2} k \left(\frac{\rho_0}{2}\right)^2 \quad / V_1 = \frac{\sqrt{3}}{2} \rho_0 \sqrt{\frac{k}{m}}$$

$$= \frac{1}{2} \cdot \left[\frac{3}{4} \rho_0^2 \frac{k}{m} + \frac{\rho_0^2}{4} \frac{k}{m} + k \frac{\rho_0^2}{4} \right]$$

$$E_i = \frac{1}{2} \rho_0^2 k \left[\frac{5}{4} \right]$$

$$E_f = \frac{1}{2} m V_{\max}^2 + \frac{1}{2} k \rho_{\min}^2$$

$V_{\max}$ es solo tangencial $C = V_{\max} \rho_{\min}$

$$\frac{\rho_0^2}{4} \sqrt{\frac{k}{m}} = \rho_{\min} \cdot V_{\max} \quad (1)$$

$$\frac{5}{8} E_i = \frac{1}{2} m V_{\max}^2 + \frac{1}{2} k \rho_{\min}^2 \quad (2)$$

$$\rho_{\min} = a \cdot \rho_0$$

$$V_{\max} = b \cdot \rho_0 \sqrt{\frac{k}{m}}$$

$$\frac{1}{4} \cdot \cancel{f_0^2} \sqrt{\frac{k}{m}} = a \cdot \cancel{f_0} \cdot b \cdot \cancel{f_0} \sqrt{\frac{k}{m}} \Rightarrow \frac{1}{4} = a \cdot b \quad (3)$$

$$\frac{5}{8} \cancel{k} \cancel{f_0^2} = \frac{1}{2} m \cdot b^2 \cancel{f_0^2} \cdot \frac{k}{m} + \frac{1}{2} \cancel{k} a^2 \cancel{f_0^2} \Rightarrow \frac{5}{4} = a^2 + b^2 \quad (4)$$

$$2 \cdot (3) + (4)$$

$$\frac{2}{4} + \frac{5}{4} = (a+b)^2$$

$$\sqrt{\frac{7}{4}} = a+b \quad (5)$$

$$-2 \cdot (3) + (4)$$

$$-\frac{2}{4} + \frac{5}{4} = (a-b)^2$$

$$\sqrt{\frac{3}{4}} = a-b \quad (6)$$

$$(5) + (6)$$

$$\frac{\sqrt{7}}{2} + \frac{\sqrt{3}}{2} = 2a \Rightarrow a = \frac{\sqrt{7} + \sqrt{3}}{4}$$

$$(5) - (6)$$

$$\frac{\sqrt{7}}{2} - \frac{\sqrt{3}}{2} = 2b \quad b = \frac{\sqrt{7} - \sqrt{3}}{4}$$

$$f_{\min} = a f_0$$

$$V_{\max} = b \cdot f_0 \sqrt{\frac{k}{m}}$$