

Paula Aux 9

P1

$$(a) \quad a(a^\dagger)^n \phi_0 = a a^\dagger (a^\dagger)^{n-1} \phi_0 = a^\dagger a (a^\dagger)^{n-1} \phi_0 + (a^\dagger)^{n-1} \phi_0 = a^\dagger a a^\dagger (a^\dagger)^{n-2} \phi_0 + (a^\dagger)^{n-1} \phi_0 \\ = (a^\dagger)^2 a (a^\dagger)^{n-2} \phi_0 + 2(a^\dagger)^{n-1} \phi_0 = \dots = n(a^\dagger)^{n-1} \phi_0 //$$

$$(b) \quad a(e^{\alpha a^\dagger} \phi_0) = C \sum_{n=0}^{\infty} \frac{\alpha^n}{n!} a(a^\dagger)^n \phi_0 = C \sum_{n=0}^{\infty} \frac{\alpha^n}{n!} n(a^\dagger)^{n-1} \phi_0 = \alpha C e^{\alpha a^\dagger} \phi_0 = \alpha \psi_\alpha //$$

$$\langle \psi_\alpha | \psi_\alpha \rangle = 1 = |C|^2 \langle \phi_0 | e^{\alpha^* a} e^{\alpha a^\dagger} | \phi_0 \rangle = |C|^2 \langle \phi_0 | e^{\alpha a^\dagger} e^{\alpha^* a} e^{[\alpha^* a, \alpha a^\dagger]} | \phi_0 \rangle \\ = |C|^2 e^{|\alpha|^2} \Rightarrow |C| = \frac{1}{\sqrt{\exp(|\alpha|^2)}}$$

$$(c) \quad (a^\dagger) \phi_n = \sqrt{n+1} \phi_{n+1}, \quad (a^\dagger)^n \phi_0 = \sqrt{n!} \phi_n \Rightarrow \psi_\alpha = C \sum \frac{\alpha^n}{n!} \phi_n \\ \Rightarrow P_n = |C|^2 |\alpha|^{2n} \cdot \frac{1}{n!} = \frac{|\alpha|^{2n}}{n!} e^{-|\alpha|^2}$$

$$(d) \quad N = a^\dagger a \quad \langle N \rangle = \langle \psi_\alpha | a^\dagger a | \psi_\alpha \rangle = |\alpha|^2$$

(e) $H = \hbar\omega(N + \frac{1}{2})$. La acción de H sobre sus autoestados la conocemos:
 $H \phi_n = \hbar\omega(n + \frac{1}{2}) \phi_n$. Mientras tanto, $a \phi_n = \sqrt{n} \phi_{n-1}$ para $n \geq 1$. En estos casos claramente los autoestados de H no son estados coherentes. Pero ϕ_0 sí lo es, con autovector $\alpha = 0$.

$$(f) \quad \Delta x^2 = \langle x^2 \rangle - \langle x \rangle^2, \quad x = \sqrt{\frac{\hbar}{2m\omega}} (a + a^\dagger), \quad p = i\sqrt{\frac{\hbar m\omega}{2}} (a^\dagger - a)$$

$$\Delta p^2 = \langle p^2 \rangle - \langle p \rangle^2.$$

$$\langle x^2 \rangle = \frac{\hbar}{2m\omega} \langle \psi_\alpha | (a + a^\dagger)^2 | \psi_\alpha \rangle = \frac{\hbar}{2m\omega} [\langle \psi_\alpha | a^2 | \psi_\alpha \rangle + \langle \psi_\alpha | (a^\dagger)^2 | \psi_\alpha \rangle + \underbrace{\langle \psi_\alpha | a a^\dagger | \psi_\alpha \rangle + \langle \psi_\alpha | a^\dagger a | \psi_\alpha \rangle}_{+1}]$$

$$\Rightarrow \langle x^2 \rangle = \frac{\hbar}{2m\omega} [\alpha^2 + (\alpha^*)^2 + 2|\alpha|^2 + 1], \quad \langle x \rangle = \sqrt{\frac{\hbar}{2m\omega}} \langle \psi_\alpha | a + a^\dagger | \psi_\alpha \rangle = \sqrt{\frac{\hbar}{2m\omega}} [\alpha + \alpha^*]$$

$$\Rightarrow \Delta x^2 = \frac{\hbar}{2m\omega}$$

$$\langle p^2 \rangle = -\frac{\hbar m\omega}{2} [\alpha^2 + (\alpha^*)^2 - \langle \psi_\alpha | a^\dagger a | \psi_\alpha \rangle - \langle \psi_\alpha | a a^\dagger | \psi_\alpha \rangle] = -\frac{\hbar m\omega}{2} [\alpha^2 + (\alpha^*)^2 - 2|\alpha|^2 - 1]$$

$$\langle p \rangle = i\sqrt{\frac{\hbar m\omega}{2}} [\alpha^* - \alpha] \Rightarrow \Delta p^2 = \frac{\hbar m\omega}{2} \{1\} \Rightarrow \Delta p \Delta x = \frac{\hbar}{2}, \text{ incerteza mínima.} //$$

P2 $\phi(\vec{x}, t) = \int \frac{d^3k}{(2\pi)^3} \cdot \frac{1}{\sqrt{2\omega_k}} \left[e^{-ik_\mu x^\mu} a_k + e^{ik_\mu x^\mu} a_k^\dagger \right]$

$$\langle 0 | \phi(x_1) \phi(x_2) | 0 \rangle = \int \frac{d^3k}{(2\pi)^3} \frac{d^3p}{(2\pi)^3} \cdot \frac{1}{\sqrt{2\omega_k}} \cdot \frac{1}{\sqrt{2\omega_p}} \langle 0 | (e^{-ik_\mu x_1^\mu} a_k + e^{ik_\mu x_1^\mu} a_k^\dagger) (e^{-ip_\mu x_2^\mu} a_p + e^{ip_\mu x_2^\mu} a_p^\dagger) | 0 \rangle$$

Pero $a_k | 0 \rangle = a_p | 0 \rangle = 0$, $\langle 0 | a_p^\dagger = \langle 0 | a_k^\dagger = 0$. Además, $\langle 0 | a_k a_p^\dagger | 0 \rangle = \langle 0 | a_p^\dagger a_k | 0 \rangle = \langle [a_k, a_p^\dagger] \rangle$

$$[a_k, a_p^\dagger] = (2\pi)^3 \delta^3(\vec{k} - \vec{p}) \Rightarrow \langle \phi(x_1) \phi(x_2) \rangle = \int \frac{d^3k}{(2\pi)^3} \cdot \frac{1}{2\omega_k} e^{-ik_\mu (x_1^\mu - x_2^\mu)} \quad \text{Entonces,}$$

$$\langle 0 | T \{ \phi(x_1) \phi(x_2) \} | 0 \rangle = \langle 0 | \phi(x_1) \phi(x_2) | 0 \rangle \theta(t_1 - t_2) + \langle 0 | \phi(x_2) \phi(x_1) | 0 \rangle \theta(t_2 - t_1)$$

$$= \int \frac{d^3k}{(2\pi)^3} \left[e^{ik_\mu (x_2^\mu - x_1^\mu)} \theta(t_1 - t_2) + e^{ik_\mu (x_1^\mu - x_2^\mu)} \theta(t_2 - t_1) \right] \cdot \frac{1}{2\omega_k}$$

$$= \int \frac{d^3k}{(2\pi)^3} \left[e^{i\vec{k} \cdot (\vec{x}_1 - \vec{x}_2)} e^{-i\omega_k \tau} \theta(\tau) + e^{-i\vec{k} \cdot (\vec{x}_1 - \vec{x}_2)} e^{i\omega_k \tau} \theta(-\tau) \right] \cdot \frac{1}{2\omega_k}, \quad \tau \equiv t_1 - t_2.$$

$$= \int \frac{d^3k}{(2\pi)^3} \left[\frac{e^{-i\vec{k} \cdot (\vec{x}_1 - \vec{x}_2)}}{2\omega_k} \right] \left[e^{-i\omega_k \tau} \theta(\tau) + e^{i\omega_k \tau} \theta(-\tau) \right]. \quad \text{Usaremos la siguiente identidad:}$$

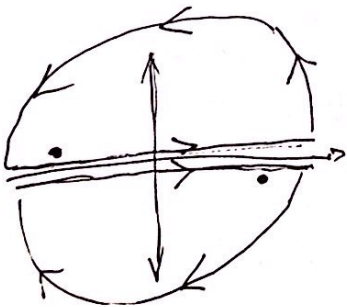
$$e^{-i\omega_k \tau} \theta(\tau) + e^{i\omega_k \tau} \theta(-\tau) = \lim_{\epsilon \rightarrow 0} \frac{-2\omega_k}{2\pi i} \int \frac{d\omega}{\omega^2 - \omega_k^2 + i\epsilon} e^{i\omega \tau}. \quad \text{Lo mostramos después.}$$

$$\Rightarrow \langle 0 | T \{ \phi(x_1) \phi(x_2) \} | 0 \rangle = \lim_{\epsilon \rightarrow 0} \int \frac{d^3k}{(2\pi)^3} \cdot \frac{e^{-i\vec{k} \cdot (\vec{x}_1 - \vec{x}_2)}}{2\omega_k} \int d\omega \frac{-2\omega_k}{2\pi i} \cdot \frac{e^{i\omega \tau}}{\omega^2 - \omega_k^2 + i\epsilon}$$

$$= \lim_{\epsilon \rightarrow 0} \int \frac{d^4k}{(2\pi)^4} \cdot \frac{i}{k_\mu k^\mu - m^2 + i\epsilon} e^{ik_\mu (x_1^\mu - x_2^\mu)}$$

Donde ya no se cumple
que $k_0^2 = \vec{k}^2 + m^2$.

Dem. de la identidad: A $\mathcal{O}(\epsilon)$, $\omega^2 - \omega_k^2 + i\epsilon = [\omega - (\omega_k - i\epsilon)][\omega - (-\omega_k + i\epsilon)]$, haciendo el cambio $\epsilon \leftrightarrow 2\epsilon\omega_k \Rightarrow \frac{1}{\omega^2 - \omega_k^2 + i\epsilon} = \frac{1}{2\omega_k} \left[\frac{1}{\omega - (\omega_k - i\epsilon)} - \frac{1}{\omega + (\omega_k - i\epsilon)} \right]$ Dos polos simples



$\tau = \int \frac{e^{i\omega \tau}}{\omega^2 - \omega_k^2 + i\epsilon} d\omega$. Para $\tau > 0$, cerramos el contorno por arriba. Al revés para $\tau < 0$.

$$\int \frac{e^{i\omega \tau} d\omega}{\omega^2 - \omega_k^2 + i\epsilon} = \left[\underbrace{\int \frac{e^{i\omega \tau} d\omega}{\omega - (\omega_k - i\epsilon)}}_{-2\pi i e^{i\omega_k \tau} \theta(-\tau)} - \underbrace{\int \frac{e^{i\omega \tau} d\omega}{\omega + (\omega_k - i\epsilon)}}_{2\pi i e^{-i\omega_k \tau} \theta(\tau)} \right] \cdot \frac{1}{2\omega_k}$$

$$\Rightarrow \lim_{\epsilon \rightarrow 0} \int \frac{d\omega}{\omega^2 - \omega_k^2 + i\epsilon} e^{i\omega \tau} = -\frac{2\pi i}{2\omega_k} \left[e^{i\omega_k \tau} \theta(-\tau) + e^{-i\omega_k \tau} \theta(\tau) \right]$$