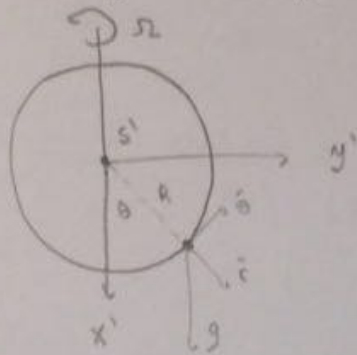


Parte Ejercicio # 8



$$\ddot{g} = g(\hat{r} \cos\theta - \hat{\theta} \sin\theta)$$

$$\ddot{r} = \Omega(\hat{\theta} \sin\theta - \hat{r} \cos\theta) \quad \ddot{r} = \Omega \hat{k}$$

• En  $s'$   $r' = R\hat{r} \rightarrow v' = R\dot{\theta}\hat{\theta} \rightarrow \dot{a}' = R(\ddot{\theta}\hat{\theta} - \dot{\theta}^2\hat{r})$

(a)  $\hat{\theta} \downarrow$   $mR\ddot{\theta} = -mg\sin\theta$

• Peso =  $-mg\hat{j} = -mg\sin\theta\hat{\theta} - mg\cos\theta\hat{r}$

• Normal =  $N\hat{r}$  1.5 pto.

pseudo Fuerzas

$\rightarrow$  centrífuga :  $-m\Omega(\hat{\theta}\sin\theta - \hat{r}\cos\theta) \times (\Omega(\hat{\theta}\sin\theta - \hat{r}\cos\theta) \times R\hat{r})$

$$= -m\Omega^2 R(-\sin^2\theta\hat{r} - \cos\theta\sin\theta\hat{\theta}) - \hat{r}\sin\theta$$

$$= m\Omega^2 R(\sin^2\theta\hat{r} + \cos\theta\sin\theta\hat{\theta})$$

$\rightarrow$  Coriolis =  $2m\Omega(\hat{\theta}\sin\theta - \hat{r}\cos\theta) \times R\dot{\theta}\hat{\theta}$

$$= +2m\Omega R\dot{\theta}\cos\theta\hat{k}$$

$\rightarrow$  transversal = 0

(b)

$\rightarrow$  ecuación completa  $\hat{\theta} \downarrow$   $mR\ddot{\theta} = -mg\sin\theta + m\Omega^2 R\cos\theta\sin\theta$  1.5 pto.

(c)

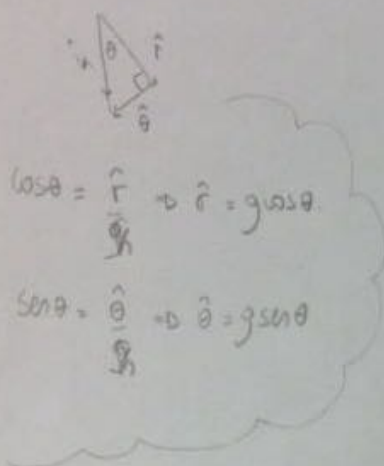
$$F = -\nabla U \rightarrow U = \int F dr = - \int (m\Omega^2 R \underbrace{\cos\theta\sin\theta}_{\frac{\sin(2\theta)}{2}} - mg\sin\theta) R d\theta$$

$$\rightarrow U = mRg \left( \frac{R\Omega^2}{4g} \cos(2\theta) - \cos(\theta) \right)$$
 1.5 pto.

(d) entonces para que sea punto de equilibrio  $F=0 \rightarrow \cos\theta\sin\theta = \frac{mg\sin\theta}{m\Omega^2 R}$

$\rightarrow \cos\theta = \frac{g}{R\Omega^2}$  y  $\frac{g}{R\Omega^2} < 1 \rightarrow \Omega^2 \geq \frac{g}{R}$

\*  $\frac{\partial U}{\partial \theta} = -m\Omega^2 R \sin^2\theta + m\Omega^2 R \cos^2\theta + mg\cos\theta$   $\theta=0 \rightarrow m\Omega^2 R + mg > 0 \rightarrow \Omega^2 > \frac{g}{R}$



$$\cos\theta = \frac{\hat{r}}{r} \rightarrow \hat{r} = g\cos\theta$$

$$\sin\theta = \frac{\hat{\theta}}{r} \rightarrow \hat{\theta} = g\sin\theta$$