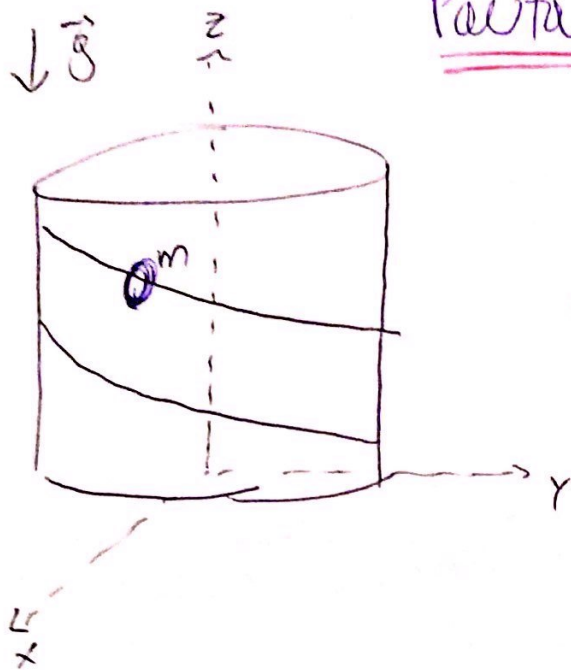




Pauta Ejercicio #6.

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Aux: Sergio Cotre

$$z = h - \phi R_1$$

$$F_{KVL} = -c\vec{v}$$

$$CI: \phi(0) = 0; z(0) = h, \dot{\phi}(0) = 0$$

a) Obtener $\vec{E}$ y el vector $\vec{N}$ general

En cilindricos:

$$\vec{e} = \rho \vec{e} + z \hat{k} = R_0 \vec{e} + (h - \phi R_1) \hat{k}$$

$$\vec{v} = \rho \dot{\phi} \vec{e} + \dot{z} \hat{k} = R_0 \dot{\phi} \vec{e} - R_1 \dot{\phi} \hat{k} = \dot{\phi} (R_0 \vec{e} - R_1 \hat{k})$$

$$\vec{a} = R_0 \ddot{\phi} \vec{e} - R_1 \ddot{\phi} \hat{k} - R_1 \dot{\phi}^2 \vec{e}$$

Sabemos que:

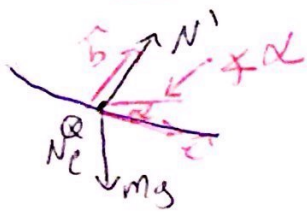
$$\vec{E} = \frac{\vec{v}}{\|\vec{v}\|} = \frac{(R_0 \vec{e} - R_1 \hat{k}) \dot{\phi}}{\dot{\phi} \sqrt{R_0^2 + R_1^2}} = \frac{R_0 \vec{e} - R_1 \hat{k}}{\sqrt{R_0^2 + R_1^2}} \quad 0.5$$

Luego sea $\vec{N} = \begin{pmatrix} N_e \\ N_\phi \\ N_k \end{pmatrix}$ el vector normal, sabemos que $\vec{E} \cdot \vec{N} = 0$

$$\Rightarrow R_0 N_\phi = R_1 N_k \Rightarrow N_\phi = \frac{R_1}{R_0} N_k$$

$$\Rightarrow \vec{N} = -N_e \vec{e} + \frac{R_1}{R_0} N_k \vec{e} + N_k \hat{k} \quad 0.5$$

b) DCL



Donde $N' = \sqrt{N_k^2 + N_p^2} = N_k \sqrt{1 + \frac{R_1^2}{R_0^2}} = \frac{N_k}{R_0} \sqrt{R_1^2 + R_0^2}$

Podemos ahora escribir la aceleración en términos de $\hat{e}$ como:

$$\vec{v} = \|\vec{v}\| \hat{e} = \dot{\phi} \sqrt{R_1^2 + R_0^2} \hat{e}$$

$$\vec{a} = R_0 \ddot{\phi} \hat{n} + \dot{\phi}^2 \sqrt{R_1^2 + R_0^2} \hat{e}$$

$$\Rightarrow \hat{n} \mid m R_0 \dot{\phi}^2 = N_e$$

Además:

$$\sin \alpha = \frac{R_1}{\sqrt{R_1^2 + R_0^2}} \quad \cos \alpha = \frac{R_0}{\sqrt{R_1^2 + R_0^2}}$$

Perdón ~~$m \dot{\phi}^2 \sqrt{R_1^2 + R_0^2} = m g \frac{R_1}{\sqrt{R_1^2 + R_0^2}} - c \dot{\phi} \sqrt{R_1^2 + R_0^2}$~~

$$\hat{e} \mid m g \frac{R_0}{\sqrt{R_1^2 + R_0^2}} = N_z$$

De $\hat{e}$ tenemos que:

$$\ddot{\phi} + \frac{c}{m} \dot{\phi} = \frac{g R_1}{R_1^2 + R_0^2} \quad \mid \cdot e^{\frac{c}{m} t} \Rightarrow \ddot{\phi} e^{\frac{c}{m} t} + \frac{c}{m} e^{\frac{c}{m} t} \dot{\phi} = \frac{g R_1}{R_0^2 + R_1^2} e^{\frac{c}{m} t} \int dt$$

$$\dot{\phi} e^{\frac{c}{m} t} = \frac{g R_1 m}{c (R_1^2 + R_0^2)} e^{\frac{c}{m} t} + C \quad \underline{CI} \quad \dot{\phi}(0) = 0 \Rightarrow C = -\frac{g R_1 m}{c (R_1^2 + R_0^2)}$$

$$\Rightarrow \boxed{\dot{\phi} = \frac{g R_1 m}{c (R_1^2 + R_0^2)} (1 - e^{-\frac{c}{m} t})} \quad 2.0$$

Así integrando $\dot{\phi}$ se tiene:

$$\boxed{\phi = \frac{g R_1 m^2}{c^2 (R_1^2 + R_0^2)} \left(e^{-\frac{c}{m} t} + \frac{c}{m} t - 1 \right)} \quad 1.0$$

Luego reemplazando $\dot{\phi}$ en $\hat{n}$ y sabiendo que $\frac{m g R_0}{\sqrt{R_1^2 + R_0^2}} = \sqrt{N_k^2 + N_p^2}$

$$\Rightarrow N_e = m R_0 \cdot \left(\frac{g R_1 m}{c (R_1^2 + R_0^2)} \right)^2 (1 - e^{-\frac{c}{m} t})^2$$

$$N_k = \frac{R_0^2 m g}{R_0^2 + R_1^2} \quad ; \quad N_p = \frac{R_1 R_0 m g}{R_0^2 + R_1^2}$$

$$\vec{N} = N_e \hat{e} + N_p \hat{e}_1 + N_k \hat{e}_2$$

N_0 es necesario reemplazar.

1.0