

Tarea Auxiliar #10

P1) $f: \mathbb{R}^2 \rightarrow \mathbb{R}$, $f(x, y) = x^2 y + x \cos(y)$

Para calcular su serie de Taylor, basta con que recordemos la fórmula:

$$f(x, y) = f(x_0, y_0) + \nabla f(x_0, y_0)^T \begin{pmatrix} x - x_0 \\ y - y_0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} x - x_0 \\ y - y_0 \end{pmatrix}^T H_f(x_0, y_0) \begin{pmatrix} x - x_0 \\ y - y_0 \end{pmatrix} + R_2(x, y),$$

con $\lim_{(x, y) \rightarrow (x_0, y_0)} \frac{|R_2(x, y)|}{\|x - x_0\|^2} = 0$. Tomamos $(x_0, y_0) = (1, 0)$

• $f(1, 0) = 1$

• $\nabla f(1, 0) = \begin{pmatrix} 2xy + \cos(y) \\ x^2 - x \sin(y) \end{pmatrix} \Big|_{(1, 0)} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

• $H_f(1, 0) = \begin{pmatrix} 2y & 2x - \sin(y) \\ 2x - \sin(y) & -x \cos(y) \end{pmatrix} \Big|_{(1, 0)} = \begin{pmatrix} 0 & 2 \\ 2 & -1 \end{pmatrix}$

$\Rightarrow f(x, y) \approx 1 + \begin{pmatrix} 1 \\ 1 \end{pmatrix}^T \begin{pmatrix} x-1 \\ y \end{pmatrix} + \frac{1}{2} \begin{pmatrix} x-1 \\ y \end{pmatrix}^T \begin{pmatrix} 0 & 2 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} x-1 \\ y \end{pmatrix}$

$\Rightarrow f(x, y) \approx 1 + (1, 1) \begin{pmatrix} x-1 \\ y \end{pmatrix} + \frac{1}{2} (x-1, y) \begin{pmatrix} 0 & 2 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} x-1 \\ y \end{pmatrix}$

$= 1 + x - 1 + y + \frac{1}{2} (x-1, y) \begin{pmatrix} 2y \\ 2x - 2 - y \end{pmatrix}$

$= 1 + x - 1 + y + \frac{1}{2} [2xy - 2y + 2x - 2 - y]$

$= x - y + 2xy - \frac{1}{2} y^2$

⊗ Como f es
clase C^2 ,
tenemos como a
describir su
serie de Taylor.

P21 $f(x,y) = \begin{cases} \frac{xy(x^2-y^2)}{x^2+y^2} & (x,y) \neq (0,0) \\ 0 & (x,y) = (0,0) \end{cases}$

a) Calcule $\partial_x f(x,y)$ y $\partial_y f(x,y)$, para $(x,y) \neq (0,0)$

R: $\frac{\partial f}{\partial x}(x,y) = \frac{[y(x^2-y^2) + xy \cdot 2x](x^2+y^2) - 2x^2(xy^2-y^2)}{(x^2+y^2)^2}$

$$= \frac{y(x^4 + 4x^2y^2 - y^4)}{(x^2+y^2)^2}$$

$\cdot \frac{\partial f}{\partial y}(x,y) = \frac{[x(x^2-y^2) - xy \cdot 2y](x^2+y^2) - 2y^2(x^2-y^2)}{(x^2+y^2)^2}$

$$= \frac{x^5 - 4x^3y^2 - xy^4}{(x^2+y^2)^2}$$

b) Muestre que $\partial_x f(0,0) = \partial_y f(0,0) = 0$

R: $\cdot \frac{\partial f}{\partial x}(0,0) = \lim_{t \rightarrow 0} \frac{f(t,0) - f(0,0)}{t} = \lim_{t \rightarrow 0} \frac{1}{t} \cdot \frac{t \cdot 0 \cdot (t^2 - 0^2)}{t^2 + 0^2} = 0$

$\cdot \frac{\partial f}{\partial y}(0,0) = \lim_{t \rightarrow 0} \frac{f(0,t) - f(0,0)}{t} = \lim_{t \rightarrow 0} \frac{1}{t} \cdot \frac{0 \cdot t \cdot (0^2 - t^2)}{0^2 + t^2} = 0$

c) Calcule $\frac{\partial^2 f}{\partial x \partial y}(0,0)$ y $\frac{\partial^2 f}{\partial y \partial x}(0,0)$

sol: Usando la def (de der. diferencial):

$$\cdot \frac{\partial^2 f}{\partial x \partial y}(0,0) = \frac{\partial}{\partial x} \left(\frac{\partial f}{\partial y} \right)(0,0) = \lim_{t \rightarrow 0} \frac{\frac{\partial f}{\partial y}(t,0) - \frac{\partial f}{\partial y}(0,0)}{t} \rightarrow 0 \text{ (por (b))}$$

$$p_k(a) = \lim_{t \rightarrow 0} \frac{1}{t} \cdot \frac{t^5 - 4t^3 \cdot 0^2 - t \cdot 0^4}{(0^2 + t^2)^2}$$

$$= \lim_{t \rightarrow 0} \frac{1}{t} \cdot \frac{t^5}{t^4} = \lim_{t \rightarrow 0} 1 = 1 \quad \text{///} \rightarrow 0 \text{ (por (b))}$$

$$\cdot \frac{\partial^2 f}{\partial y \partial x}(0,0) = \frac{\partial}{\partial y} \left(\frac{\partial f}{\partial x} \right)(0,0) = \lim_{t \rightarrow 0} \frac{\frac{\partial f}{\partial x}(0,t) - \frac{\partial f}{\partial x}(0,0)}{t}$$

$$p_k(a) = \lim_{t \rightarrow 0} \frac{1}{t} \cdot \frac{t(0^4 + 4 \cdot 0^2 t^2 - t^4)}{(0^2 + t^2)^2}$$

$$= \lim_{t \rightarrow 0} \frac{-t^4}{t^4} = -1$$

d) ¿Qué vale?

sol: ~~Usando la definición de derivada~~

El teo. de Schwarz exige que C^2 .

Notemos que $f \sim 0$ en C^2 : si $(x,y) \neq (0,0)$, se tiene que $\frac{\partial^2 f}{\partial x^2}(x,y) = -\frac{4xy^3(x^2 - 3y^2)}{(x^2 + y^2)^3}$.

$$p_k(a) = \frac{\partial^2 f}{\partial x^2}(0,0) = \lim_{t \rightarrow 0} \frac{\frac{\partial^2 f}{\partial x^2}(t,0) - \frac{\partial^2 f}{\partial x^2}(0,0)}{t} = \lim_{t \rightarrow 0} \frac{1}{t} \cdot \frac{0 \cdot (t^4 + 4t^2 \cdot 0^2 - 0^4)}{(t^2 + 0^2)^2} = 0$$

Por otro lado, si tomamos $x_n = \frac{1}{n}$, $y_n = \frac{1}{n}$ ($x_n \rightarrow 0$ y $y_n \rightarrow 0$):

$$\frac{\partial^2 f}{\partial x^2}\left(\frac{1}{n}, \frac{1}{n}\right) = -\frac{4 \cdot \frac{1}{n} \cdot \left(\frac{1}{n}\right)^3 \left(\left(\frac{1}{n}\right)^2 - 3\left(\frac{1}{n}\right)^2\right)}{\left(\left(\frac{1}{n}\right)^2 + \left(\frac{1}{n}\right)^2\right)^3} = 1 \rightarrow 0 = \frac{\partial^2 f}{\partial x^2}(0,0)$$

(i.e., $\frac{\partial^2 f}{\partial x^2}(0,0)$ no es continuo) ///

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$$\begin{cases} x^2 y + \sin(xyz) + z^2 = 1 \\ e^{yz} + xz = 1 \end{cases}$$

implícita

a) Sol: Primero, hallamos el dominio de la f. ~~función~~:

Teo: (Función implícita)
Sea $f: \mathbb{R}^{m+l} \rightarrow \mathbb{R}^l$ de clase C^1 , sea $\bar{x} \in \mathbb{R}^m, \bar{y} \in \mathbb{R}^l$
talos que $f(\bar{x}, \bar{y}) = \bar{c}$, con $\bar{c} \in \mathbb{R}^l$. Si
 $D_y f(\bar{x}, \bar{y})$ ($\in L(\mathbb{R}^l, \mathbb{R}^l)$) es invertible, entonces
 $\exists U \subseteq \mathbb{R}^m$ con $\bar{x} \in U$, y $\exists \Phi: U \rightarrow \mathbb{R}^l$ de
clase C^1 tal que

$$f(x, \Phi(x)) = \bar{c}, \forall x \in U.$$

Además,

$$D\Phi(x) = -[D_y f(x, \Phi(x))]^{-1} \cdot D_x f(x, \Phi(x)), \forall x \in U.$$

Así, definamos $f: \mathbb{R}^{1+2} \rightarrow \mathbb{R}^2$ con

$$f(x, y, z) = (x^2 y + \sin(xyz) + z^2 - 1, e^{yz} + xz - 1),$$

y tomamos $\bar{x} = 1, (\bar{y}, \bar{z}) = (1, 0), \bar{c} = (0, 0)$. Ahora
verificamos las hipótesis:

1) $f(\bar{x}, \bar{y}, \bar{z}) = \bar{c}$: Directo. En efecto,

$$\begin{aligned} f(1, 1, 0) &= (1^2 \cdot 1 + \sin(1 \cdot 1 \cdot 0) + 0^2 - 1, e^{1 \cdot 0} + 1 \cdot 0 - 1) \\ &= (0, 0) \end{aligned}$$

2) f es C^1 : (húsnimo; álg. y comp. de C^1).

3) $D_{(y,z)} f(\bar{x}, \bar{y}, \bar{z})$ es invertible,

$$\begin{aligned} D_{(y,z)} f(\bar{x}, \bar{y}, \bar{z}) &= \begin{pmatrix} \frac{\partial f_1}{\partial y}(\bar{x}, \bar{y}, \bar{z}) & \frac{\partial f_1}{\partial z}(\bar{x}, \bar{y}, \bar{z}) \\ \frac{\partial f_2}{\partial y}(\bar{x}, \bar{y}, \bar{z}) & \frac{\partial f_2}{\partial z}(\bar{x}, \bar{y}, \bar{z}) \end{pmatrix} \\ &= \begin{pmatrix} \bar{x}^2 + 6y(\bar{x}\bar{y}\bar{z})\bar{x}\bar{z} & 6y(\bar{x}\bar{y}\bar{z})\bar{x}\bar{y} + 2\bar{z} \\ e^{\bar{y}\bar{z}} \cdot \bar{z} & e^{\bar{y}\bar{z}} \cdot \bar{y} + \bar{x} \end{pmatrix} \\ &= \begin{pmatrix} 1 & 1 \\ 0 & 2 \end{pmatrix} \end{aligned}$$

$$= \det(D_{(y,z)} f(\bar{x}, \bar{y}, \bar{z})) = 1 \cdot 2 - 0 \cdot 1 = 2 \neq 0$$

$\Rightarrow D_{(y,z)} f(\bar{x}, \bar{y}, \bar{z})$ es invertible $\Rightarrow$.

Y así hemos reunido las hip. del teo. 1, y se cumple lo pedido. $\square$

b) Sol: Aquí tenemos que usar la def. de derivada del teorema. Ordenámonos: la función $g(x,y,z) = x^2 + y^2 + z^2$ es diferenciable

$$\Rightarrow dg(x,y,z)d = \langle Dg(x,y,z), d \rangle, \forall d \text{ con } \|d\| = 1.$$

Debemos que la dir. tang. es $r'(t)$. En este caso:

$$r(t) = (t, y(t), z(t)) \Rightarrow r'(t) = (1, y'(t), z'(t)),$$

para $t=1$. Es decir, buscamos $(1, y'(1), z'(1))$.

Pero, de la 2ª Grc. se ve, se ve que:

$$D\mathcal{F}(\bar{x}) = -[D_{(y,z)}f(\bar{x}, \mathcal{F}(\bar{x}))]^{-1} \cdot D_x f(\bar{x}, \mathcal{F}(\bar{x})).$$

Calculamos $\mathcal{F}(\bar{x}) = \begin{pmatrix} y(\bar{x}) \\ z(\bar{x}) \end{pmatrix}$ (el vector).

Notemos que: (vemos $\bar{x} = 1$)

$$\bullet D_{(y,z)}f(\bar{x}, \mathcal{F}(\bar{x})) = D_{(y,z)}f(\bar{x}, \bar{y}, \bar{z})$$

$$\text{la sea en (a)} \quad \sim 1 = \begin{pmatrix} 1 & 1 \\ 0 & 2 \end{pmatrix}$$

$$\Rightarrow [D_{(y,z)}f(\bar{x}, \mathcal{F}(\bar{x}))]^{-1} = \begin{pmatrix} 1 & -\frac{1}{2} \\ 0 & \frac{1}{2} \end{pmatrix}$$

$$\bullet D_x f(\bar{x}, \mathcal{F}(\bar{x})) = D_x f(\bar{x}, \bar{y}, \bar{z}) = \begin{pmatrix} \frac{\partial f_1}{\partial x}(\bar{x}, \bar{y}, \bar{z}) \\ \frac{\partial f_2}{\partial x}(\bar{x}, \bar{y}, \bar{z}) \end{pmatrix}$$

$$= \begin{pmatrix} 2\bar{x} \cdot \bar{y} + \cos(\bar{x} \cdot \bar{y} \cdot \bar{z}) \bar{y} \bar{z} \\ \bar{z} \end{pmatrix}$$

$$= \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} y'(1) \\ z'(1) \end{pmatrix} = D\mathcal{F}(1) \neq \text{no}$$

$$= - \begin{pmatrix} 1 & -\frac{1}{2} \\ 0 & \frac{1}{2} \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} -2 \\ 0 \end{pmatrix}$$

$$\Rightarrow y'(1) = -2, \quad z'(1) = 0.$$

On d6:

$$\Rightarrow r'(1) = (1, y'(1), z'(1)) \\ = (1, -2, 0).$$

Notons que $\|r'(1)\| = \sqrt{1^2 + (-2)^2} = \sqrt{5}$. En plus,

$$dg(1, 1, 0; \frac{r'(1)}{\|r'(1)\|}) = \left\langle Dg(1, 1, 0), \frac{r'(1)}{\|r'(1)\|} \right\rangle$$

$$= \left\langle \begin{pmatrix} 2 \\ 2 \\ 0 \end{pmatrix}^T, \frac{1}{\sqrt{5}} \cdot \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix} \right\rangle \quad \left(\text{pus } Dg(x, y, z) = \begin{pmatrix} 2x \\ 2y \\ 2z \end{pmatrix} = 2 \begin{pmatrix} x \\ y \\ z \end{pmatrix} \right)$$

$$= -\frac{2}{\sqrt{5}}$$