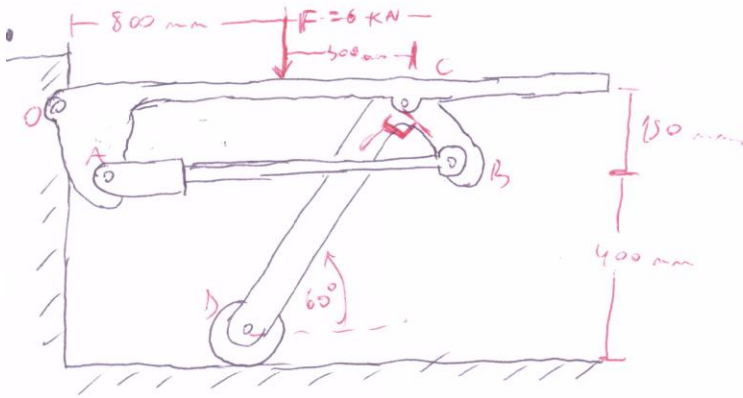


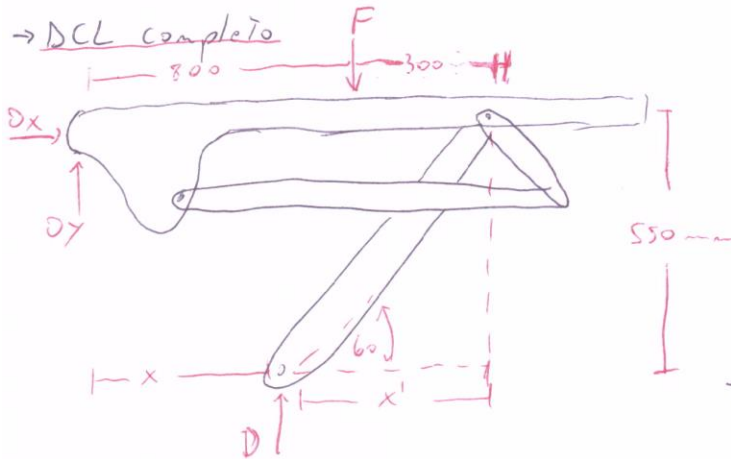


$$L_{AB} = 1000 \text{ mm}$$

$$E = 190 \text{ GPa}$$

$$F.S = 2,5$$

→ DCL completo



$$\sum_0 M_z = 0 \rightarrow x \cdot D - 800 F = 0$$

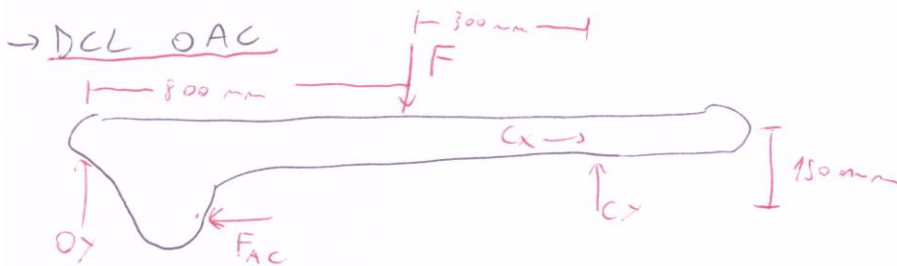
$$\tan 60 = \frac{550}{x'} \Rightarrow x' = \frac{550}{\tan 60} = 317 \text{ mm}$$

$$x = 1100 - x' = 782,46 \text{ mm}$$

$$\Rightarrow D = \frac{800}{x} F = 6,13 \text{ kN}$$

$$\sum F_x = 0 \rightarrow D_x = 0 \quad \wedge \quad \sum F_y = 0 \rightarrow D_y = F - D = -0,13 \text{ kN}$$

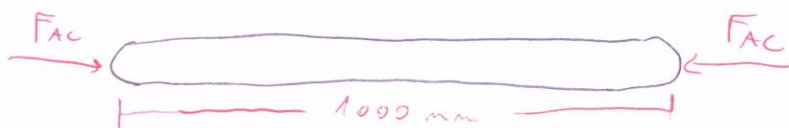
→ DCL OAC



$$\sum_c M_z = 0 \rightarrow -150 F_{Ac} - 1100 D_y + 300 F = 0$$

$$\therefore F_{Ac} = 12,953 \text{ kN}$$

→ DCL FAc



• Análisis de pandeo



$$\rightarrow \hat{y}(x) = C_1 \cdot \sin\left(\sqrt{\frac{P}{EI_z}} x\right) + C_2 \cos\left(\sqrt{\frac{P}{EI_z}} x\right) + C_3 x + C_4$$

$$\rightarrow \frac{d\hat{y}}{dx}(x) = C_1 \lambda \cos(\lambda x) - C_2 \lambda \sin(\lambda x) + C_3$$

$$\rightarrow \frac{d^2\hat{y}}{dx^2}(x) = -C_1 \lambda^2 \sin(\lambda x) - C_2 \lambda^2 \cos(\lambda x)$$

→ C.B.

$$\cdot \frac{d^2\hat{y}}{dx^2}(0) = 0 \Rightarrow C_2 = 0$$

$$\cdot \hat{y}(0) = 0 \Rightarrow C_4 = 0$$

$$\cdot \frac{d^2\hat{y}}{dx^2}(L) = 0 \Rightarrow -C_1 \lambda^2 \sin(\lambda L) = 0 \Rightarrow \boxed{C_1 = 0 \vee \sin(\lambda L)} \quad (*)$$

$$\cdot \hat{y}(L) = 0 \Rightarrow C_1 \sin(\lambda L) + C_3 L = 0$$

→ Si tomamos $C_1 = 0 \leadsto C_3 = 0 \Rightarrow \hat{y}(x) = 0$ (Trivial)

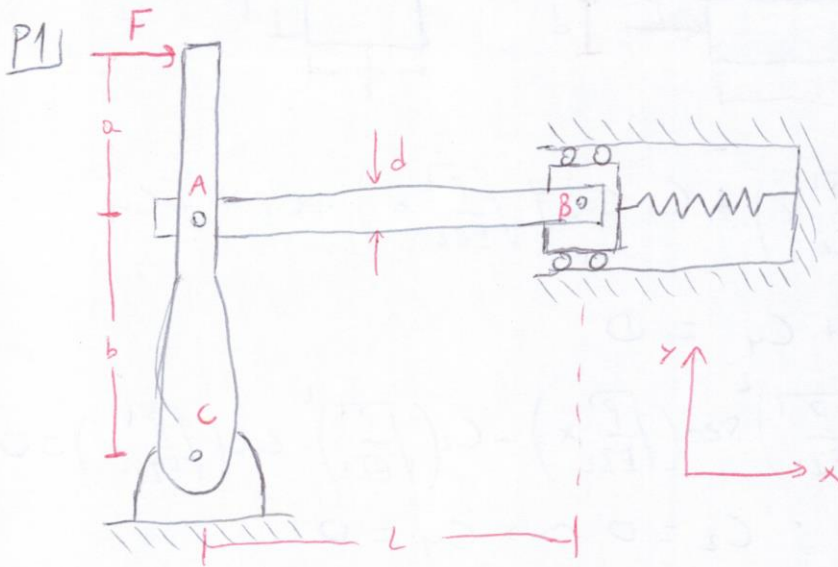
→ Si tomamos $\sin(\lambda L) = 0 \Rightarrow \lambda L = n\pi, \forall n = 1, 2, \dots$

$$\sqrt{\frac{P}{EI_z}} L = n \cdot \pi$$

$$\Rightarrow P_{cr}^{(n)} = \frac{n^2 \pi^2}{L^2} E I_z \equiv \frac{n^2 \pi^2}{L^2} E \frac{\pi d^4}{64} \Rightarrow \boxed{d^{(n)} = 4 \sqrt{\frac{64 L^2 P_{cr}^{(n)}}{\pi E n^2 \pi^2}}}$$

→ Análisis del 1º modo de pandeo: $P_{cr}^{(n)} = P_{cr}^{(1)} = P_{dc} \wedge n = 1$

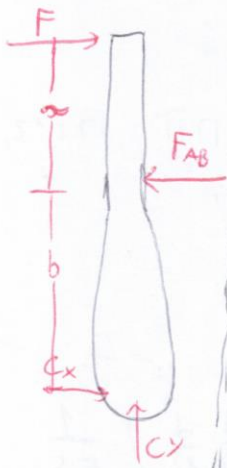
$$\therefore d = \sqrt[4]{\frac{64 L^2 P_{dc}}{\pi^3 E}} = 0,0194 \text{ m}$$



$$\begin{aligned}\sigma_0 &= 350 \text{ MPa} \\ E &= 190 \text{ GPa} \\ L &= 20 \text{ cm} \\ b &= 8 \text{ cm} \\ a &= 10 \text{ cm} \\ d &= 8 \text{ mm} \\ F.S. &= 2\end{aligned}$$

- Existen 3 fuentes de falla:
 - Fallo por plasticidad en compresión
 - Fallo por pandeo en el plano $x-y$
 - Fallo por pandeo en el plano $x-z$

DCL (Para encontrar fuerza de compresión en AB)



$$\sum_c M_z = 0 \Rightarrow b \cdot F_{AB} + (a+b) \cdot F = 0$$

$$\therefore F_{AB} = \frac{(a+b)}{b} F$$

> Fallo por plasticidad: Encontramos σ_x

$\hookrightarrow \sigma_x = \frac{F_{AB}}{A}$, Pero σ_x debe cumplir factor de Seguridad

$$\Rightarrow \sigma_x = \frac{\sigma_0}{F.S.} \Rightarrow \frac{(a+b)}{b} \cdot \frac{4F}{\pi \cdot \frac{d^2}{4}} = \frac{\sigma_0}{F.S.}$$

$$\therefore F = \frac{\sigma_0 b \cdot d^2}{3 F.S. (a+b)} = 1659,26 \text{ N}$$

ii) Falla por pandeo en el plano $x-y$



Soln $y(x) = C_1 \cdot \sin\left(\sqrt{\frac{P}{EI_z}} x\right) + C_2 \cos\left(\sqrt{\frac{P}{EI_z}} x\right) + C_3 x + C_4$

C.b) $y(0) = 0 \leadsto C_2 + C_4 = 0$

$\frac{d^2 y}{dx^2}(0) = 0 \leadsto -C_1 \left(\sqrt{\frac{P}{EI_z}}\right)^2 \sin\left(\sqrt{\frac{P}{EI_z}} x\right) - C_2 \left(\sqrt{\frac{P}{EI_z}}\right)^2 \cos\left(\sqrt{\frac{P}{EI_z}} x\right) = 0$

$\therefore C_2 = 0 \leadsto C_4 = 0$

$\frac{dy}{dx}(L) = 0 \leadsto -C_1 \frac{P}{EI_z} \cdot \sin\left(\sqrt{\frac{P}{EI_z}} L\right) = 0 (*)$

$y(L) = 0 \leadsto C_1 \sin\left(\sqrt{\frac{P}{EI_z}} L\right) + C_3 L = 0$

$\hookrightarrow$ De (*) $\Rightarrow C_3 = 0$

* Tomando (*) $\leadsto \sin\left(\sqrt{\frac{P}{EI_z}} L\right) = 0 \leadsto \sqrt{\frac{P}{EI_z}} L = n\pi, n=1,2,\dots$

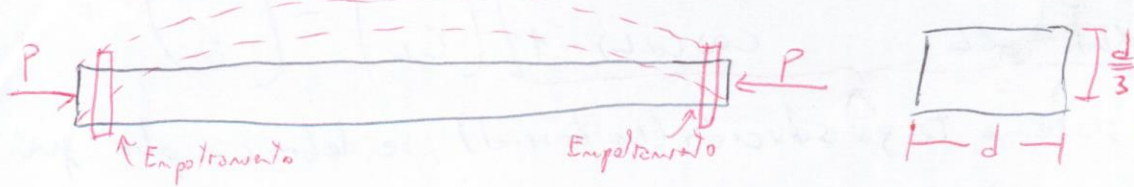
$$\therefore P_{cr}^{(1)} = \left(\frac{n\pi}{L}\right)^2 EI_z = \left(\frac{\pi}{L}\right)^2 EI_z$$

(Primera carga crítica)

Condición de falla $F_{AB} = \frac{P_{cr}^{(1)}}{F.S} \leadsto \frac{(a+b)}{b} F = \left(\frac{\pi}{L}\right)^2 E \cdot \left(\frac{d}{3} \cdot \frac{d^3}{12}\right) \cdot \frac{1}{F.S}$

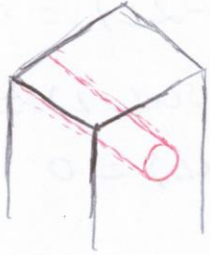
$$\therefore F = \left(\frac{\pi}{L}\right)^2 \cdot \frac{b d^4 E}{36(a+b) \cdot F.S} = 1185,33 \text{ N}$$

iii) Falla por pandeo en el plano x-z



Soln

$$z(x) = C_1 \cdot \sin\left(\sqrt{\frac{P}{EI_z}} x\right) + C_2 \cos\left(\sqrt{\frac{P}{EI_z}} x\right) + C_3 x + C_4$$



El pasador permite el giro libre en una dirección (plano x-y), sin embargo, impide completamente el movimiento en la otra (plano x-z), por lo tanto, en ese plano se considera como un empotramiento (y se toman las cond. de borde correspondientes)

C.B)

$$z(0) = 0 \rightarrow C_2 + C_4 = 0 \quad (1)$$

$$\frac{dz}{dx}(0) = 0 \rightarrow C_1 \sqrt{\frac{P}{EI_z}} + C_3 = 0 \quad (2)$$

$$\frac{dz}{dx}(L) = 0 \rightarrow C_1 \sqrt{\frac{P}{EI_z}} \cos\left(\sqrt{\frac{P}{EI_z}} L\right) - C_2 \sin\left(\sqrt{\frac{P}{EI_z}} L\right) + C_3 = 0$$

* Reemplazando C_3 desde (2): $\alpha = \sqrt{\frac{P}{EI_z}}$

$$C_1 \left(\alpha \cos\left(\sqrt{\frac{P}{EI_z}} L\right) - \alpha \right) - C_2 \sin\left(\sqrt{\frac{P}{EI_z}} L\right) \alpha = 0 \quad (3)$$

$$z(L) = 0 \rightarrow C_1 \sin(\alpha L) + C_2 \cos(\alpha L) + C_3 L + C_4 = 0$$

* Reemplazando C_3 desde (2) y C_4 desde (1):

$$C_1 (\sin(\alpha L) - \alpha L) + C_2 (\cos(\alpha L) - 1) = 0 \quad (4)$$

• Es posible expresar las eqs. (3) y (4) como un sistema matricial:

$$\begin{pmatrix} \alpha \cos(\alpha L) - \alpha & -\alpha \sin(\alpha L) \\ \sin(\alpha L) - \alpha L & \cos(\alpha L) - 1 \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

• Para que este sistema tenga solución (No trivial), se debe cumplir que:

$$\det(A) = 0$$

$$\Rightarrow (\alpha \cos(\alpha L) - \alpha)(\cos(\alpha L) - 1) + \sin(\alpha L)(\sin(\alpha L) - \alpha L) = 0$$

$$\alpha \cos^2(\alpha L) - \alpha \cos(\alpha L) - \alpha \cos(\alpha L) + \alpha + \sin^2(\alpha L) - \alpha L \sin(\alpha L) = 0$$

$$\alpha (\sin^2(\alpha L) + \cos^2(\alpha L)) - 2\alpha \cos(\alpha L) + \alpha - \alpha L \sin(\alpha L) = 0$$

$$2\alpha - 2\alpha \cos(\alpha L) - \alpha L \sin(\alpha L) = 0$$

$$\therefore 2 - 2\cos(\alpha L) - L \sin(\alpha L) = 0$$

• Ec. se cumple si $\alpha L = 2n\pi$, $n = 1, 2, 3, \dots$

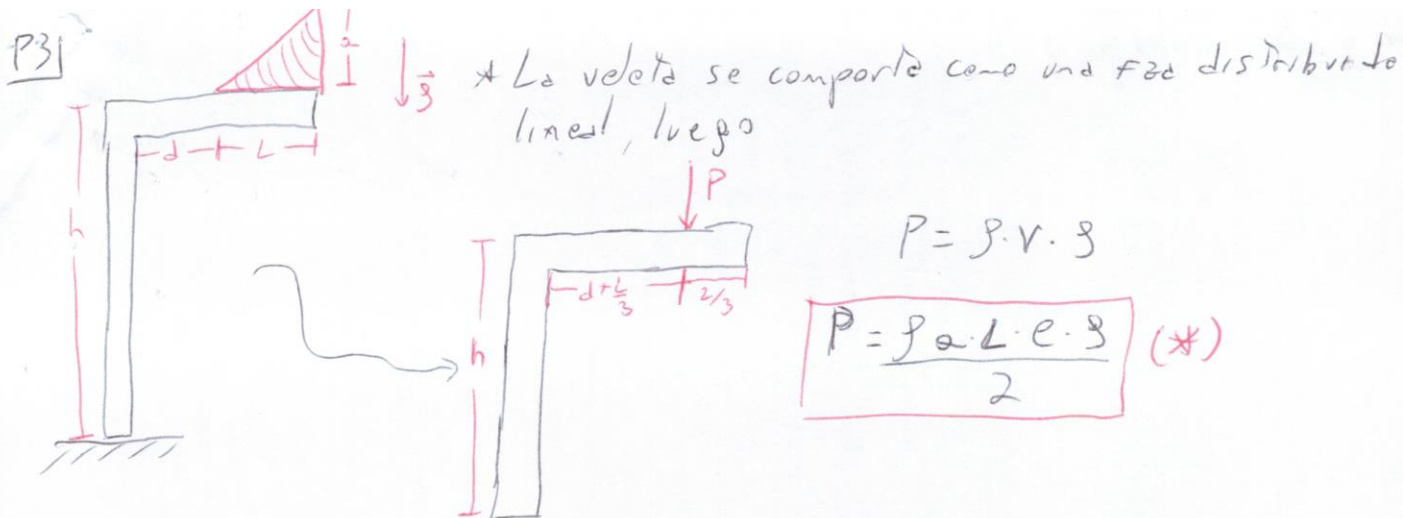
$$\Rightarrow \sqrt{\frac{P}{EI_y}} L = 2\pi n \quad \leadsto \quad P_{cr}^{(1)} = 4 \left(\frac{\pi}{L} \right)^2 EI_y$$

Condición de falla $F_{AB} = \frac{P_{cr}^{(1)}}{F.S} \leadsto \frac{(e+ b)}{b} F = \frac{4}{F.S} \left(\frac{\pi}{L} \right)^2 EI_y$

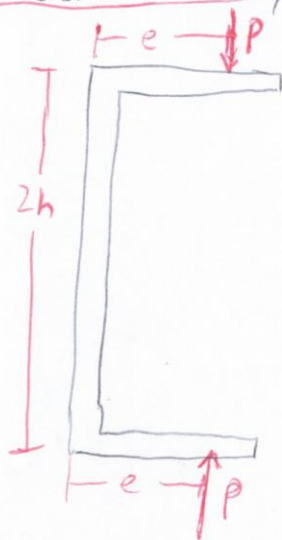
$$* I_y = \frac{d \cdot \left(\frac{d}{3} \right)^3}{12} = \frac{d^4}{324} \leadsto \therefore F = \left(\frac{\pi}{L} \right)^2 \frac{4Eb \cdot d^4}{324(e+b)(F.S)}$$

$$F = 526,81 \text{ N}$$

$$\therefore F_{crítico} = 526,81 \text{ N (Falla por pandeo en el plano X-Z primero)}$$



* El problema se asemeja a la mitad de un problema de pandeo con excentricidad, luego:



Soln]

$$y(x) = C_1 \operatorname{sen}\left(\sqrt{\frac{P'}{EI_z}} x\right) + C_2 \cos\left(\sqrt{\frac{P'}{EI_z}} x\right) - e$$

C.B) (sólo dos)

$$\bullet y(0) = 0 \leadsto C_2 = e$$

$$\bullet y(2h) = 0 \leadsto C_1 \operatorname{sen}\left(\sqrt{\frac{P'}{EI_z}} 2h\right) + e \cos\left(\sqrt{\frac{P'}{EI_z}} L\right) - e = 0$$

$$\therefore C_1 = \frac{e \left(1 - \cos\left(\sqrt{\frac{P'}{EI_z}} L\right)\right)}{\operatorname{sen}\left(\sqrt{\frac{P'}{EI_z}} 2h\right)}$$

* En C1 se puede dar inestabilidad si $\operatorname{sen}\left(\sqrt{\frac{P'}{EI_z}} 2h\right) = 0$

$$\Rightarrow \sqrt{\frac{P'}{EI_z}} \cdot 2h = n\pi \Rightarrow P_{cr}^{(n)} = \frac{1}{4} \left(\frac{n\pi}{h}\right)^2 EI_z \quad (n=1)$$

$$* I_z = \frac{\pi}{64} (\phi_e^4 - \phi_i^4) = 3,68 \cdot 10^{-8} \text{ m}^4$$

* Reemplazando en (*), se tiene $\leadsto a = \frac{EI_z}{2\rho L e g} \left(\frac{\pi}{h}\right)^2 = 0,274 \text{ m}$