

$$mg - kx = m\ddot{x}$$

$$0 = m\ddot{x} + kx - mg$$

$$0 = \ddot{x} + \frac{k}{m}x - g$$

$$0 = \ddot{x} + \frac{k}{m}\left(x - \frac{mg}{k}\right)$$

$$z(t) = x(t) - \frac{mg}{k}$$

$$\dot{z} = \dot{x}$$

$$\ddot{z} = \ddot{x}$$

$$0 = \ddot{z} + \frac{k}{m}z$$

$$\omega^2 = \frac{k}{m}$$

Ans: $z(t) = A \cos(\omega t + \phi)$

$$\dot{z} = -A\omega \sin(\omega t + \phi)$$

C-I $z(0) = d$

$$\dot{z}(0) = 0$$

$$0 = -A\omega \sin(\phi) \Rightarrow \phi = 0$$

$$z(t) = A \cos(\omega t)$$

$$z(0) = d = A \cos(0) \Rightarrow A = d$$

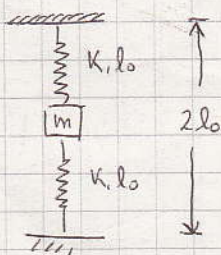
$$\Rightarrow z(t) = d \cos(\omega t)$$

Wiederum a $x(t) \Rightarrow x(t) = z(t) + \frac{mg}{k}$

$$x(t) = d \cos(\omega t) + \frac{mg}{k}$$

Plt

o oscilador armónico:



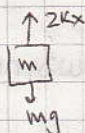
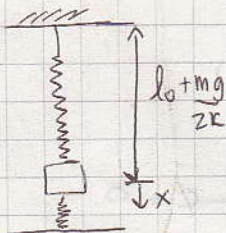
determine ec. de mov. para el MAS considerando que inicialmente ($t=0$) ambos resortes están en su largo natural y el bloque está en reposo.

sol: consideramos el pto de equilibrio con el bloque: bajo una distancia X del pto de equilibrio



$$2Kx - mg = 0$$

$$X = \frac{mg}{2K} \quad \text{nuevo pto de eq}$$



$$2Kx - mg = +m \cdot \ddot{x}$$

$$\frac{2Kx}{m} - g = +\ddot{x}$$

$$0 = \ddot{x} + g - \frac{2Kx}{m}$$

$$0 = \ddot{x} + \frac{2K}{m} \left(\frac{mg}{2K} - x \right)$$

$$z = \frac{mg}{2K} - x$$

$$\dot{z} = -\dot{x}$$

$$\ddot{z} = -\ddot{x}$$

$$0 = -\ddot{z} + \frac{2K}{m} z$$

$$0 = \left(\ddot{z} - \frac{2K}{m} z \right) \cdot -1$$

$$\omega^2 = -\frac{2K}{m}$$

$$0 = \ddot{z} + \omega^2 z$$

$$z(t) = A \cos(\omega t + \phi)$$

$$\dot{z}(t) = -A\omega \sin(\omega t + \phi)$$

$$\text{c.I: } z(t) = d$$

$$\dot{z}(0) = 0$$

$$0 = -A\omega \sin \phi \Rightarrow \phi = 0$$

$$d = A \cos(0) \Rightarrow A = d$$

$$z(t) = d \cos(\omega t)$$

$$\Rightarrow X = \frac{mg}{2K} - d \cos(\omega t)$$