

Universidad de Chile
Departamento de Geofísica

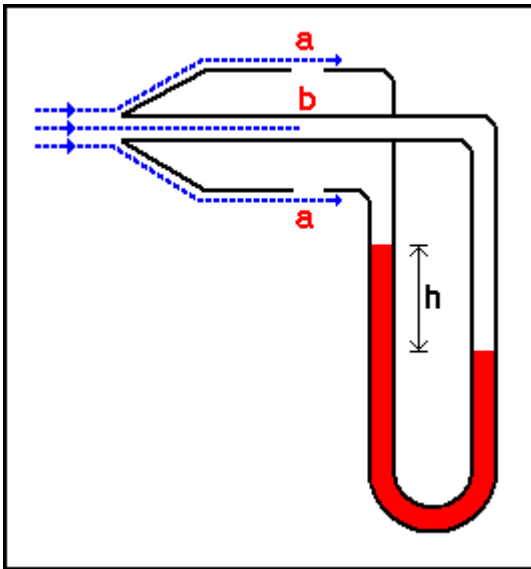
Introducción a la Meteorología

Dinámica Atmosférica



Prof. René Garreaud
www.dgf.uchile.cl/rene

Medición del viento en superficie
Magnitud: anemómetro



Pitot (calibración)



Manga de viento

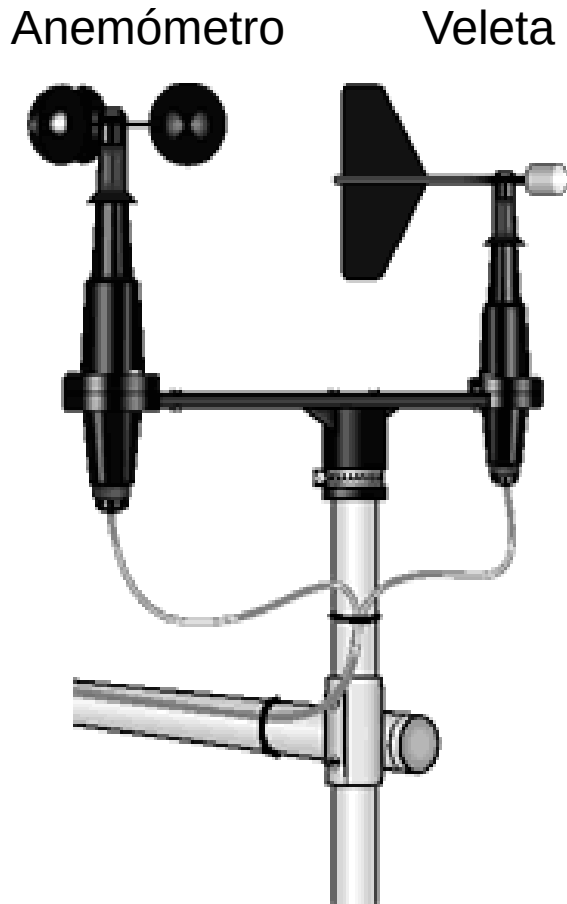


De Copela o rotación

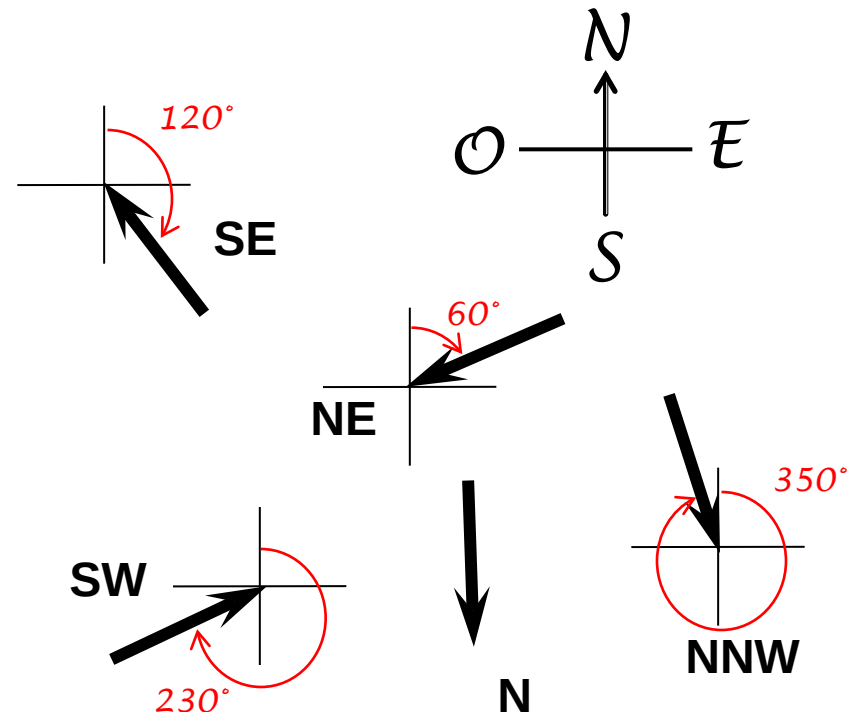


Infrasónico

Dirección del Viento



La dirección del viento se designa según la dirección geográfica desde donde el viento esta soplando. (desde donde viene). La dirección (dd) se mide c/r al Norte en forma horaria en grados sexagesimales.



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Observations for TEMUCO MAQUEHUE, Chile (SCTC)

Location: 38.75S 72.63W 120 meters

2200Z 15 May 2012 to 2200Z 16 May 2012

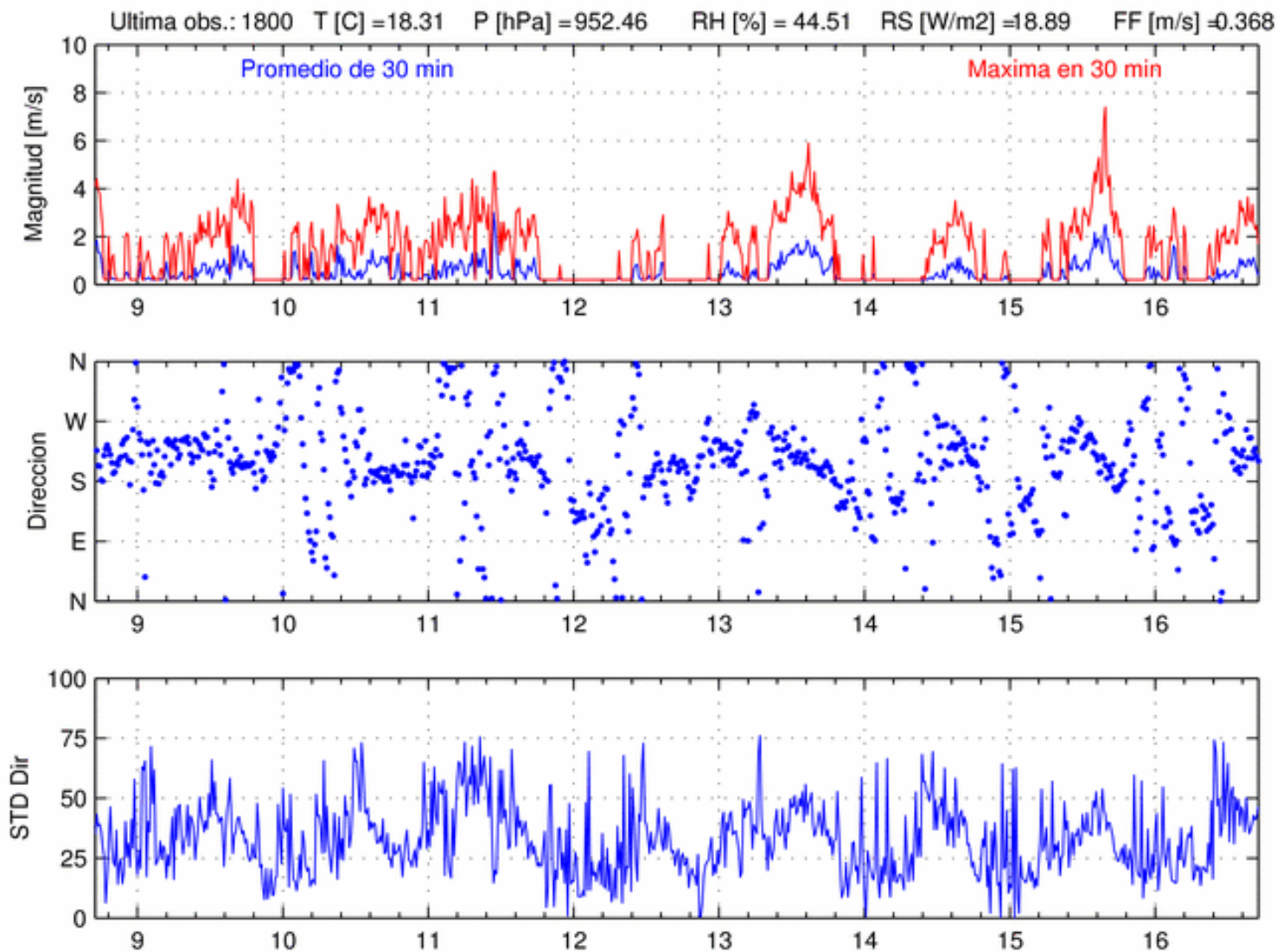
STN	TIME	ALTM	TMP	DEW	RH	DIR	SPD	VIS	CLOUDS	Weather
	DD/HHMM	hPa	C	C	%	deg	m/s	km		
SCTC	16/2200	1019.0	11	7	76	20	2	10.0		
SCTC	16/2100	1019.0	12	6	67	10	3	10.0		
SCTC	16/2000	1019.0	14	7	63	350	3	10.0	FEW025	SCT070
SCTC	16/1900	1019.0	14	6	59	330	3	10.0	SCT025	SCT070
SCTC	16/1800	1019.0	13	7	67	340	3	10.0	SCT025	BKN070
SCTC	16/1700	1020.0	12	10	88	80	3	10.0	FEW025	BKN070
SCTC	16/1600	1020.0	11	9	87	80	3	10.0	FEW025	BKN070
SCTC	16/1500	1021.0	8	8	100	70	4	7.0	BKN070	H
SCTC	16/1400	1021.0	7	7	100	80	3	2.0	BKN070	F
SCTC	16/1300	1020.0	6	5	93	90	2	0.3	BKN070	F
SCTC	16/1200	1020.0	4	4	100	90	2	0.2	BKN070	F
SCTC	16/1100	1020.0	3	2	93	90	2	0.8	SCT035	F
SCTC	16/1000	1019.0	3	2	93	0	0	0.2	CLR	F
SCTC	16/0900	1019.0	6	5	93	0	0	0.5		
SCTC	16/0800	1019.0	8	7	93	90	2	10.0		
SCTC	16/0700	1019.0	8	7	93	90	2	10.0		
SCTC	16/0600	1019.0	9	8	93	70	3	10.0	BKN020	
SCTC	16/0500	1018.0	9	8	93	70	2	10.0	OVC020	
SCTC	16/0400	1018.0	9	8	93		1	10.0	OVC020	
SCTC	16/0300	1017.0	9	9	100	250	1	8.0	OVC020	RW-
SCTC	16/0200	1017.0	10	9	93		2	10.0	BKN020	
SCTC	16/0100	1015.0	10	10	100	270	3	10.0	FEW006	SCT020
SCTC	16/0000	1014.0	11	10	94	310	4	7.0	SCT006	BKN020 OVC070 R
SCTC	15/2300	1012.0	12	10	88	360	5	7.0	BKN020	OVC070 R
SCTC	15/2200	1012.0	11	10	94	360	6	7.0	BKN020	OVC070 R

Viento débil del N

Viento débil del E

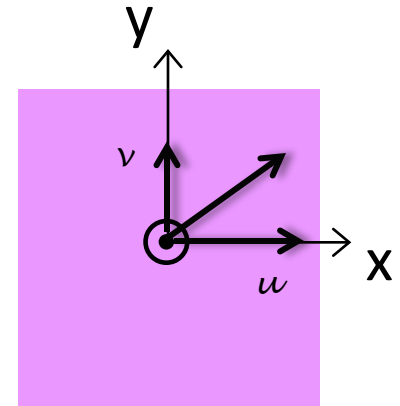
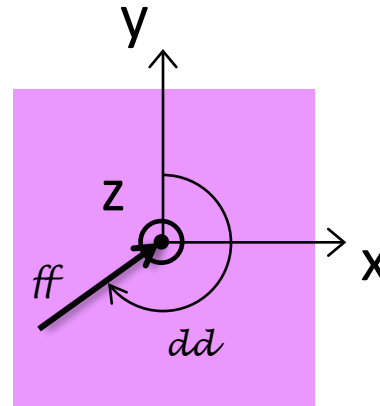
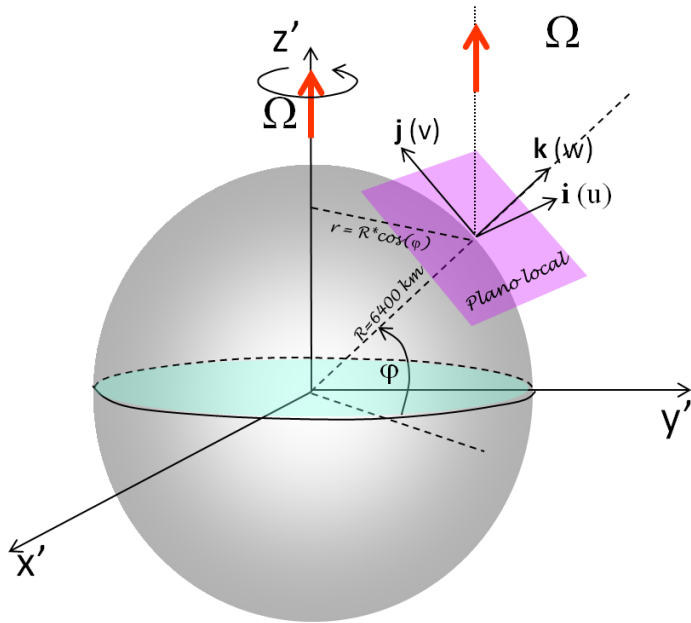
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X: Dirección zonal (W-E)...Componente Zonal $u = dx/dt$

Y: Dirección Meridional (S-N) ...Componente Meridional $v = dy/dt$

Z: Dirección vertical...Componente vertical $w = dz/dt$

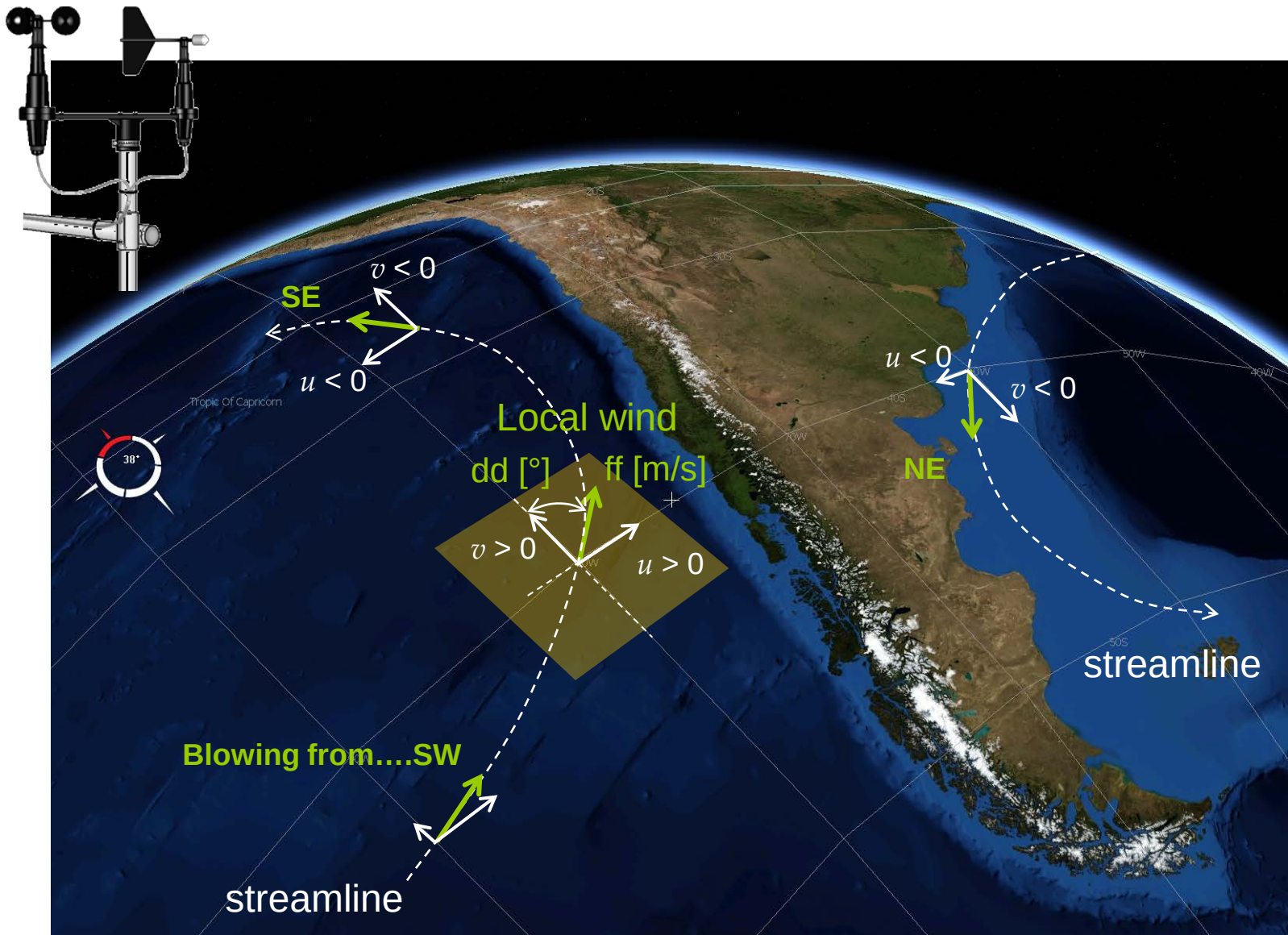
$$U = -ff \cdot \sin(dd)$$

$$V = -ff \cdot \cos(dd)$$

$$ff = \sqrt{U^2 + V^2}$$

$$dd = \text{atan}(ff/dd)$$

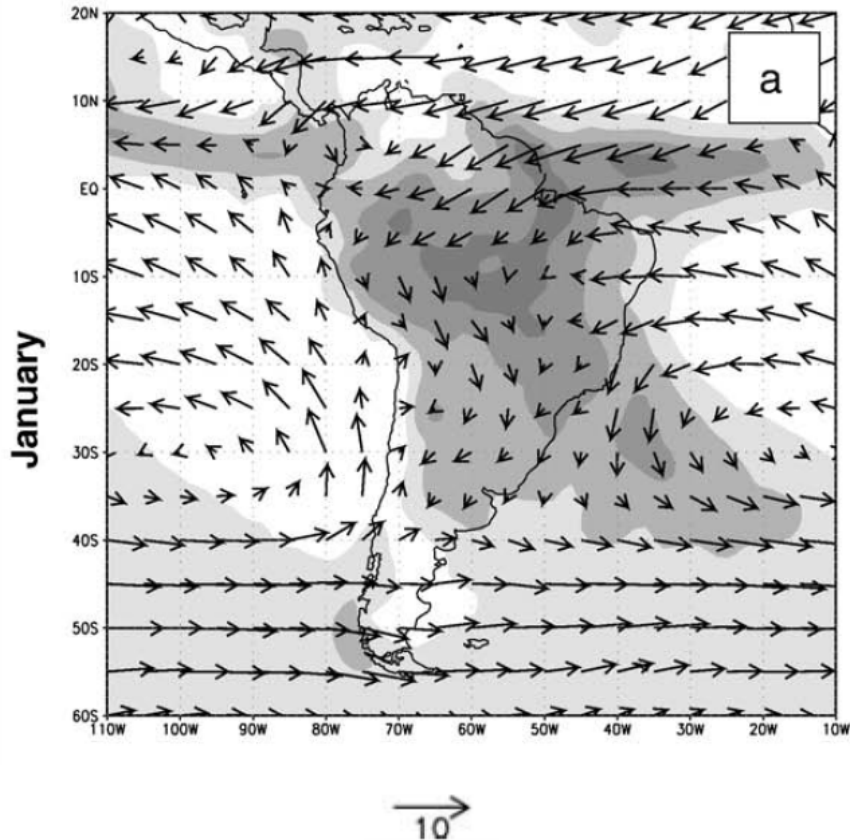
Wind is a vector: magnitude (speed) and blowing direction ($^{\circ}$ wrt north)
Alternatively, zonal (u , west-east) and meridional (v , south-north) components



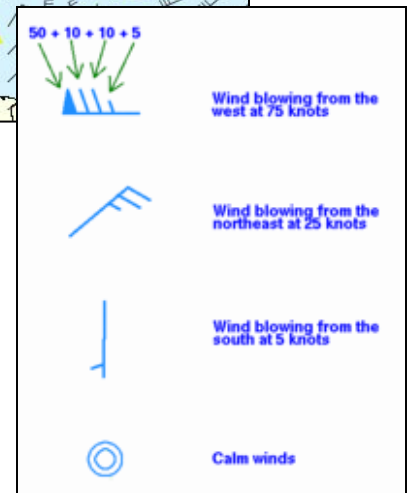
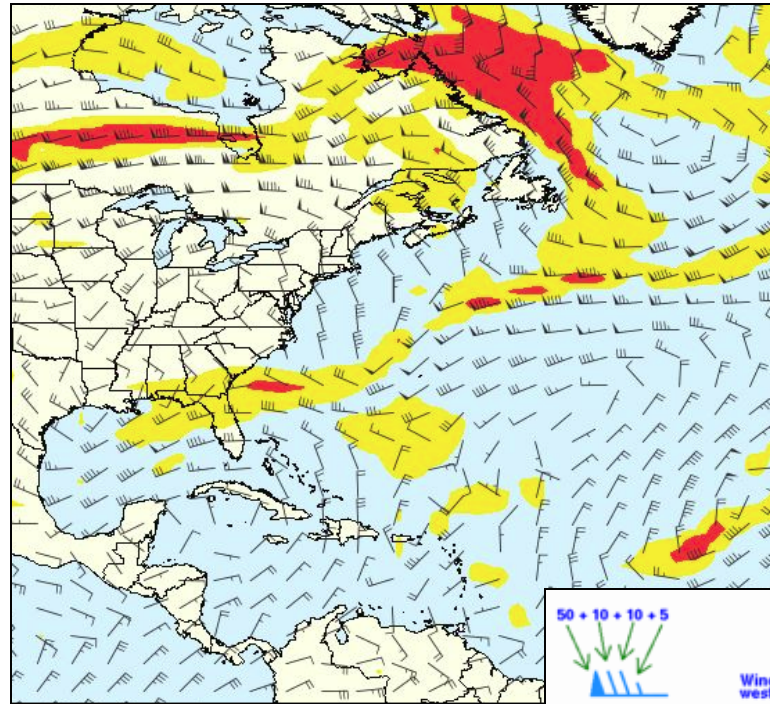
Representación de viento en Mapas

Vectores

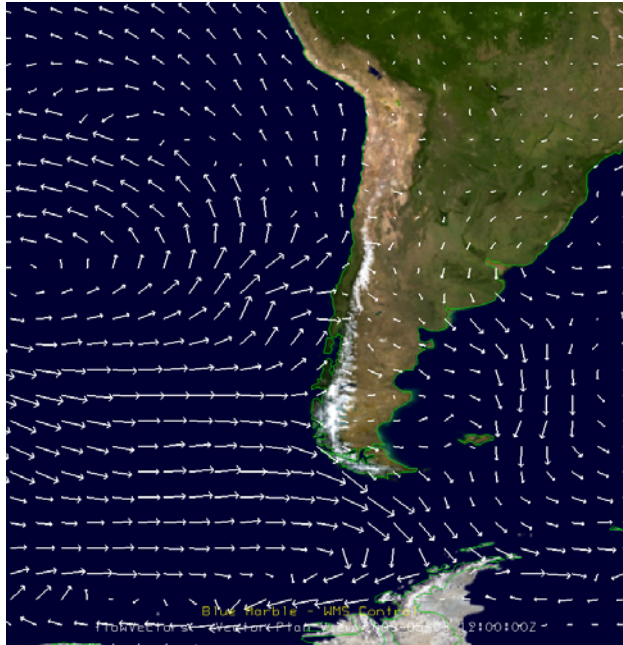
Precipitation and 925 hPa winds



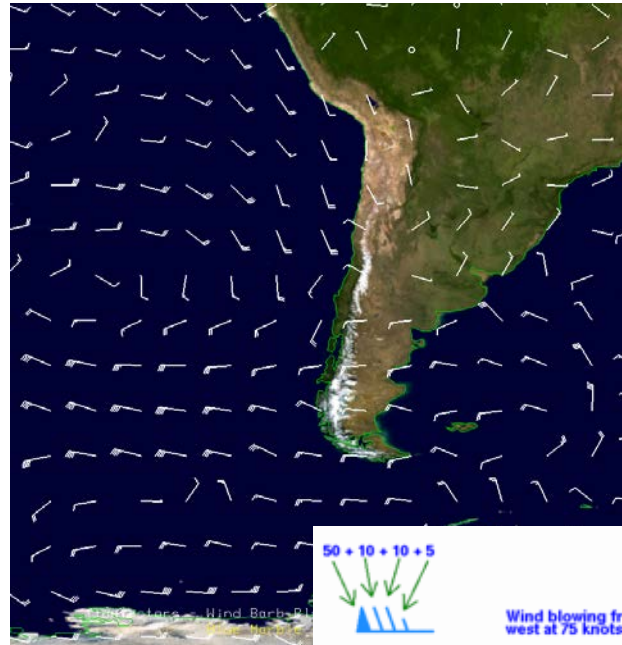
Barbas



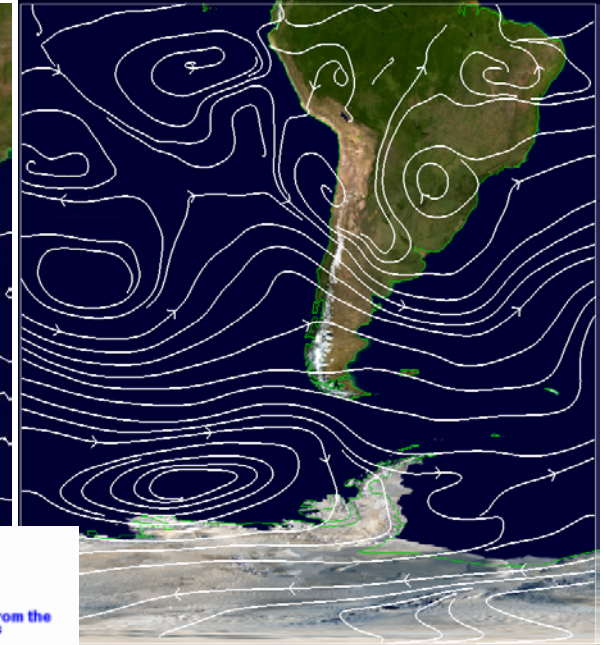
Representación de viento en Mapas



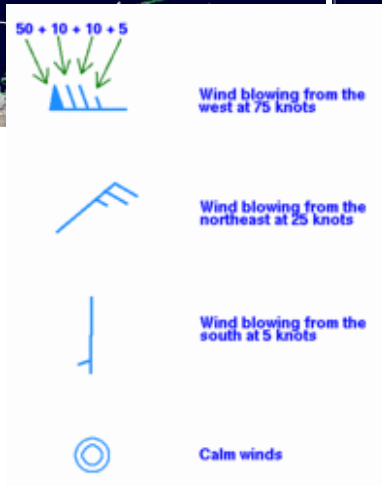
Vectores



Barbas



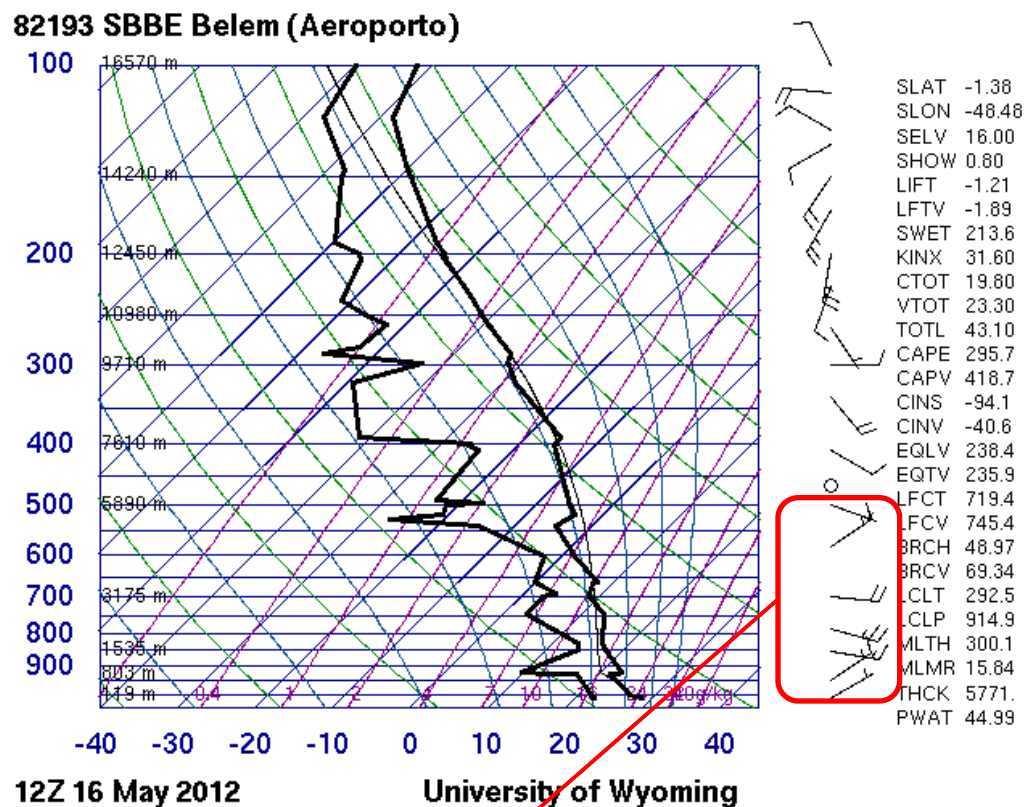
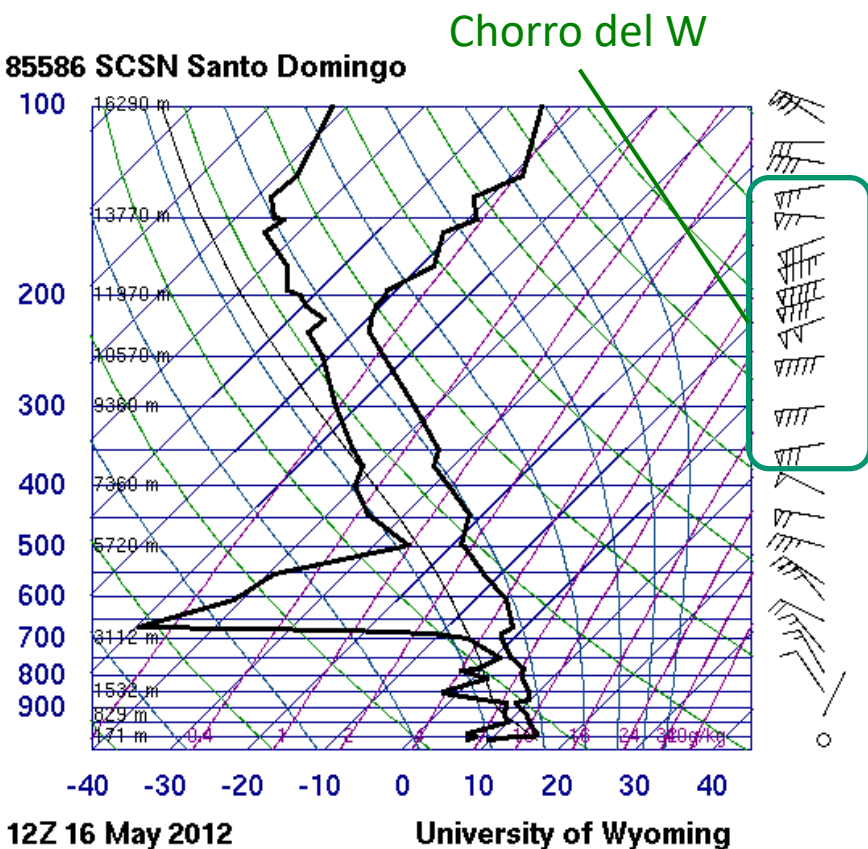
Líneas de corriente



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Radiosondas miden viento en altura



Viento débil del E

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Apuntes de H. E. de Swart

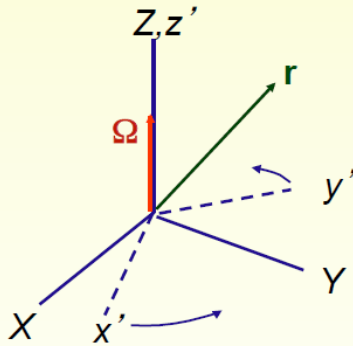
Momentum balance; absolute frame

Newton's second law in an absolute frame

$$\frac{D_a \mathbf{u}_a}{Dt} = \sum_i \mathbf{F}_i$$

$\mathbf{F}_i$: forces (per mass unit)

Operator D_a/Dt is total time derivative in absolute frame;
 $\mathbf{u}_a$ is velocity in absolute frame



Ω : rotation vector
 X, Y, Z : axes in absolute frame
 x', y', z' : axes in rotating frame
 $\mathbf{r}$: position vector

By definition:

$$\mathbf{u}_a = \frac{D_a \mathbf{r}}{Dt}$$

$$\mathbf{u} = \frac{D\mathbf{r}}{Dt}$$

$$\mathbf{u}_a = \mathbf{u} + \Omega \times \mathbf{r}$$

$\Rightarrow$

$$\frac{D_a \mathbf{r}}{Dt} = \frac{D\mathbf{r}}{Dt} + \Omega \times \mathbf{r}$$

Note: in the boxed relation $\mathbf{r}$ can be replaced by any vector, in particular by $\mathbf{u}_a \Rightarrow$

$$\begin{aligned} \frac{D_a \mathbf{u}_a}{Dt} &= \frac{D\mathbf{u}_a}{Dt} + \Omega \times \mathbf{u}_a \\ &= \frac{D}{Dt} (\mathbf{u} + \Omega \times \mathbf{r}) + \Omega \times (\mathbf{u} + \Omega \times \mathbf{r}) \\ &= \frac{D\mathbf{u}}{Dt} + \Omega \times \mathbf{u} + \Omega \times (\mathbf{u} + \Omega \times \mathbf{r}) \end{aligned}$$

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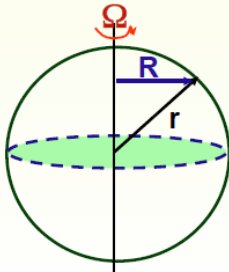
The momentum balance in a rotating frame

$$\frac{D\mathbf{u}}{Dt} + 2\boldsymbol{\Omega} \times \mathbf{u} + \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \mathbf{r}) = \sum_i \mathbf{F}_i$$

Here, two apparent forces emerge:

$$-2\boldsymbol{\Omega} \times \mathbf{u} \quad \text{Coriolis force/mass}$$

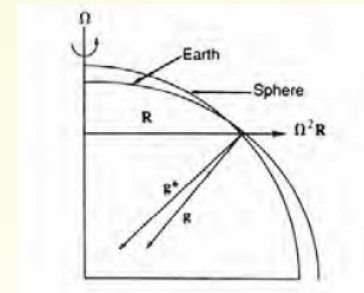
$$-\boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \mathbf{r}) = \Omega^2 \mathbf{R} \quad \text{centrifugal force/mass}$$



$|\mathbf{R}|$: distance to rotation axis

Manifestation of centrifugal force $\mathbf{F}_{ce}$

If earth would be a sphere, then $\mathbf{F}_{ce}$ would have a component along the earth's surface



However, $\mathbf{F}_{ce}$ causes shape of the earth to adjust from sphere $\rightarrow$ spheroid, such that **gravity**

$$\mathbf{g} = \mathbf{g}_s + \Omega^2 \mathbf{R}$$

is perpendicular to the surface of the earth.

Thus, momentum equations on a rotating earth become

$$\frac{D\mathbf{u}}{Dt} + 2\boldsymbol{\Omega} \times \mathbf{u} = \mathbf{g} + \mathbf{F}_p + \mathbf{F}_{\text{tide}} + \mathbf{F}_{\text{fric}}$$

with

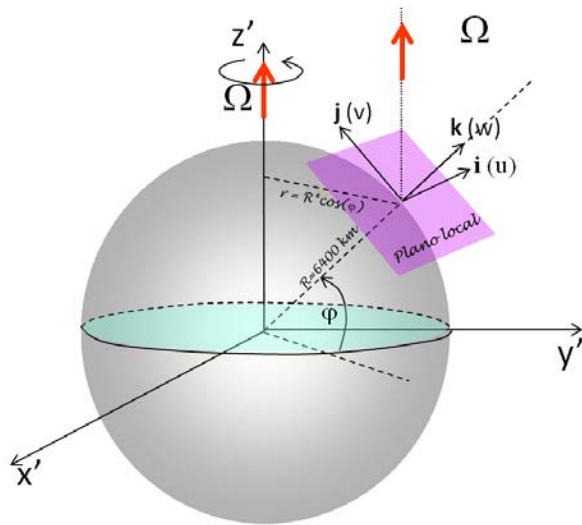
$\mathbf{F}_p$: pressure force/mass

$\mathbf{F}_{\text{tide}}$: tidal force/mass

$\mathbf{F}_{\text{fric}}$: frictional force/mass

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Apuntes de H. E. de Swart



Thus, in this coordinate system, the Coriolis force

$$-2\Omega \times \mathbf{u} = \begin{vmatrix} \mathbf{e}_x & \mathbf{e}_y & \mathbf{e}_z \\ 0 & -2\Omega \cos \phi & -2\Omega \sin \phi \\ u & v & w \end{vmatrix}$$

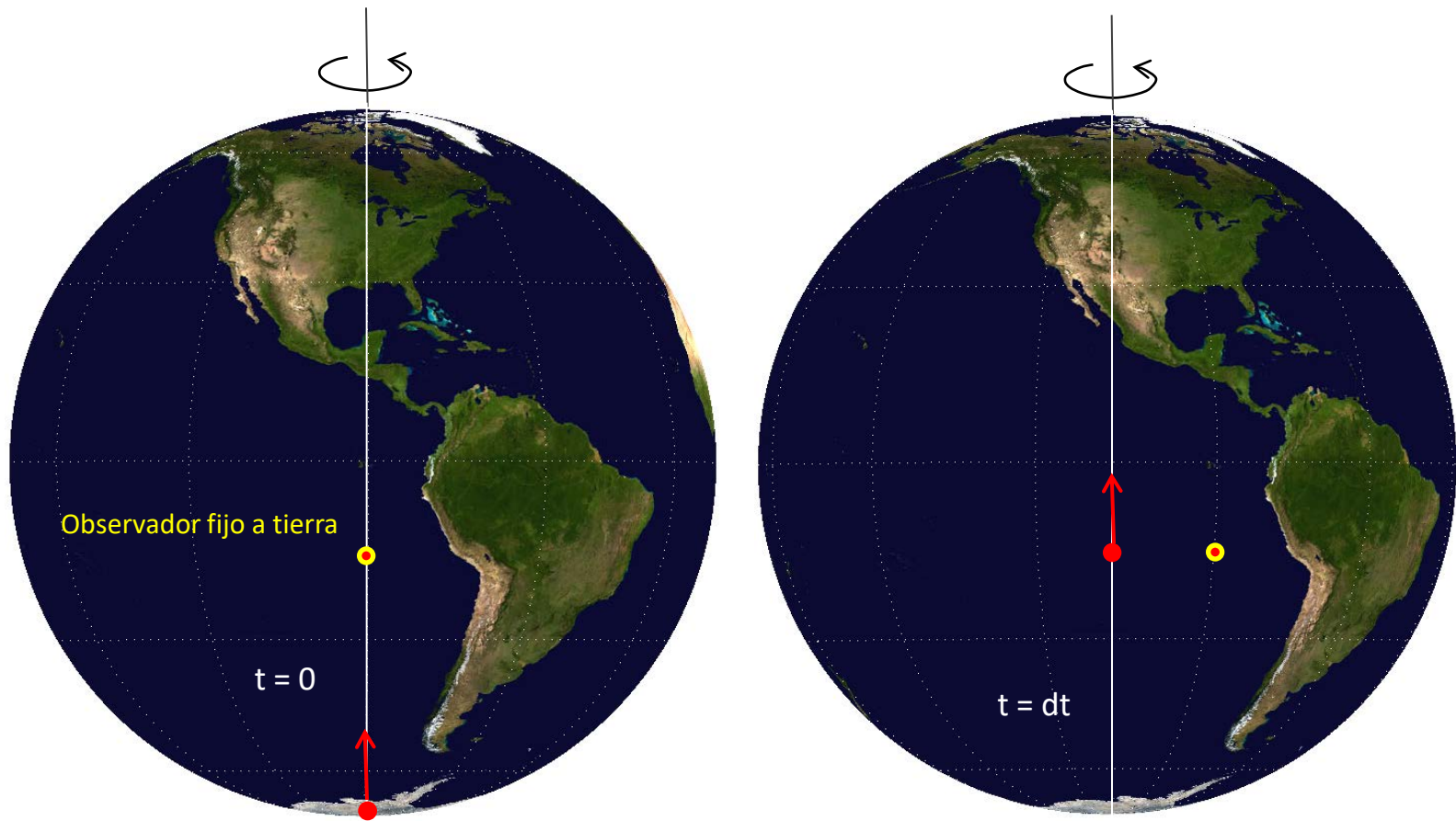
Coriolis parameter f
(2x vertical component of Ω)

$$= \mathbf{e}_x(-2\Omega \cos \phi w - 2\Omega \sin \phi v) - \mathbf{e}_y 2\Omega \sin \phi u + \mathbf{e}_z 2\Omega \cos \phi u$$

$$\mathbf{F}_{\text{co}} = \mathbf{e}_x(-2\Omega \cos \phi w + 2\Omega \sin \phi v) - \mathbf{e}_y 2\Omega \sin \phi u + \mathbf{e}_z 2\Omega \cos \phi u$$

Parametro de Coriolis: $f = 2\Omega \sin(\phi)$

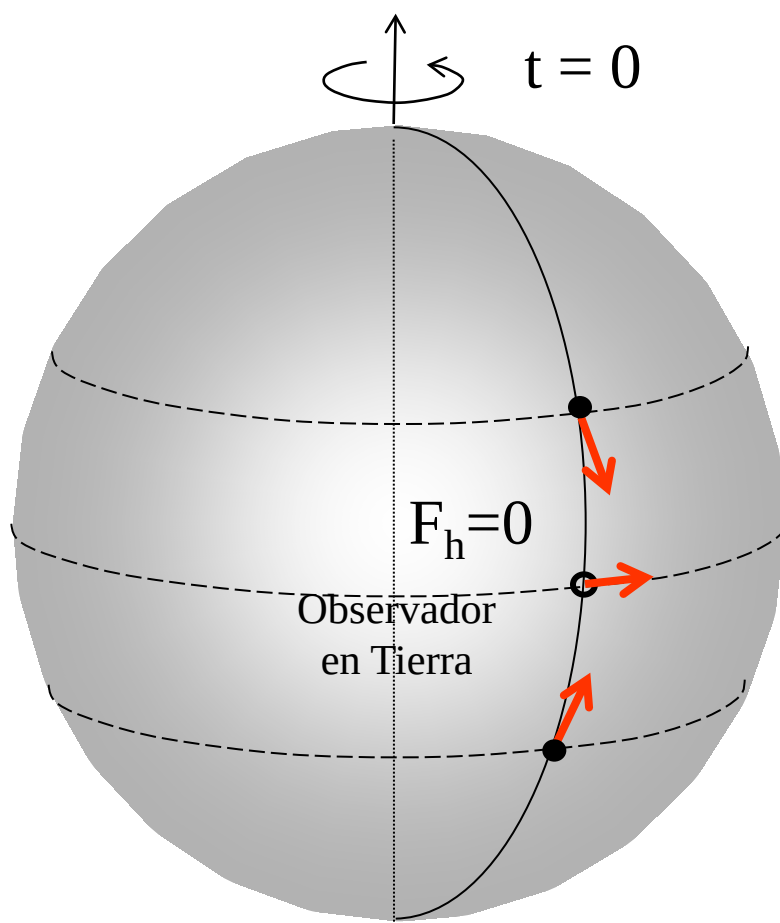
Efecto de Coriolis



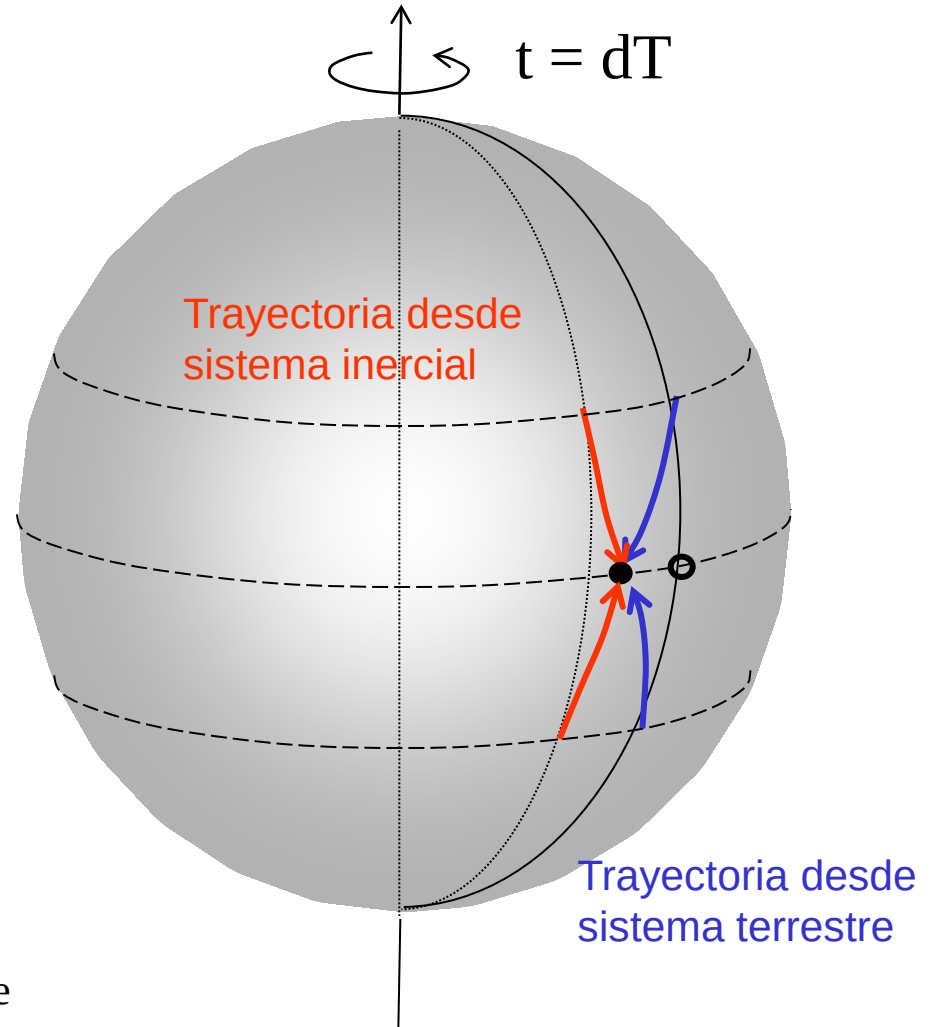
- * Partícula es lanzada directamente desde el PS al ecuador.
- * Despreciando la fuerza de roce, partícula mantiene un MRU.
- * Observador fijo a tierra describe una “misteriosa” desviación hacia la izquierda

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- Partículas flotando sobre superficie parten impulsivamente al ecuador....



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Cuando observamos un movimiento desde un sistema de referencia que acelera (por ejemplo en rotación), se deja de cumplir la segunda ley de Newton ($F=ma$). Podemos “bajarnos” del sistema móvil, o introducir fuerzas aparentes, de manera de seguir cumpliendo $F=ma$

En meteorología, decidimos mantener nuestra descripción del viento desde el planeta (sistema móvil), por lo cual debemos agregar la Fuerza de Coriolis a nuestro análisis de movimiento.

Propiedades de la Fuerza de Coriolis

- Actúa sobre cuerpos no fijos a la tierra
- Siempre deflece el movimiento hacia la izquierda (derecha) en el hemisferio sur (norte)
- Su magnitud es cero en el ecuador y máxima en los polos
- Su magnitud es dependiente de la velocidad de rotación de la tierra (o el planeta en cuestión). $F_C=0$ para rotación nula.

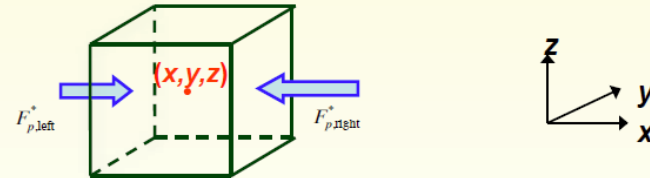
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Apuntes de H. E. de Swart

Pressure gradient force

Note: pressure itself is a force per surface area. It are the spatial variations in pressure that result in a force/mass.

Derivation (fixed control volume):



Pressure force 'right' :

$$F_{p,right}^* = -p|_{(x+\frac{1}{2}\Delta x, y, z)} \Delta y \Delta z \approx -\left(p|_{(x,y,z)} + \frac{\partial p}{\partial x}|_{(x,y,z)} \frac{1}{2}\Delta x\right) \Delta y \Delta z$$

Pressure force 'left' :

$$F_{p,left}^* = p|_{(x-\frac{1}{2}\Delta x, y, z)} \Delta y \Delta z \approx \left(p|_{(x,y,z)} - \frac{\partial p}{\partial x}|_{(x,y,z)} \frac{1}{2}\Delta x\right) \Delta y \Delta z$$

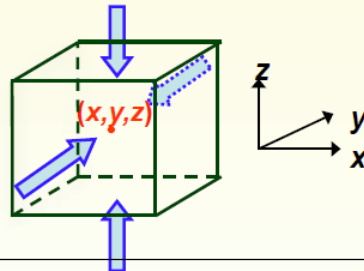
Total force/mass in x-direction:

$$F_{p,x} = \frac{F_{p,left}^* + F_{p,right}^*}{\rho \Delta x \Delta y \Delta z} = -\frac{1}{\rho} \frac{\partial p}{\partial x}$$

Likewise, total force/mass in y- and z-direction:

$$F_{p,y} = \frac{F_{p,front}^* + F_{p,back}^*}{\rho \Delta x \Delta y \Delta z} = -\frac{1}{\rho} \frac{\partial p}{\partial y}$$

$$F_{p,z} = \frac{F_{p,down}^* + F_{p,up}^*}{\rho \Delta x \Delta y \Delta z} = -\frac{1}{\rho} \frac{\partial p}{\partial z}$$



Final result in vector notation:

$$\mathbf{F}_p = -\frac{1}{\rho} \nabla p \quad \text{directed from high} \rightarrow \text{low pressure}$$

Thus, momentum equations on a rotating earth become

$$\frac{D\mathbf{u}}{Dt} + 2\boldsymbol{\Omega} \times \mathbf{u} = \mathbf{g} + \mathbf{F}_p + \mathbf{F}_{\text{tide}} + \mathbf{F}_{\text{fric}}$$

with

$\mathbf{F}_p$: pressure force/mass

$\mathbf{F}_{\text{tide}}$: tidal force/mass

$\mathbf{F}_{\text{fric}}$: frictional force/mass

momentum equations in components:

$$\begin{aligned} \frac{Du}{Dt} - \frac{uv \tan \phi}{r} + \frac{uw}{r} - 2\Omega \sin \phi v + 2\Omega \cos \phi w &= -\frac{1}{\rho} \frac{\partial p}{\partial x} - \frac{\partial \Phi_t}{\partial x} + F_x \\ \frac{Dv}{Dt} + \frac{u^2 \tan \phi}{r} + \frac{vw}{r} + 2\Omega \sin \phi u &= -\frac{1}{\rho} \frac{\partial p}{\partial y} - \frac{\partial \Phi_t}{\partial y} + F_y \\ \frac{Dw}{Dt} - \frac{u^2 + v^2}{r} - 2\Omega \cos \phi u &= -\frac{1}{\rho} \frac{\partial p}{\partial z} - g - \frac{\partial \Phi_t}{\partial z} + F_z \end{aligned}$$

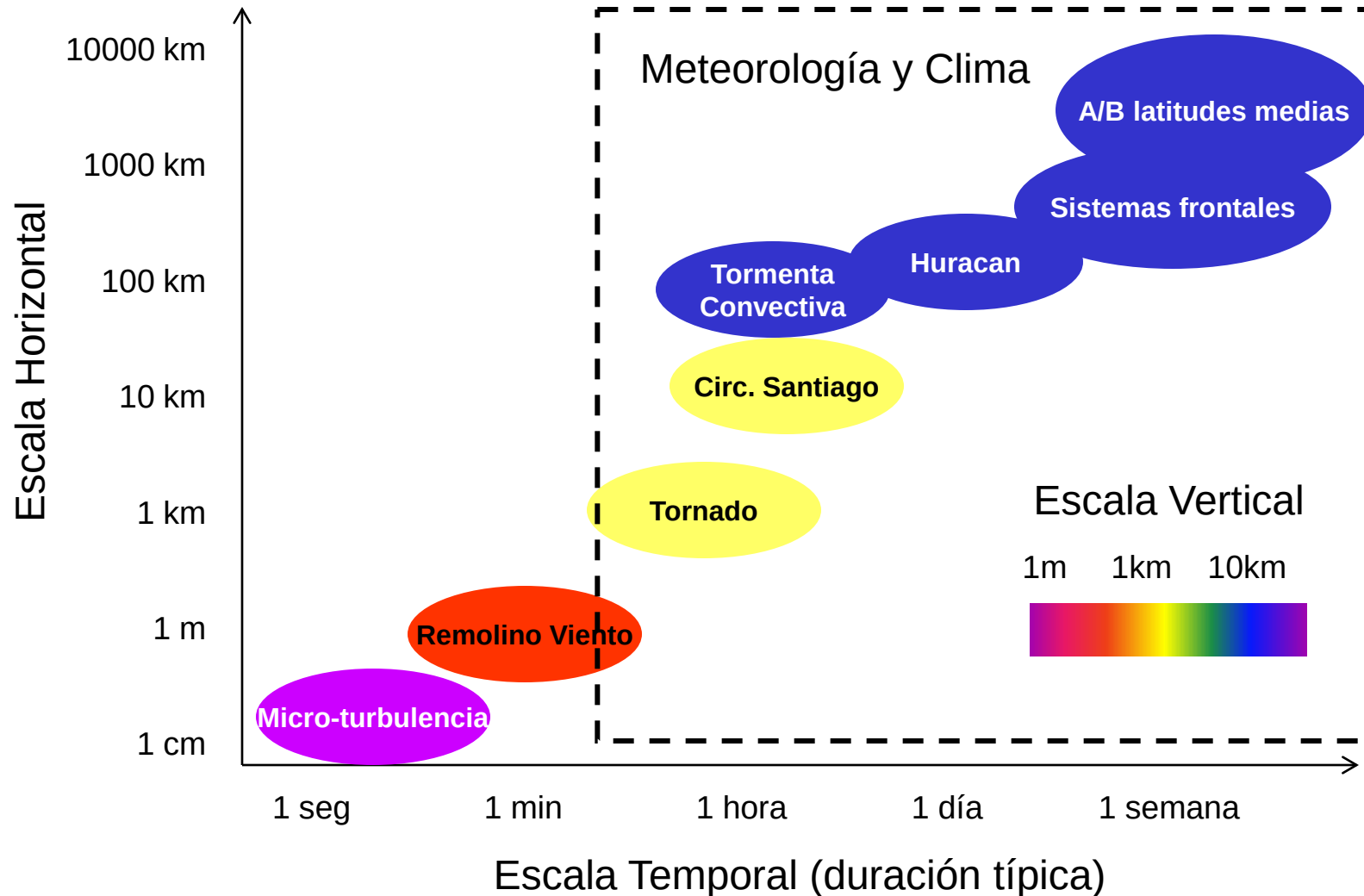
metric

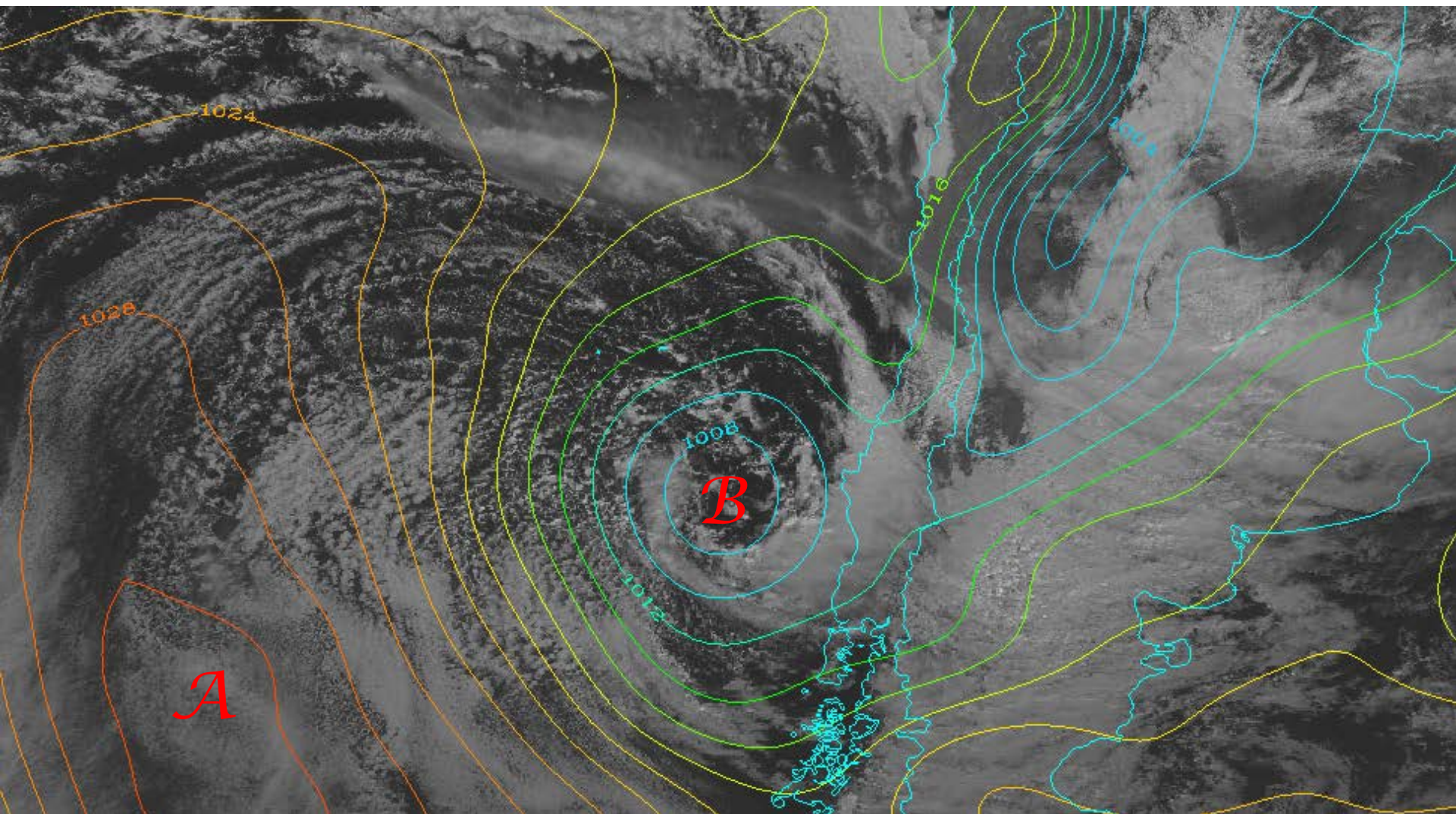
Coriolis

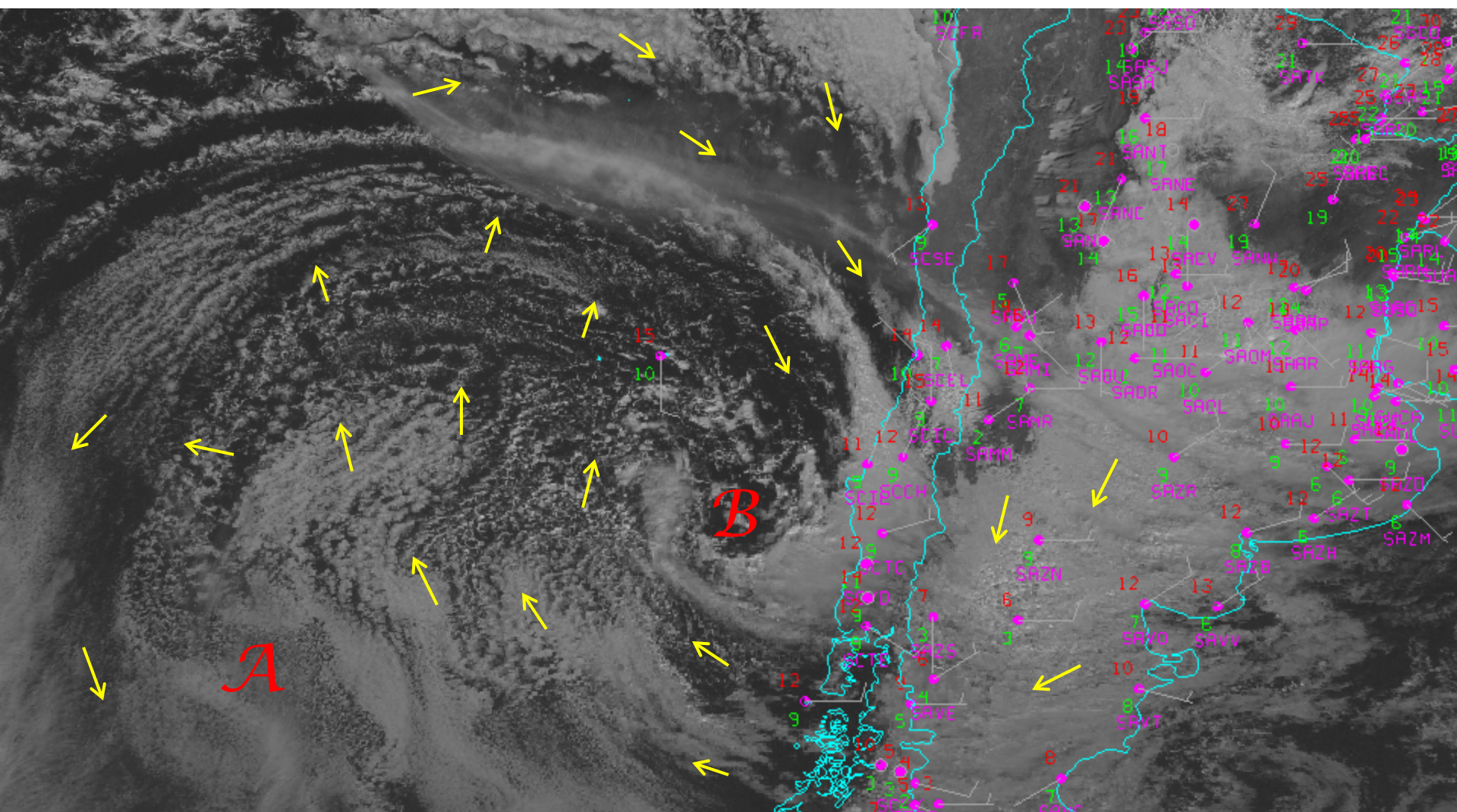
pressure
gradient

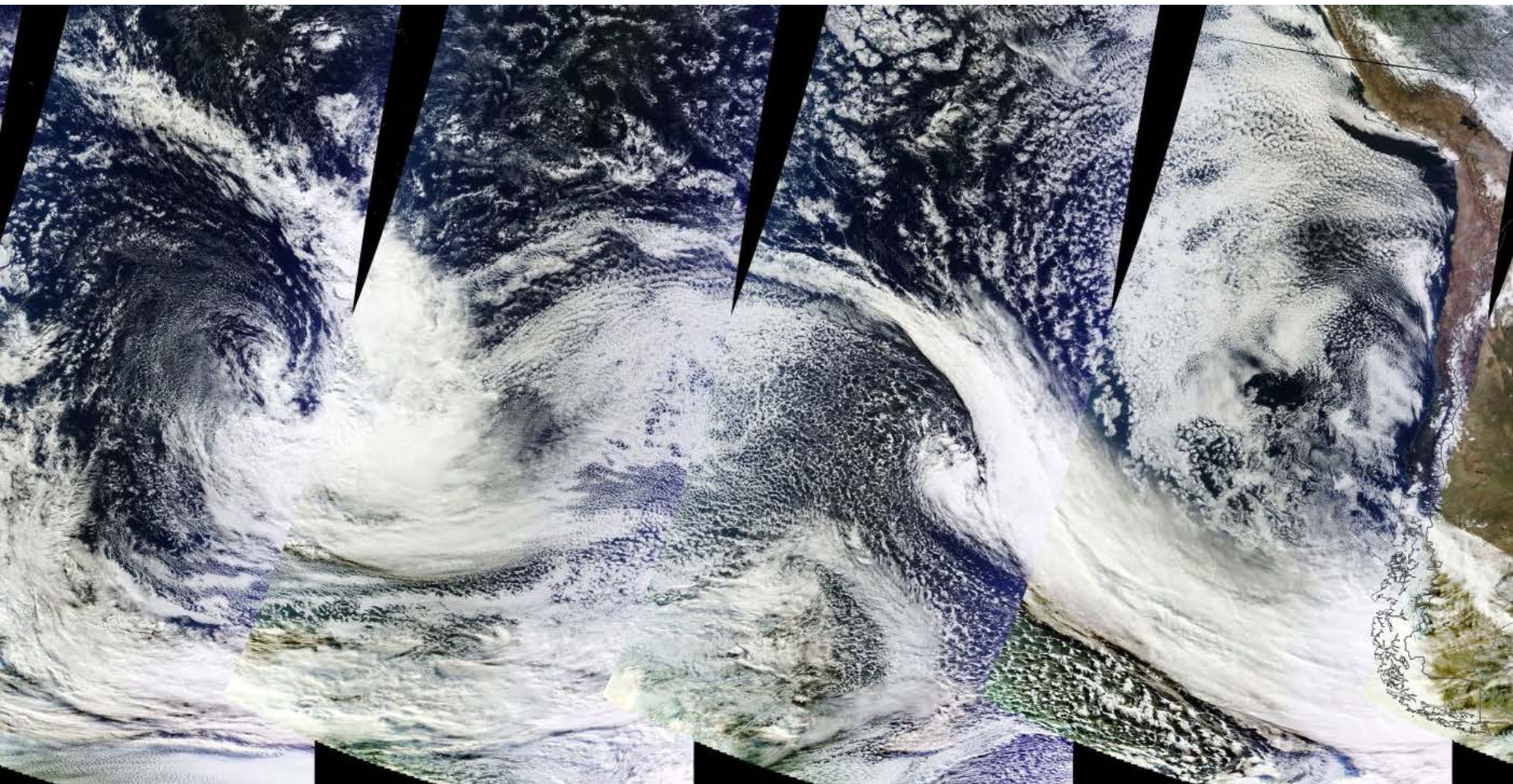
gravity tide friction

Escala temporal-espacial de fenómenos atmosféricos



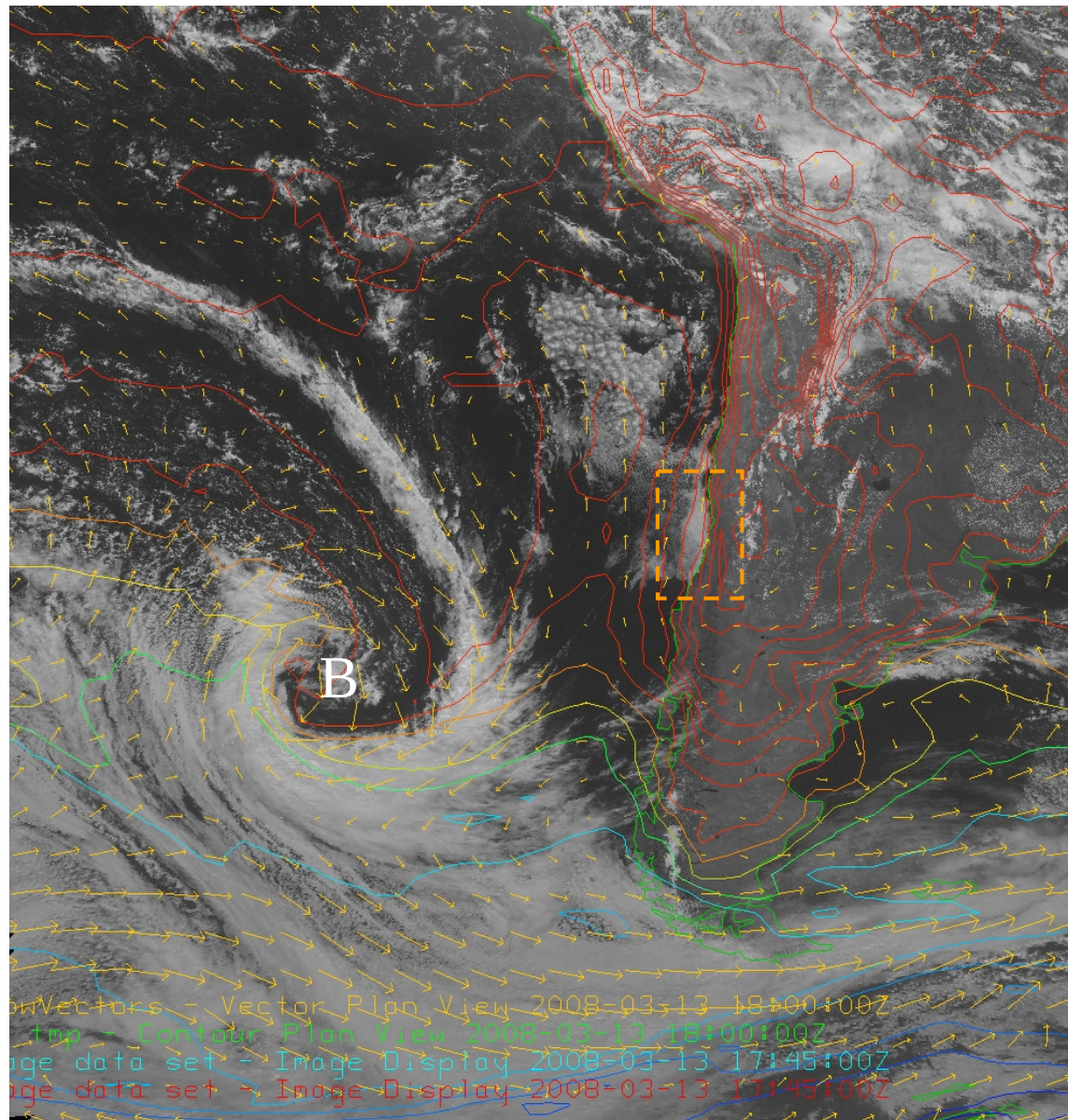






Depresión extratropical / Frente frío

Imagen visible (GOES) + viento 850 hPa



Análisis de Escala de Sistemas de Latitudes Medias

$$\begin{aligned}
 U &= 10 \text{ m s}^{-1}; \quad W = 10^{-2} \text{ m s}^{-1}; \\
 L &= 10^6 \text{ m (10}^3 \text{ km)}; \quad H = 10^4 \text{ m (10 km)}; \\
 T &= L/U \sim 10^5 \text{ (1 day)}; \quad \delta P = 10^3 \text{ Pa (10 mb)} \\
 \text{and} \quad \rho^* &= 1 \text{ kg m}^{-3}.
 \end{aligned}$$

(a) horizontal momentum equations

$$\begin{aligned}
 \frac{Du}{Dt} - 2\Omega v \sin \phi + 2\Omega w \cos \phi &= -\frac{1}{\rho} \frac{\partial p}{\partial x} \\
 \frac{Dv}{Dt} + 2\Omega u \sin \phi &= -\frac{1}{\rho} \frac{\partial p}{\partial y}
 \end{aligned}$$

scales	U^2/T	$2\Omega U \sin \phi$	$2\Omega W \cos \phi$	$\delta P/(\rho L)$
orders	10^{-4}	10^{-3}	10^{-6}	10^{-3}

(b) vertical momentum equation (total pressure form)

$$\frac{Dw}{Dt} - 2\Omega u \cos \phi = -\frac{1}{\rho} \frac{\partial p_T}{\partial z} - g$$

scales	UW/L	$2\Omega u \cos \phi$	$\delta P_0/(\rho H)$	g
orders	10^{-7}	10^{-3}	10	10

$$\frac{D\mathbf{u}_h}{Dt} + f\mathbf{k} \wedge \mathbf{u}_h = -\frac{1}{\rho} \nabla_h p$$

$$0 = -\frac{1}{\rho} \frac{\partial p}{\partial z} + \sigma,$$

THE ROSSBY NUMBER

- Dividing the horizontal momentum equation, (6), through by fV we get

$$\frac{1}{fV} \frac{D\vec{V}}{Dt} = -\frac{1}{\rho fV} \nabla p - \hat{k} \times \frac{f\vec{V}}{fV}.$$

- Using the representative scales the order of magnitude of these terms are

$$\frac{U}{fL} = \frac{\delta P}{\rho fU} + 1.$$

- The dimensionless combination U/fL is defined as the *Rossby number* (named for Gustav Rossby),

$$Ro \equiv U/fL \quad (7)$$

GEOSTROPHIC BALANCE (VERY SMALL ROSSBY NUMBER)

- When the Rossby number is much less than unity ($Ro \ll 1$), then the acceleration (inertial) term can be ignored and the only two terms left are the pressure gradient term and the Coriolis term, which must be nearly in balance.
 - This is known as *geostrophic balance*, and the velocity in this case is known as the *geostrophic wind*.
 - The momentum equation in this case reduces to

$$\hat{k} \times f\vec{V}_g = -\frac{1}{\rho} \nabla p$$

which is solved for the geostrophic wind to yield

$$\vec{V}_g = \frac{1}{f\rho} \hat{k} \times \nabla p,$$

CYCLOSTROPHIC BALANCE (VERY LARGE ROSSBY NUMBER)

- When the Rossby number is much greater than unity ($Ro \gg 1$) then the Coriolis term can be ignored. In this instance the only terms that are left are the acceleration and the pressure gradient terms, and so the acceleration is a direct result of the pressure gradient force

$$\frac{D\vec{V}}{Dt} = -\frac{1}{\rho} \nabla p. \quad (10)$$

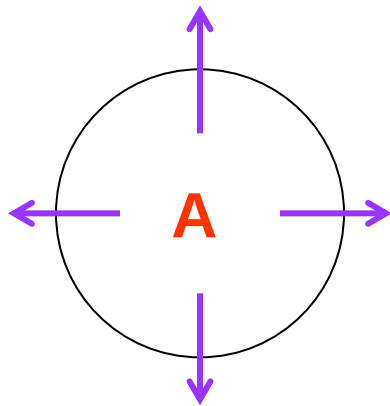
- This type of balance is called *cyclostrophic*.
- In cyclostrophic balance the pressure gradient acceleration is exactly that required for the centripetal acceleration, and so we have

$$\frac{V_c^2}{r} = \frac{|\nabla p|}{\rho}$$

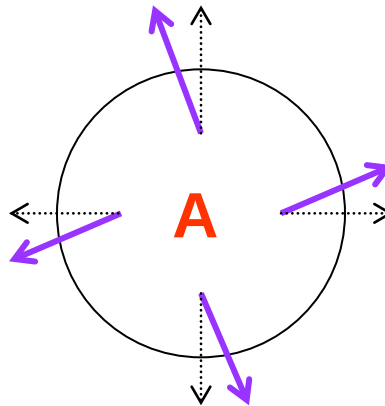
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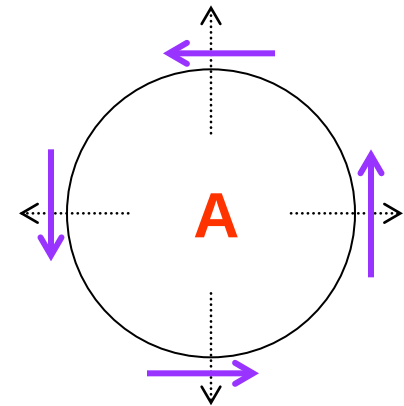
¿Como circula el aire en torno a los centros de alta y baja presión (HS)?



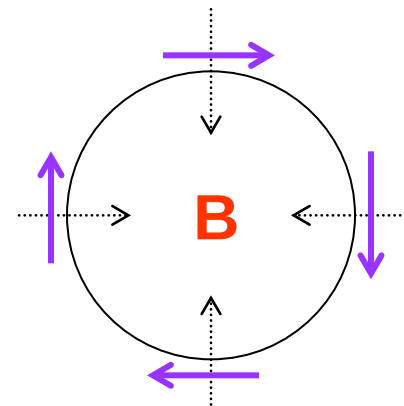
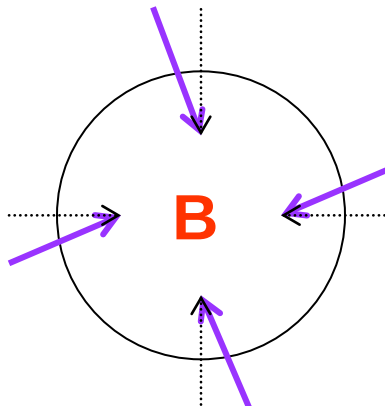
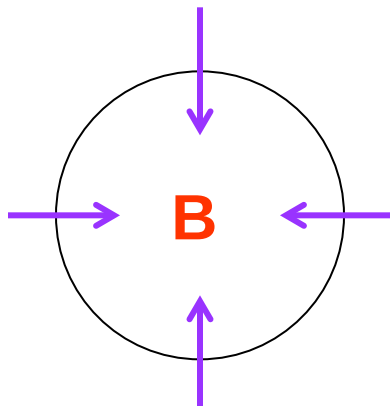
En el ecuador o en planeta sin rotación



Muy cerca del ecuador o rotación planetaria muy lenta



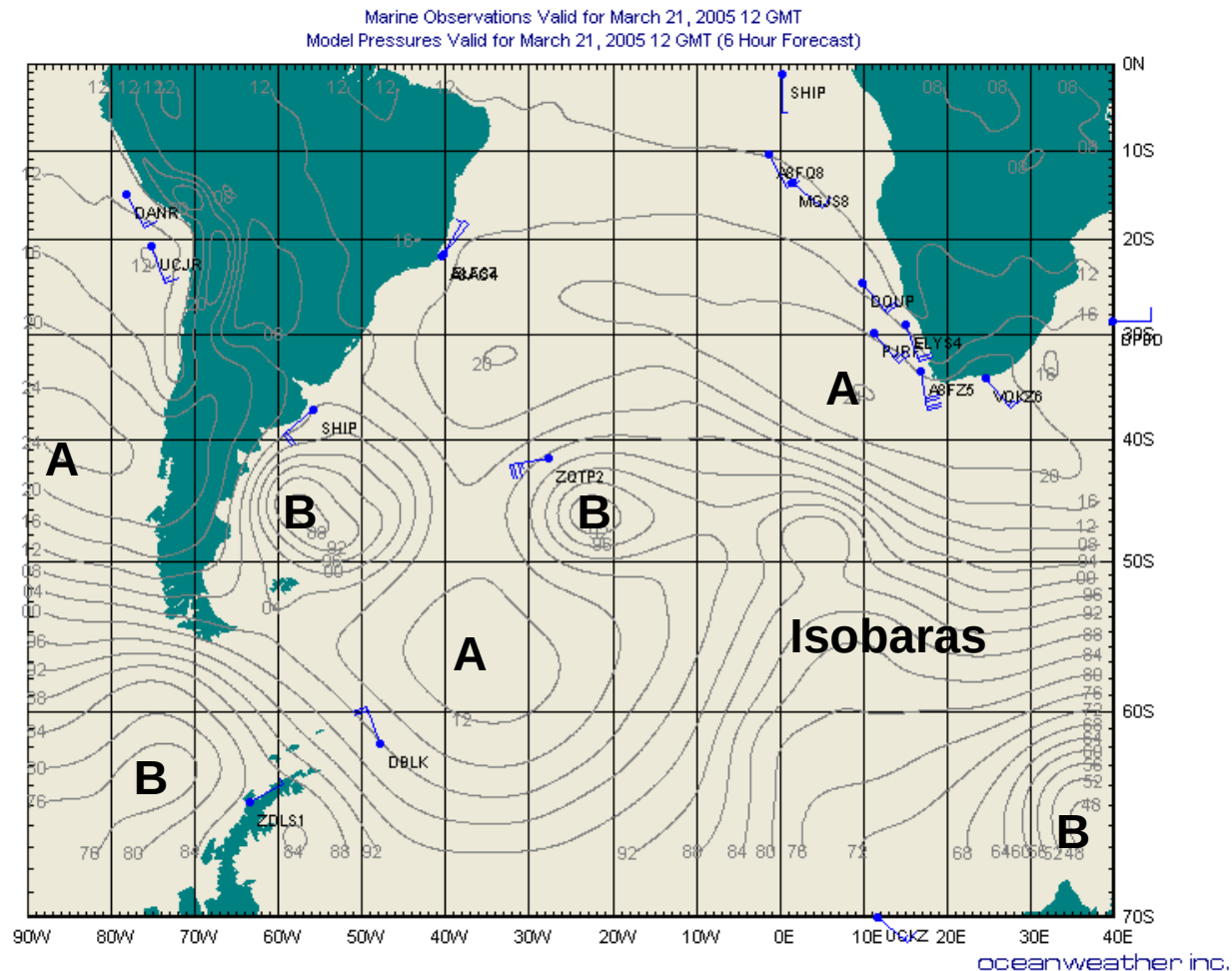
Lejos del ecuador ($>20^\circ$) para movimientos lentos



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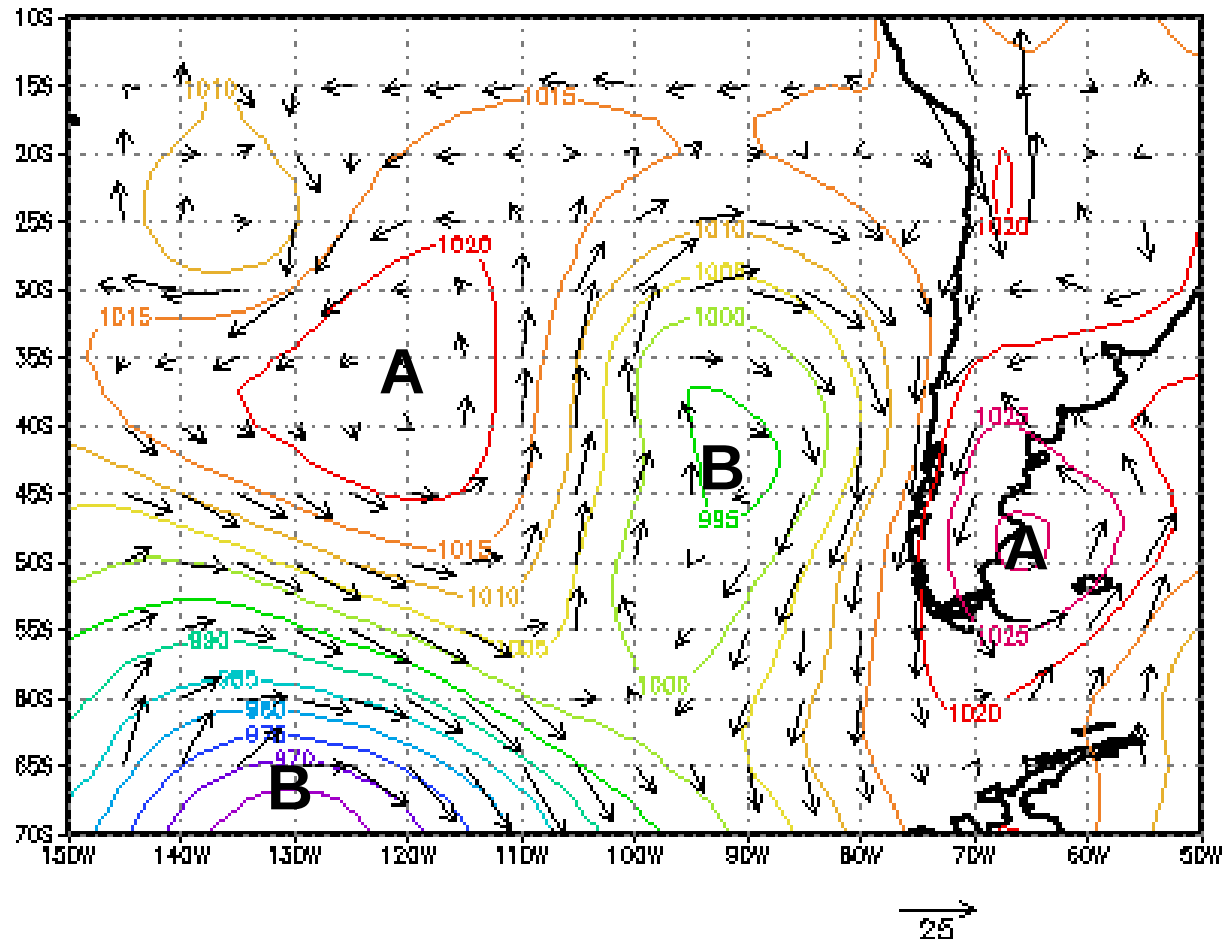
¿Porque nos gustan tanto los mapas del tiempo?



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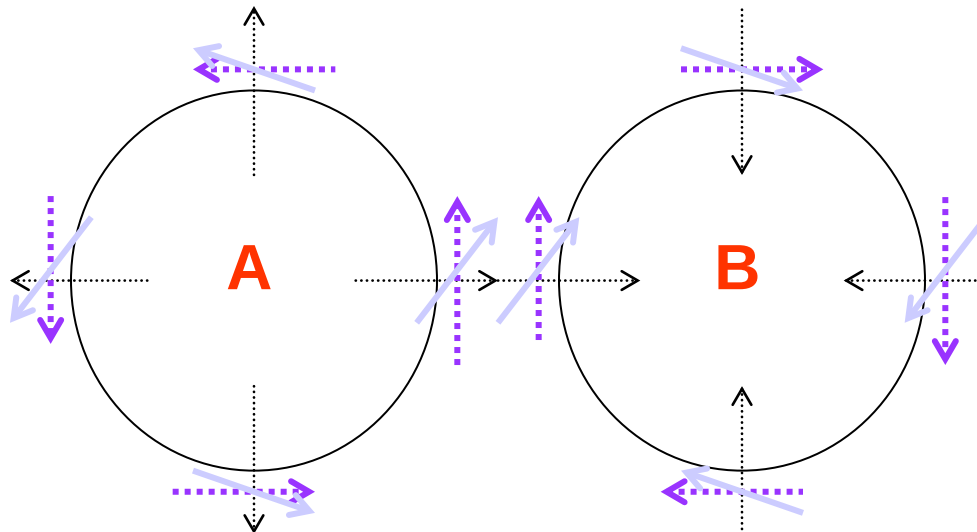
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Contornos: líneas de igual presión
Flechas: vector viento



Efecto de la Fricción

Si queremos agregar mas realismo a nuestro balance de fuerzas que determinan el viento real, debemos considerar el efecto de la fricción que sufre el aire en contacto con el suelo (o cercano a el).



Viento solo debido a gradiente de presión

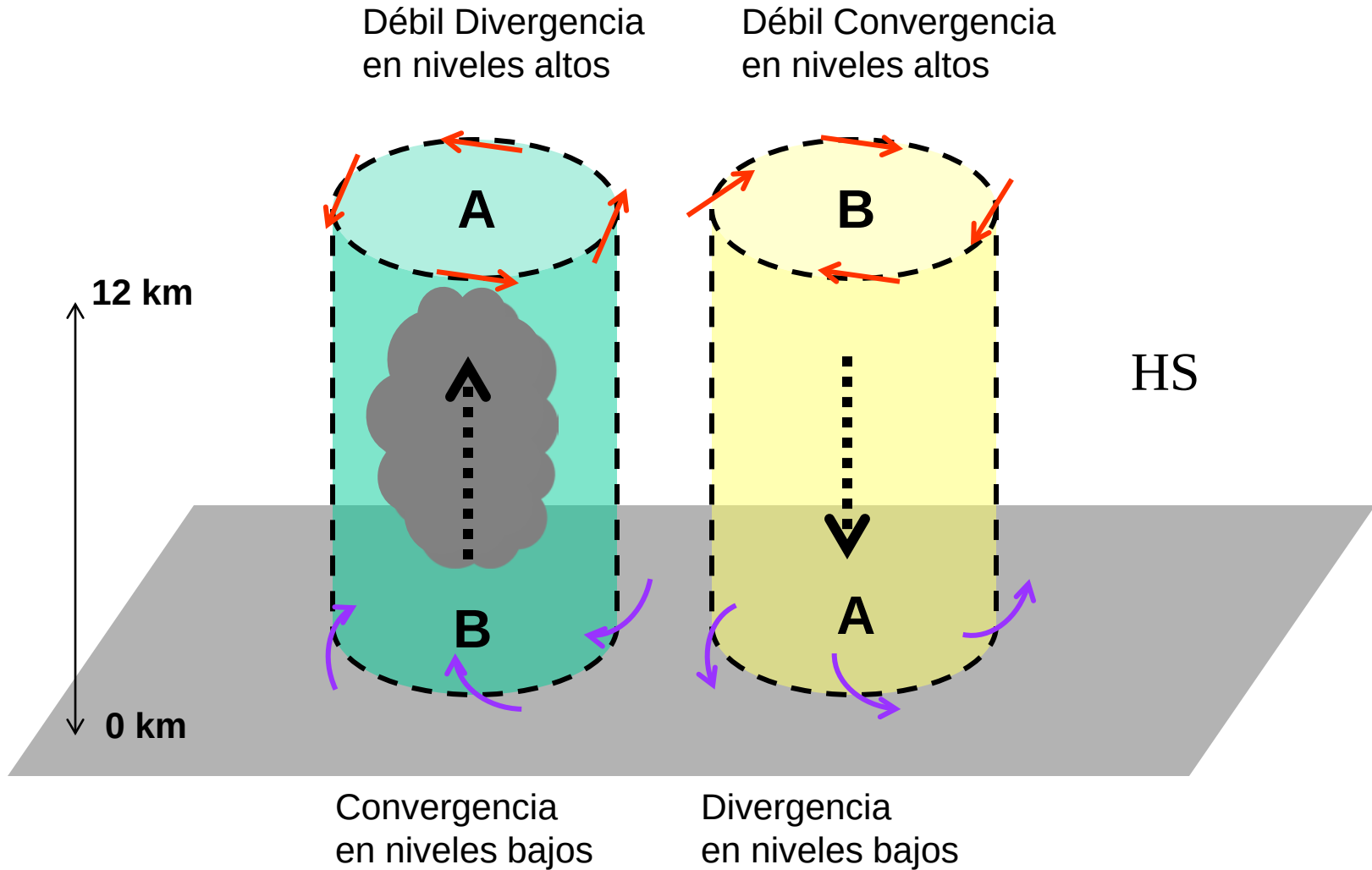
Viento Geostrofico (equilibrio FGP y Fcoriolis)

Viento real (equilibrio FGP y Fcoriolis y Froce)

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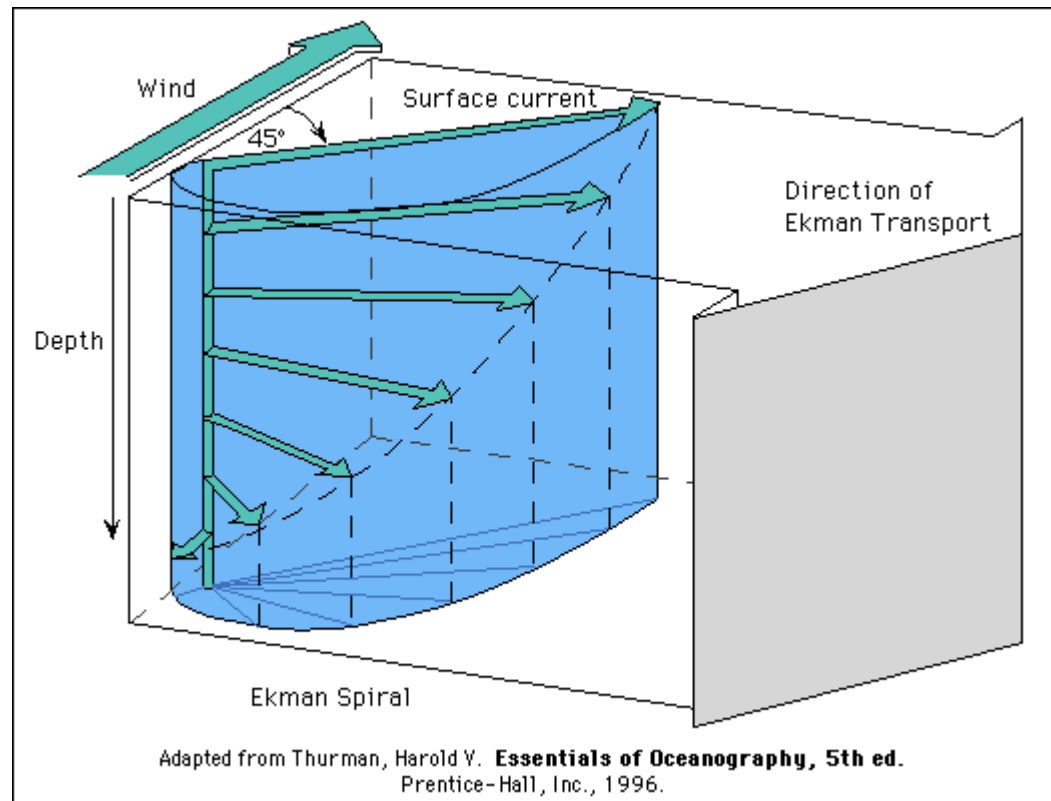
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Efecto de la fricción en torno a centros de A y B presión...



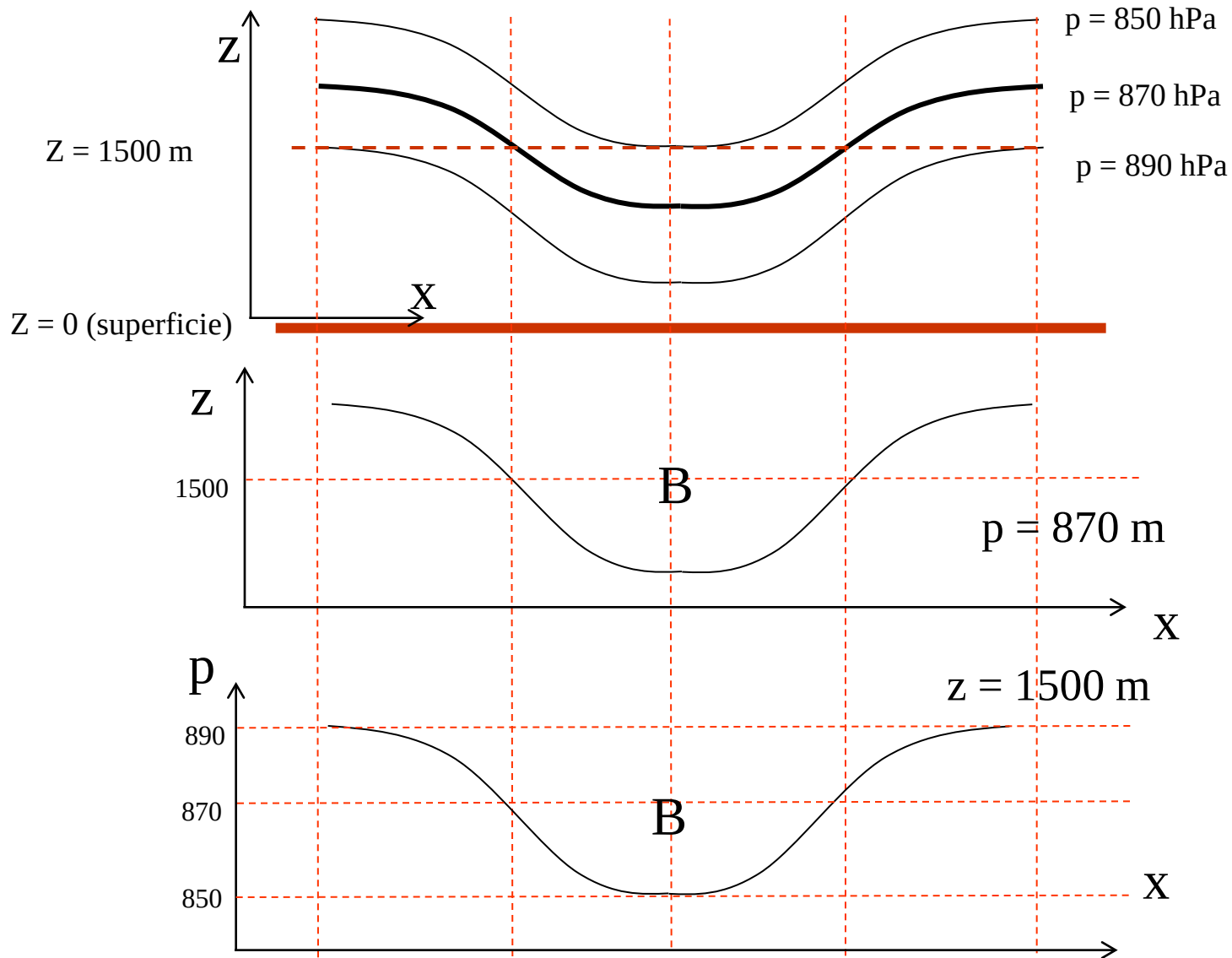
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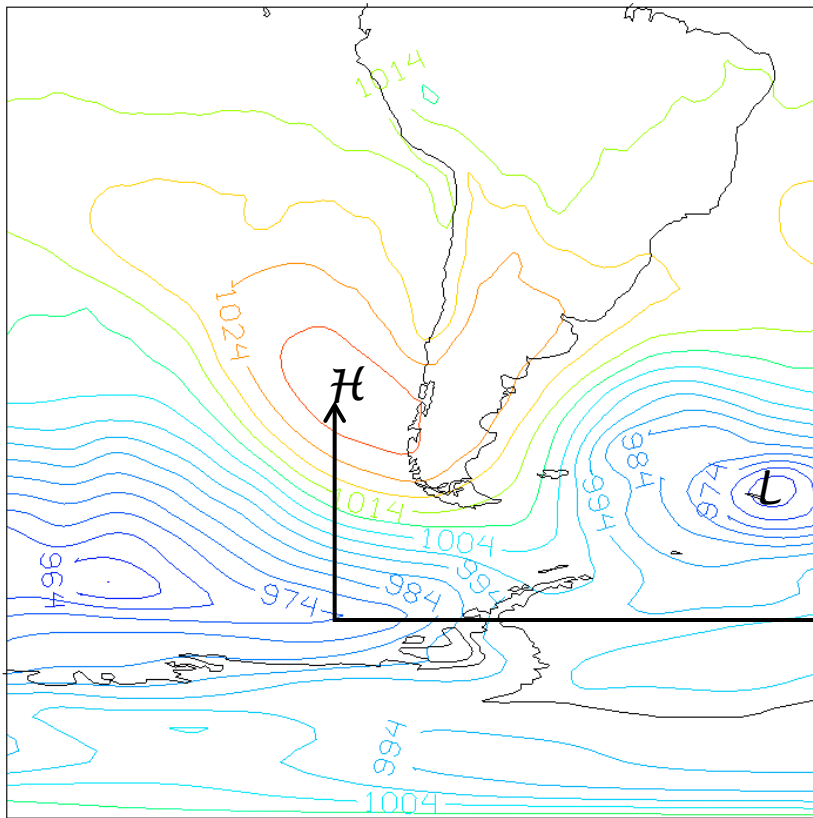
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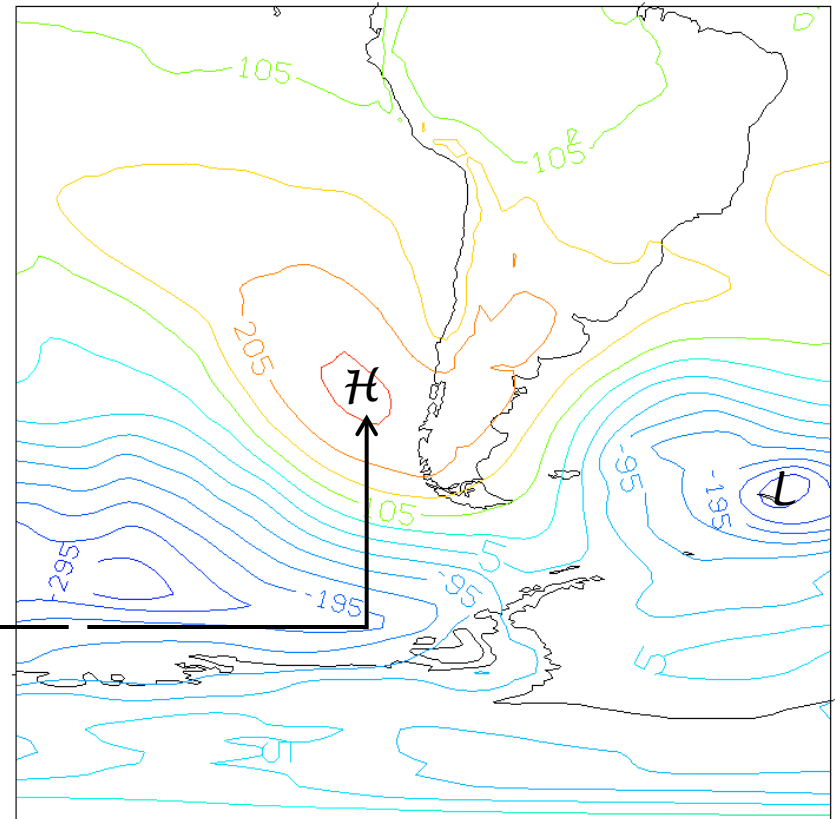
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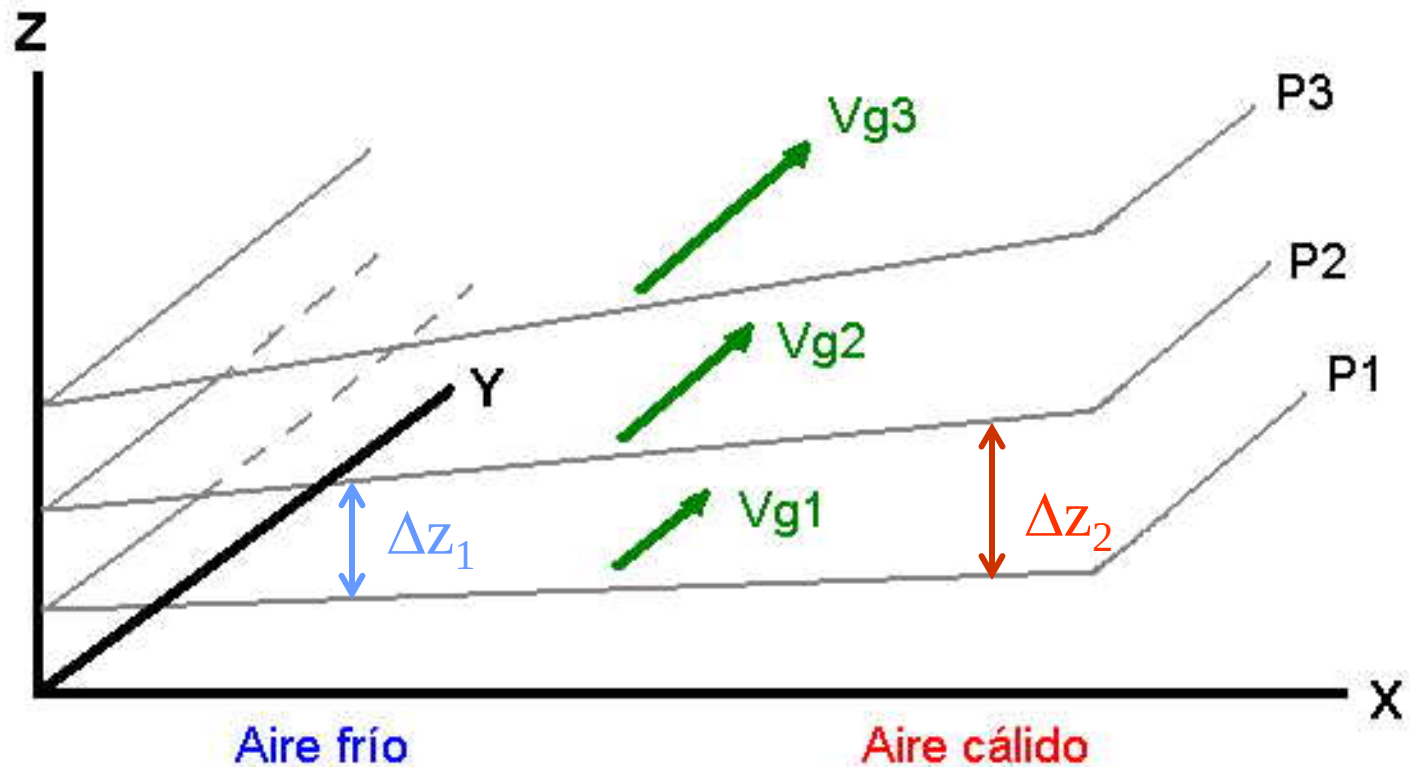
Presión @ $z = 0$ m (PNM)



Altura geopotencial @ $p = 1000$ hPa

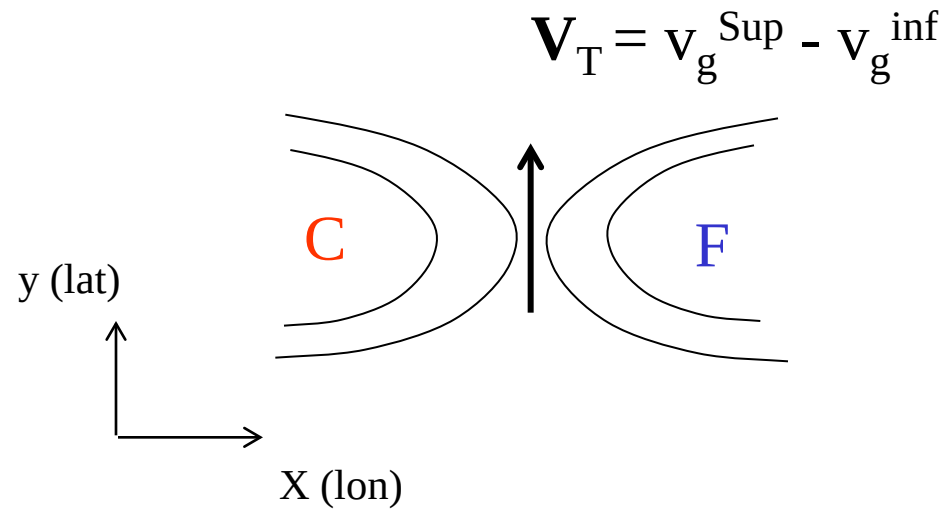
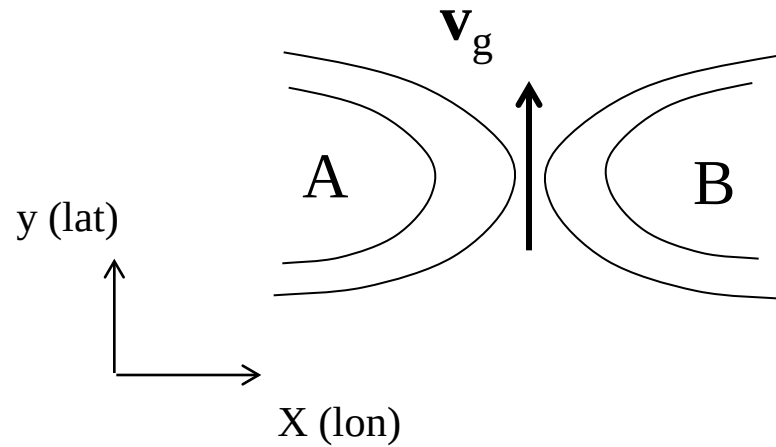


Gradiente de T, Cizalle del Viento y Viento Térmico



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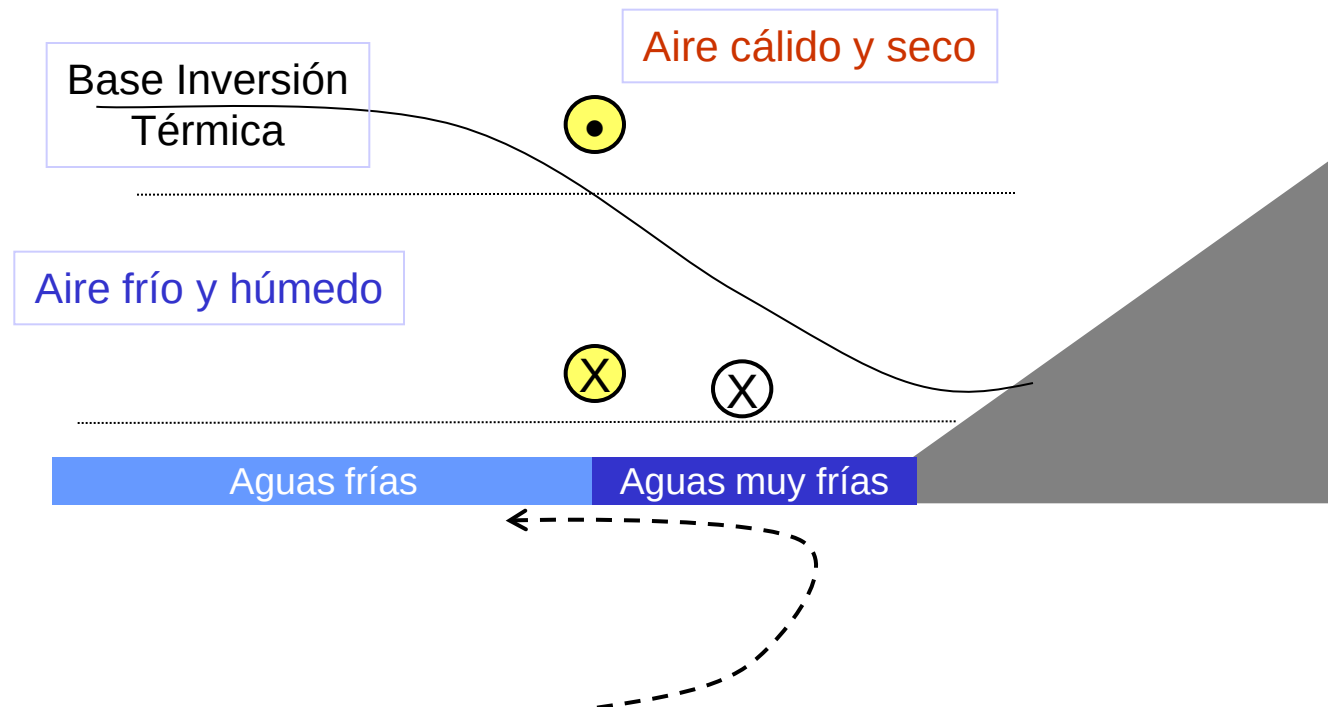


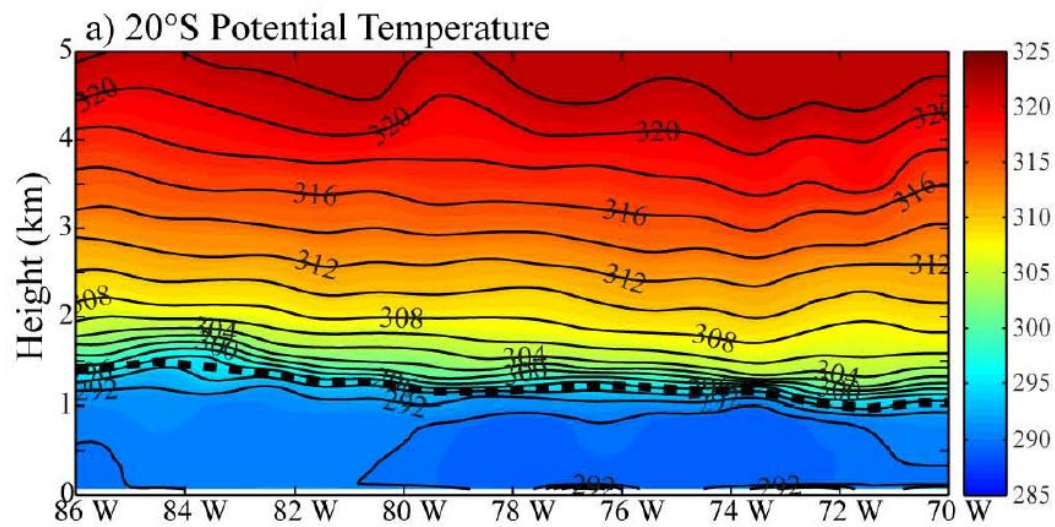
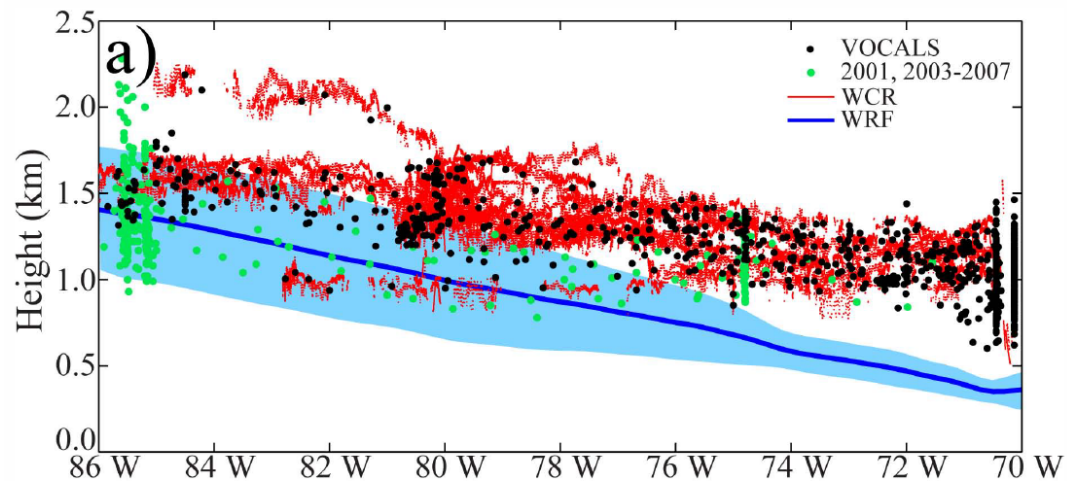
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Aplicación cualitativa de viento térmico.

Dibuje el perfil vertical del viento meridional ($v(z)$) frente a la costa de Chile central. En superficie el viento es del sur. Para ello, considere la dirección del viento térmico a 50 m y 500 m





Misión Tongoy 02

La Serena (SCSE) – Santiago (SCEL) leg
Wind speed; Altitude range: 170-220 m ASL

04-01-2011 15-16 HL

