

Control of a Brushless Doubly-Fed Induction Machine



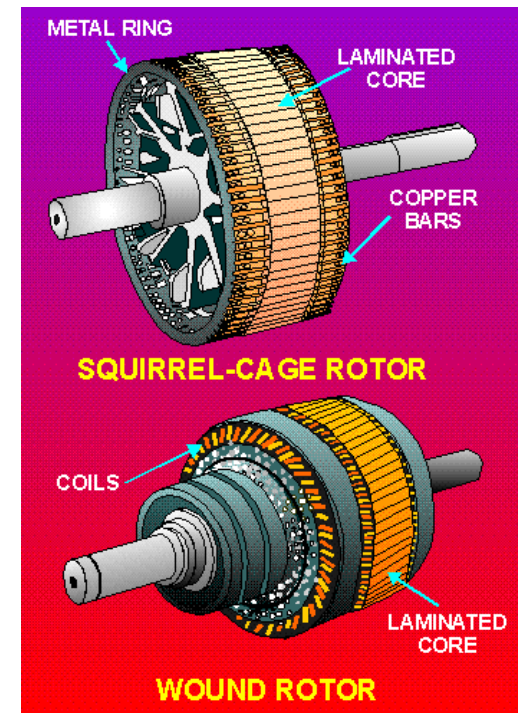
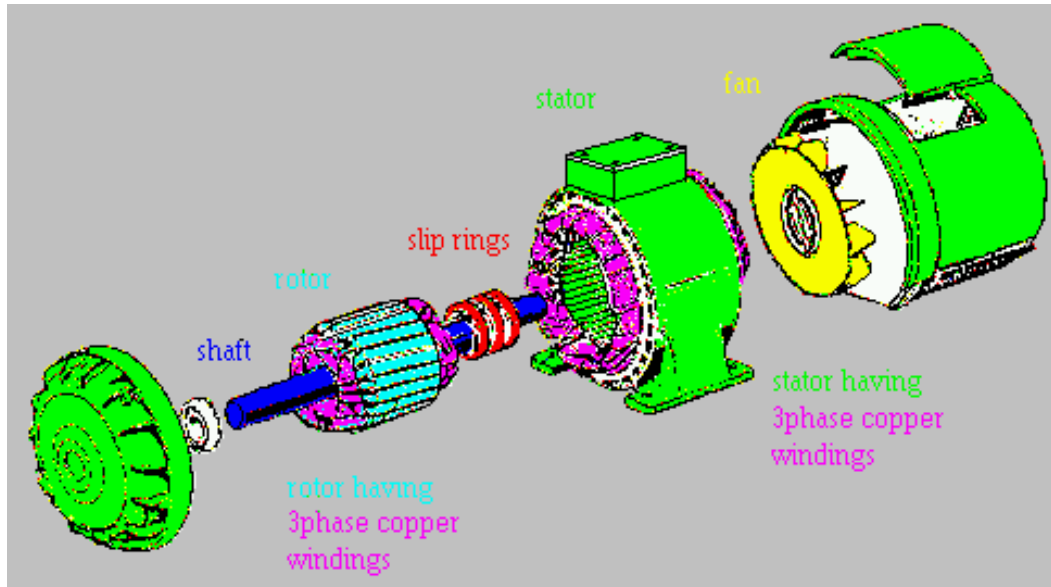
**The University
Of Chile**

Presented by:

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University of Chile

Doubly-Fed Induction Generators

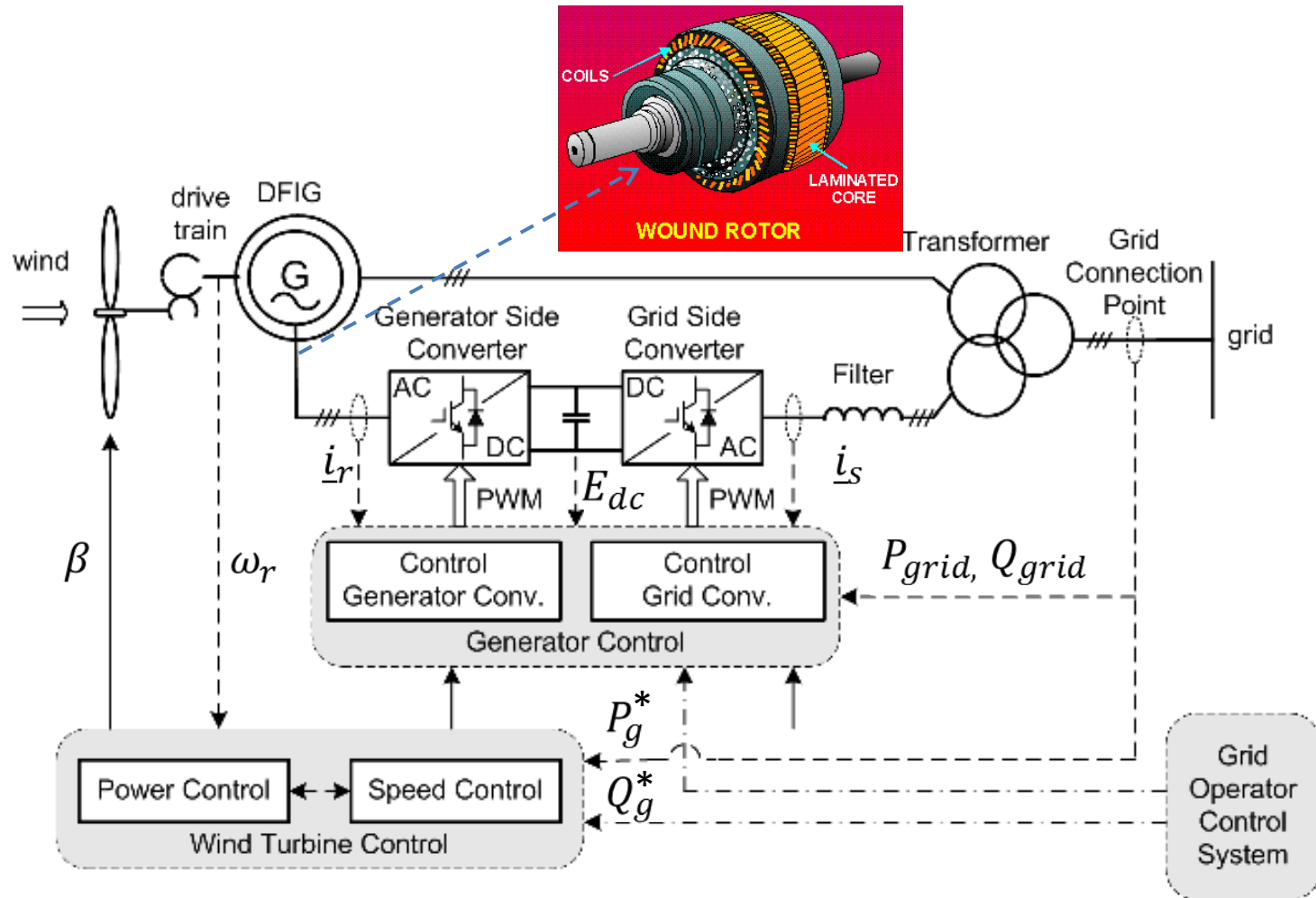
- This machine is widely used in variable speed wind energy applications. Currently this topology occupies close to 50% of the wind energy market.



Manufacturer AAER	Reference A1650-A2000	NM 6	Pow. Range (MW) 2.0
Acciona	AW	6	1.5 - 3.0
Alstom Power	ECO	4	1.67 - 3.0
Dewind	D8.0 – D9.0	1	2.0
Fuhrlander	FL	6	1.5 - 2.5
Gamesa	G	3	2.0
General Electric	GE Energy	7	1.5 - 2.5 - 2.75
Ghodawat	G	1	1.65
Guangdong Mingyang	MY	2	1.5
Guodian United <u>Power</u>	UP1500 UP2000 UP3000	17	1.5-2.0-3.0
Hyosung	HS	1	2.0
Inox Wind	WT	1	2.0
Mitsubishi	MWT	5	2.4
Nordex	N	9	1.5 - 2.4 - 2.5
Repower	MM	6	2.0 - 2.05
Sinovel	SL	8	3.0
Suzlon	S	2	1.5 - 2.1
Vestas	V80 – V90 V100	7	1.8 – 2.0 – 2.6 – 3.0

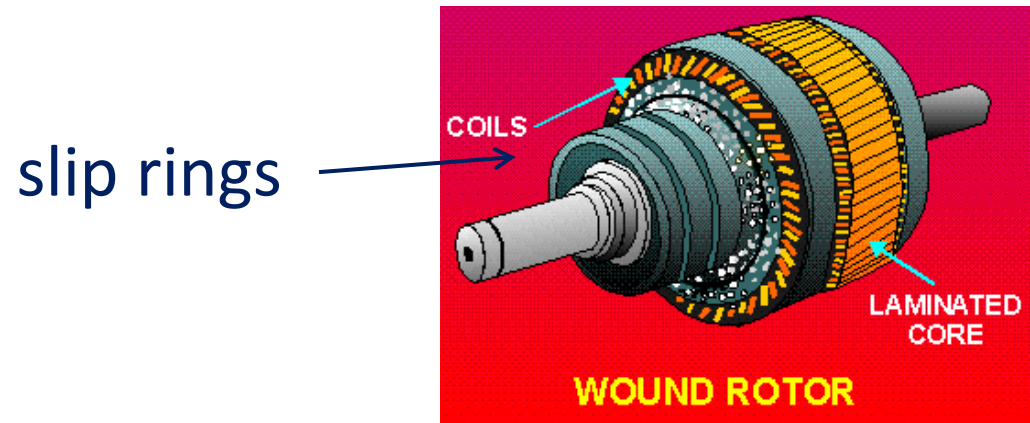
Some commercial DFIGs
in the 1MW to 3MW
power range

Typical topology for a DFIG



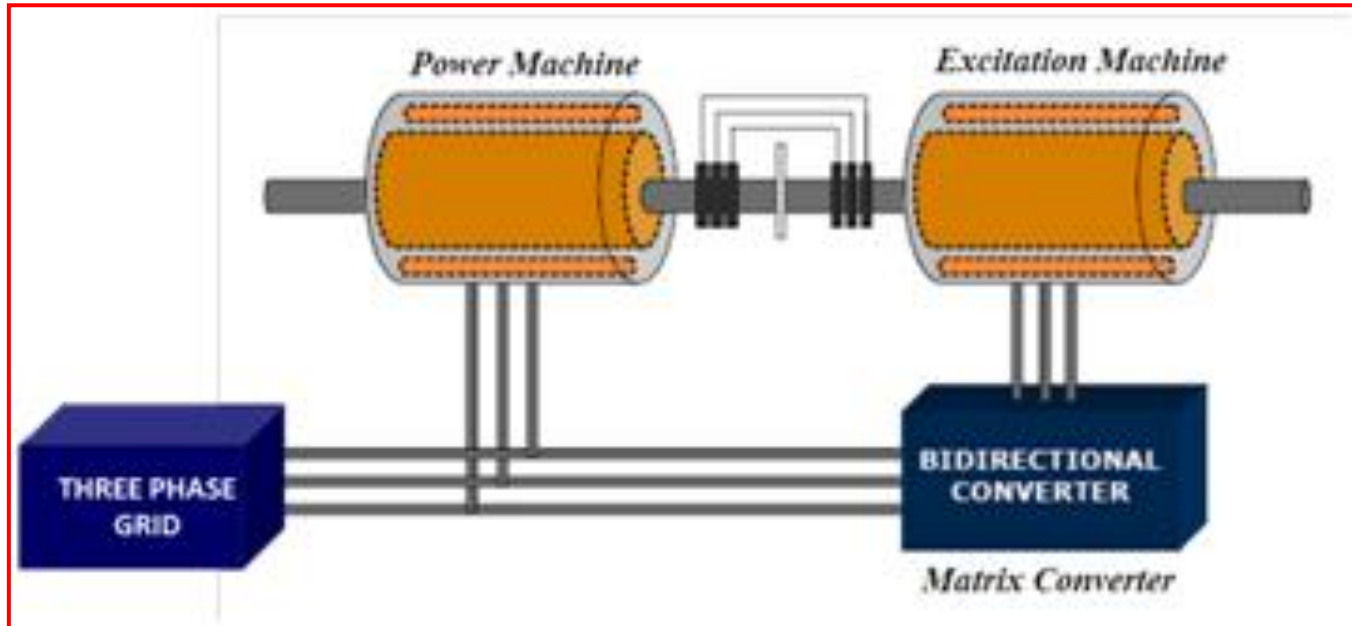
Power converters are usually designed for a nominal power of 30% of that of the doubly-fed machine.

Problems related to the use of Brushes



- In most of the applications where robustness is required, the use of brushes has to be avoided.
- For instance in remote areas, where regular maintenance is difficult to achieve.

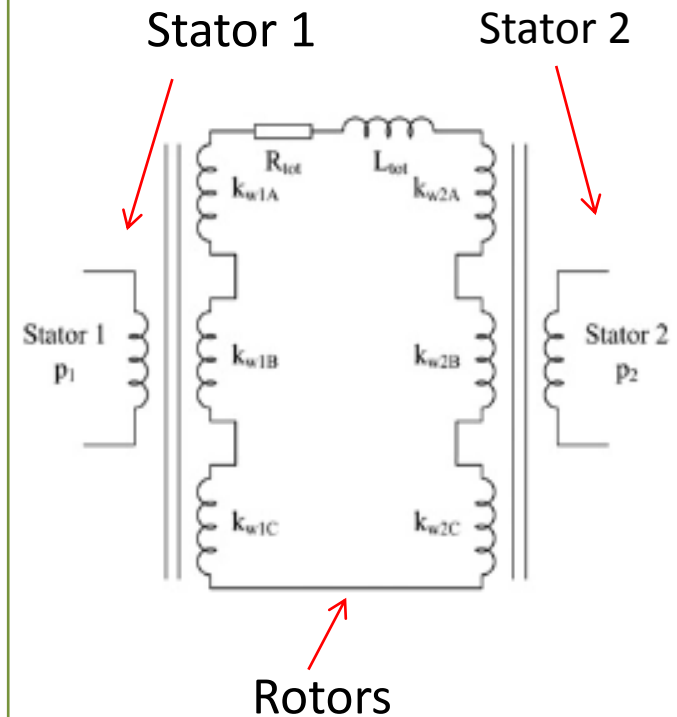
Proposed Brushless Topology

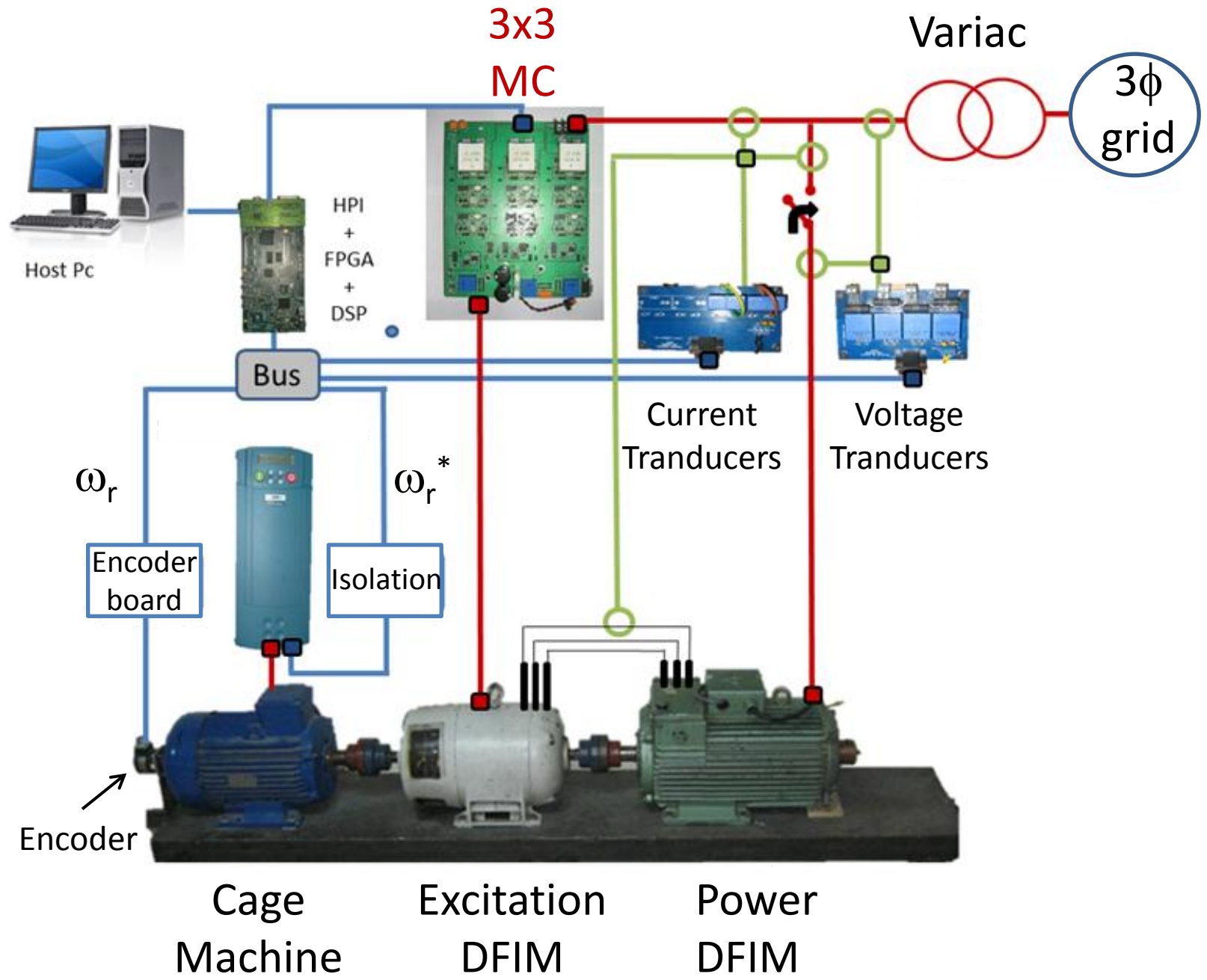


- This is just a representation.
- Two DFIGs in the same shaft (“cascaded” implementation). The signals induced in the rotor of the first machine are used to excite the power machine.

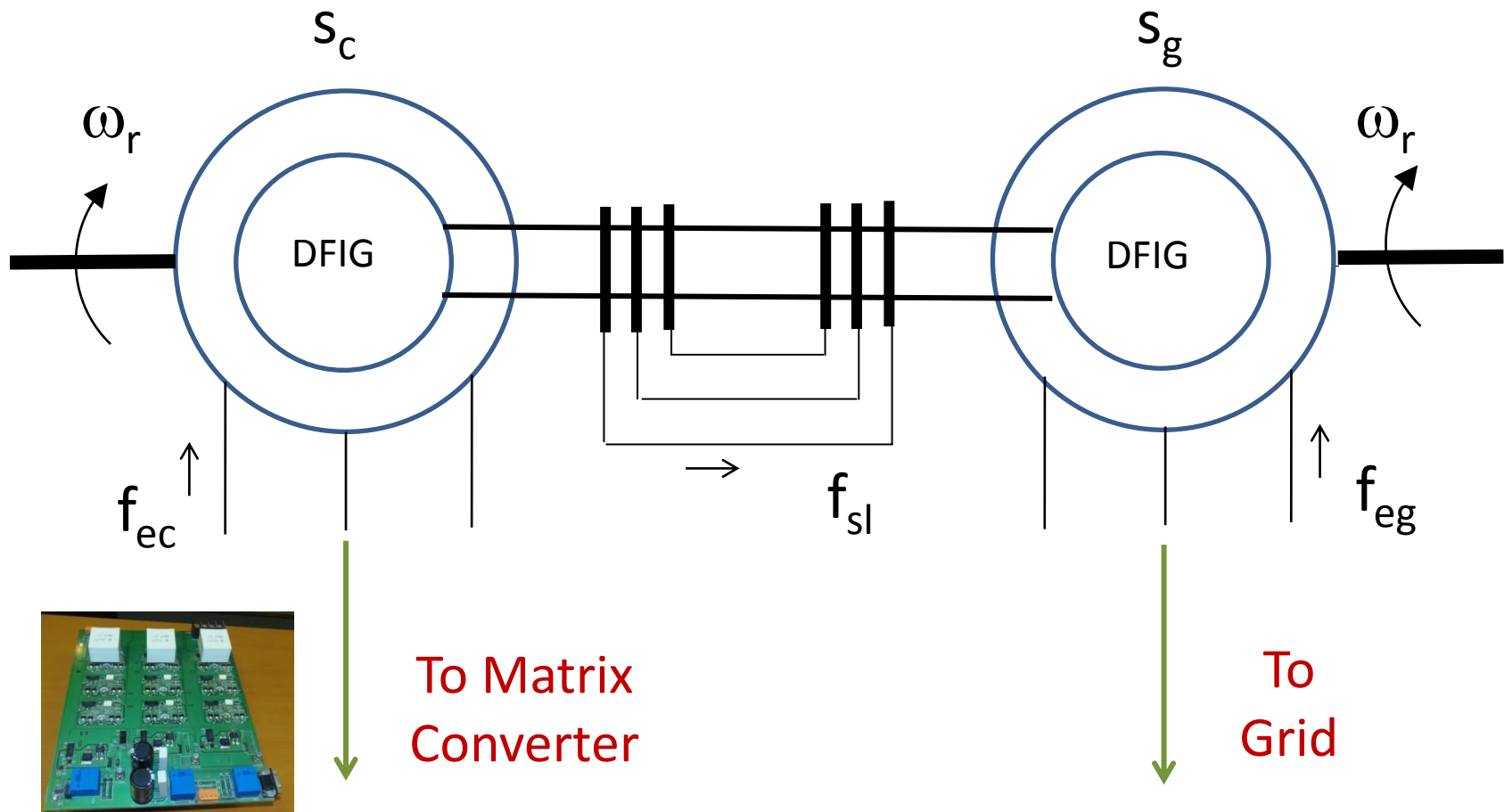
Proposed Brushless Topology

- The Brushless DFIG (BDFIG) could be also implemented using two (3 ϕ each one) stator windings.
- Mathematically the BDFIG implemented using two cascaded machines is similar.

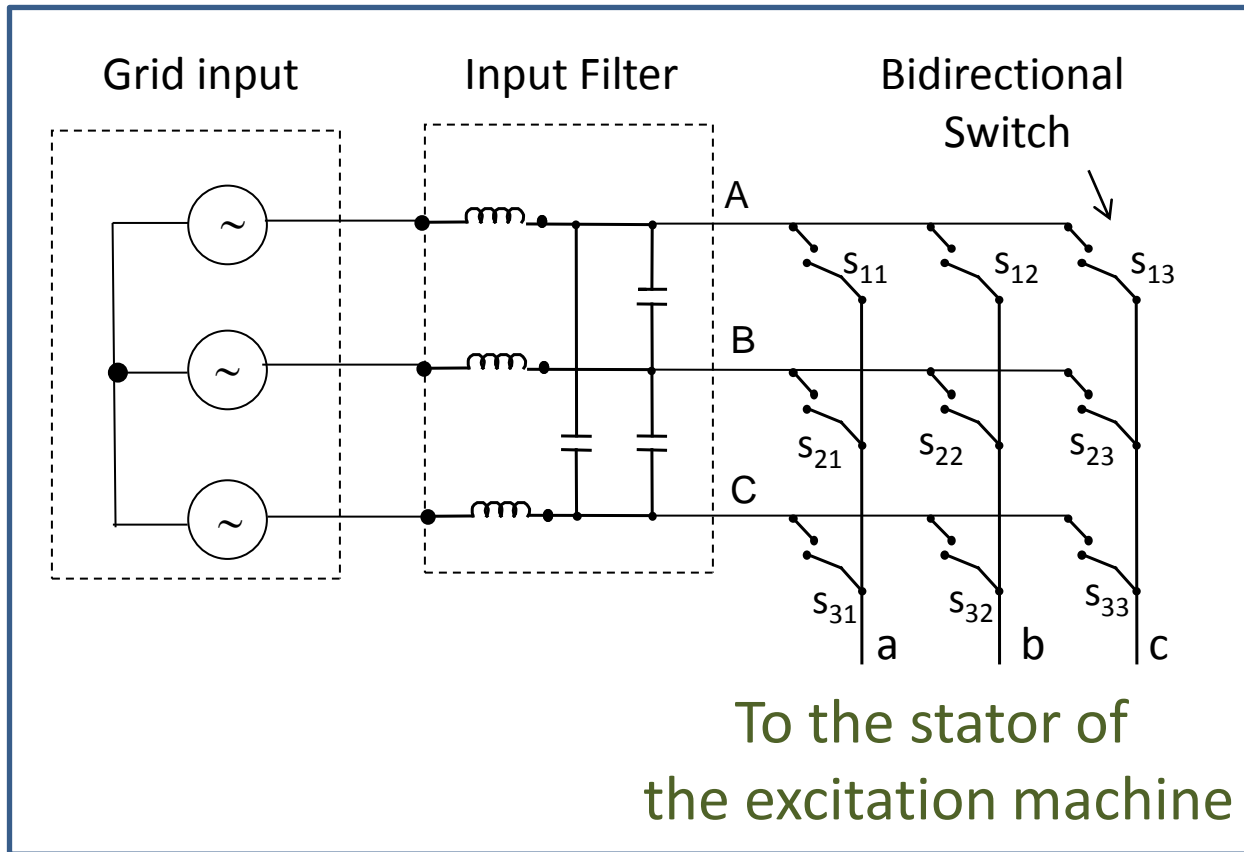




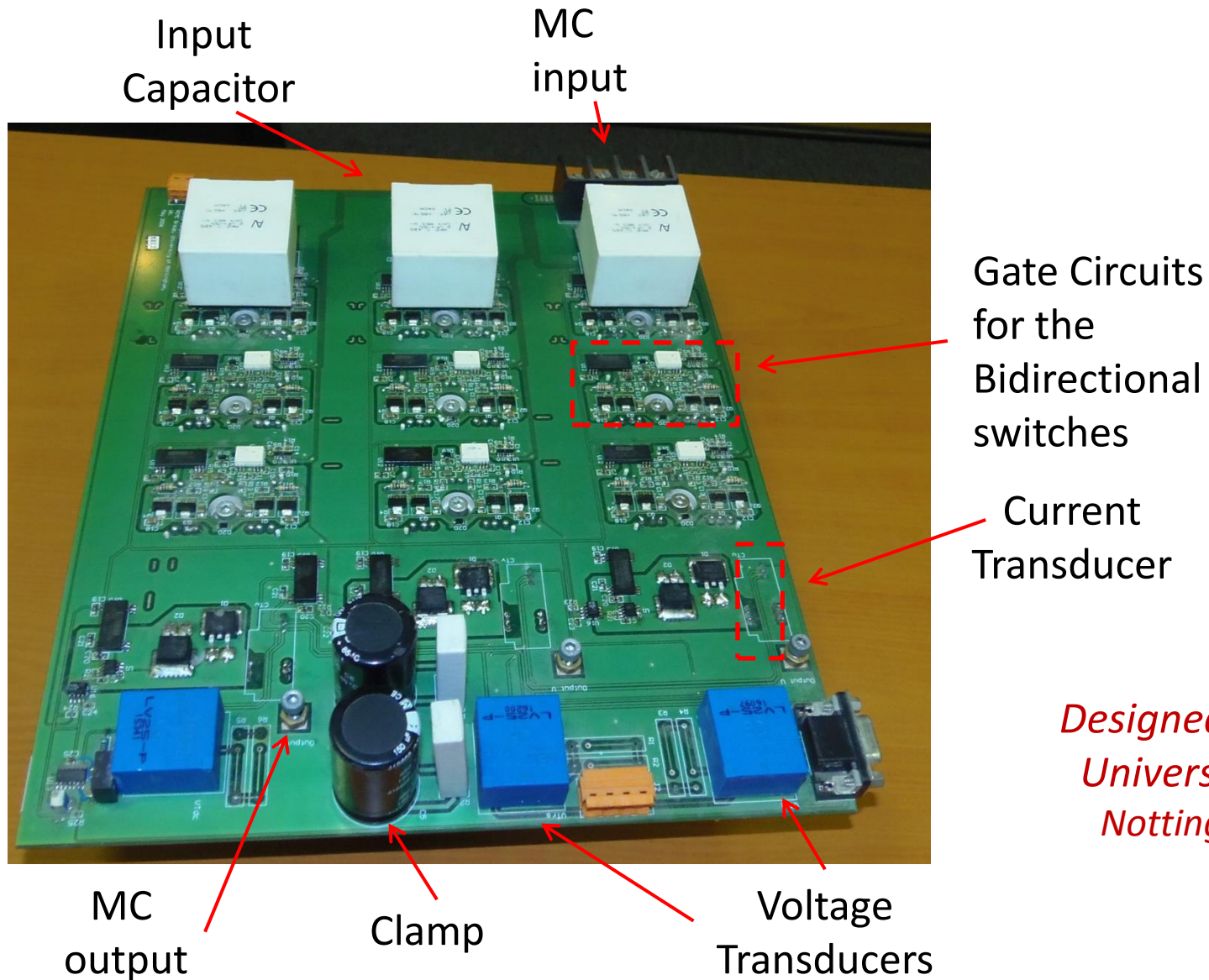
Proposed Brushless Topology



Power Converter used in this applications

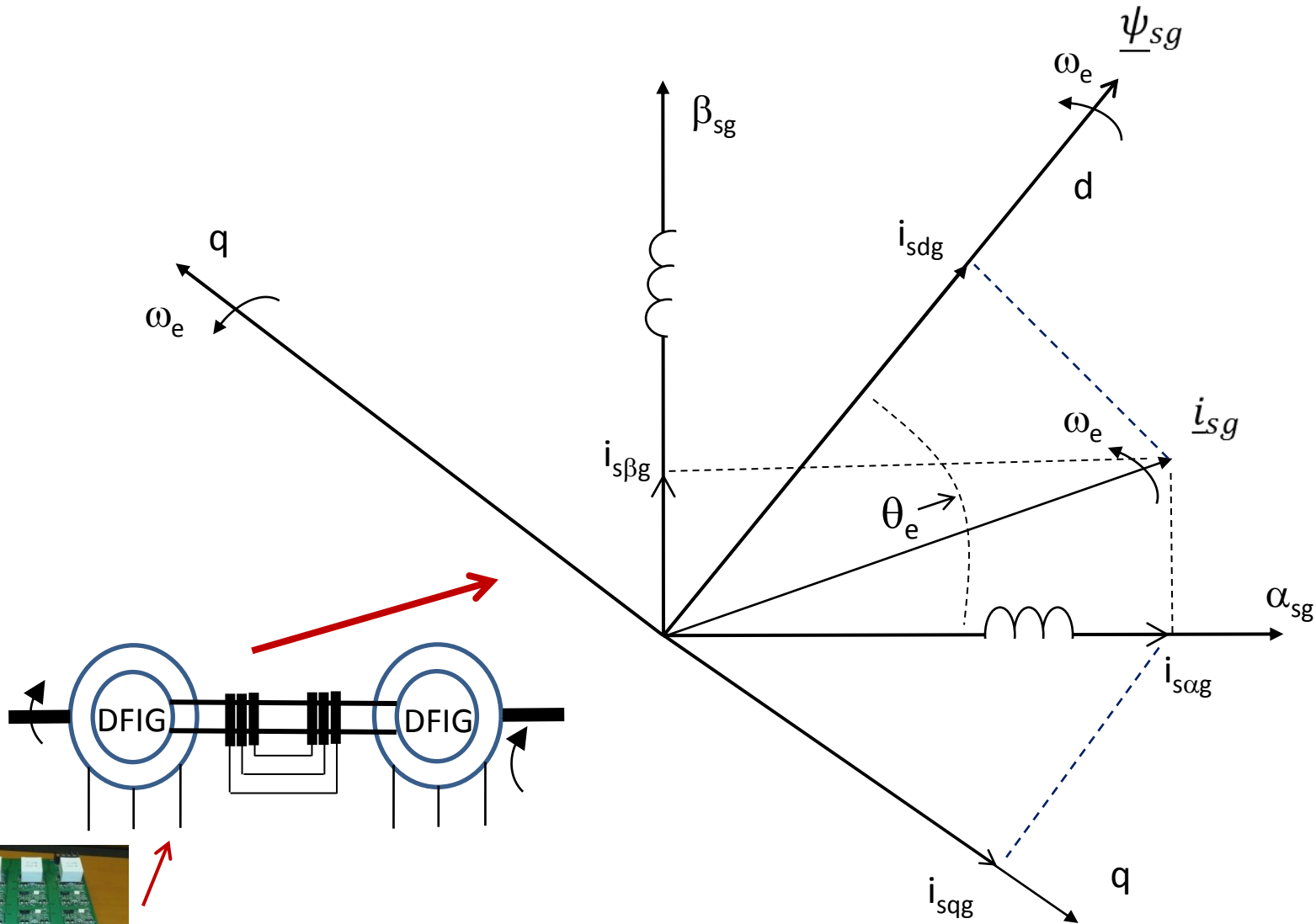


Power Converter used in this applications



*Designed in the
University of
Nottingham*

Vector Control System

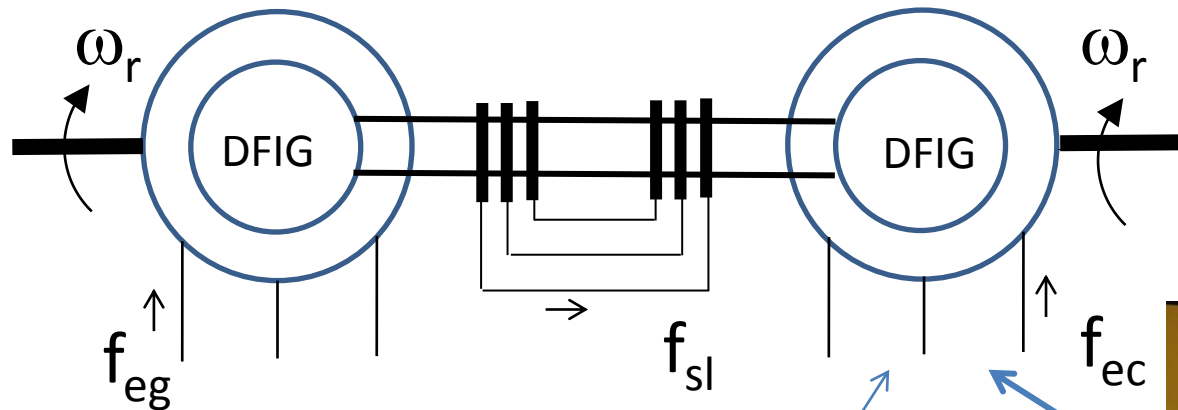


Control system

Power machine
currents

Excitation machine
currents

$$\begin{bmatrix} \Delta i_{sgd} \\ \Delta i_{sgq} \end{bmatrix} = \begin{bmatrix} G_d(s) & -G_q(s) \\ G_q(s) & G_d(s) \end{bmatrix} \begin{bmatrix} \Delta i_{scd} \\ \Delta i_{scq} \end{bmatrix}$$

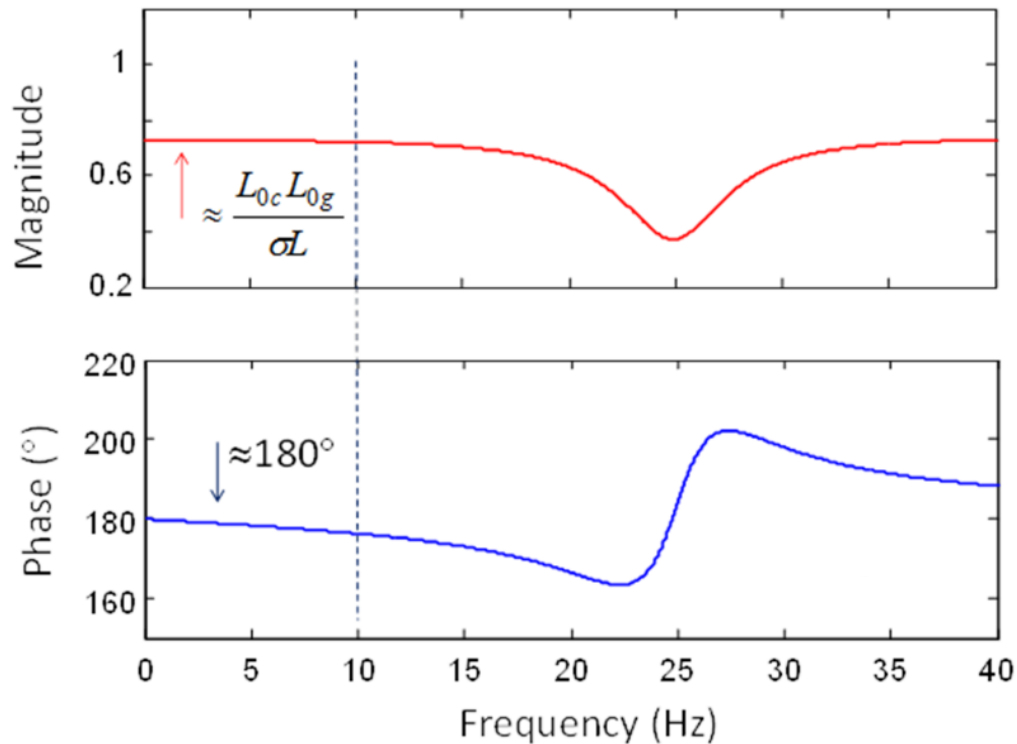


Power machine
currents

Excitation machine
currents

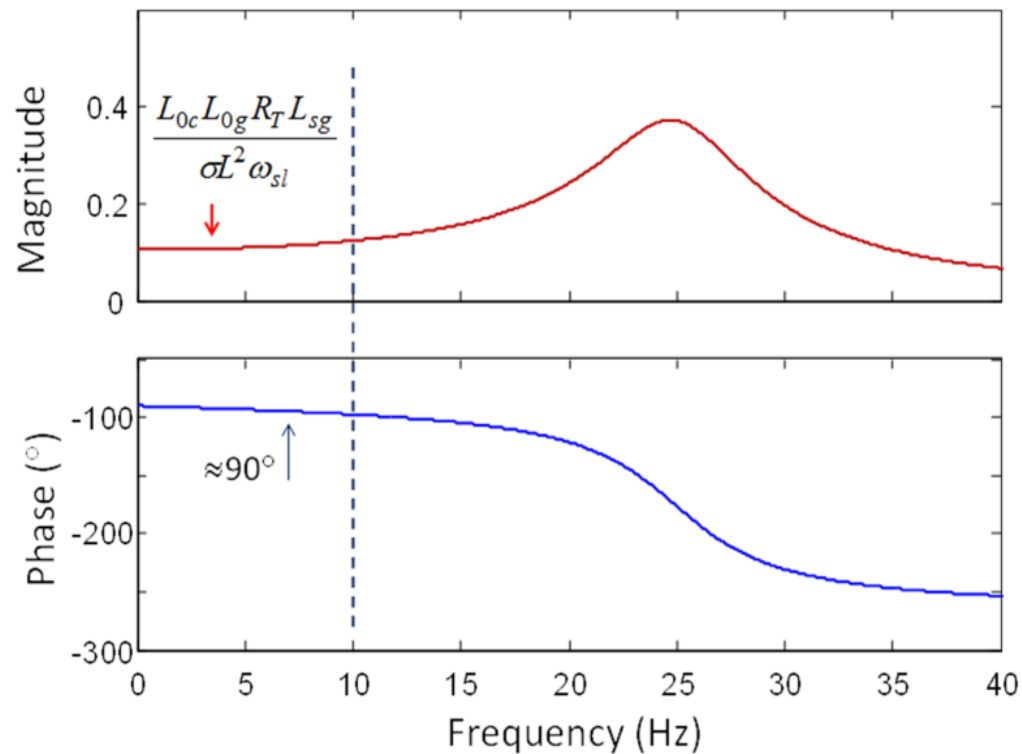


Relationship between the currents in the excitation and power machines



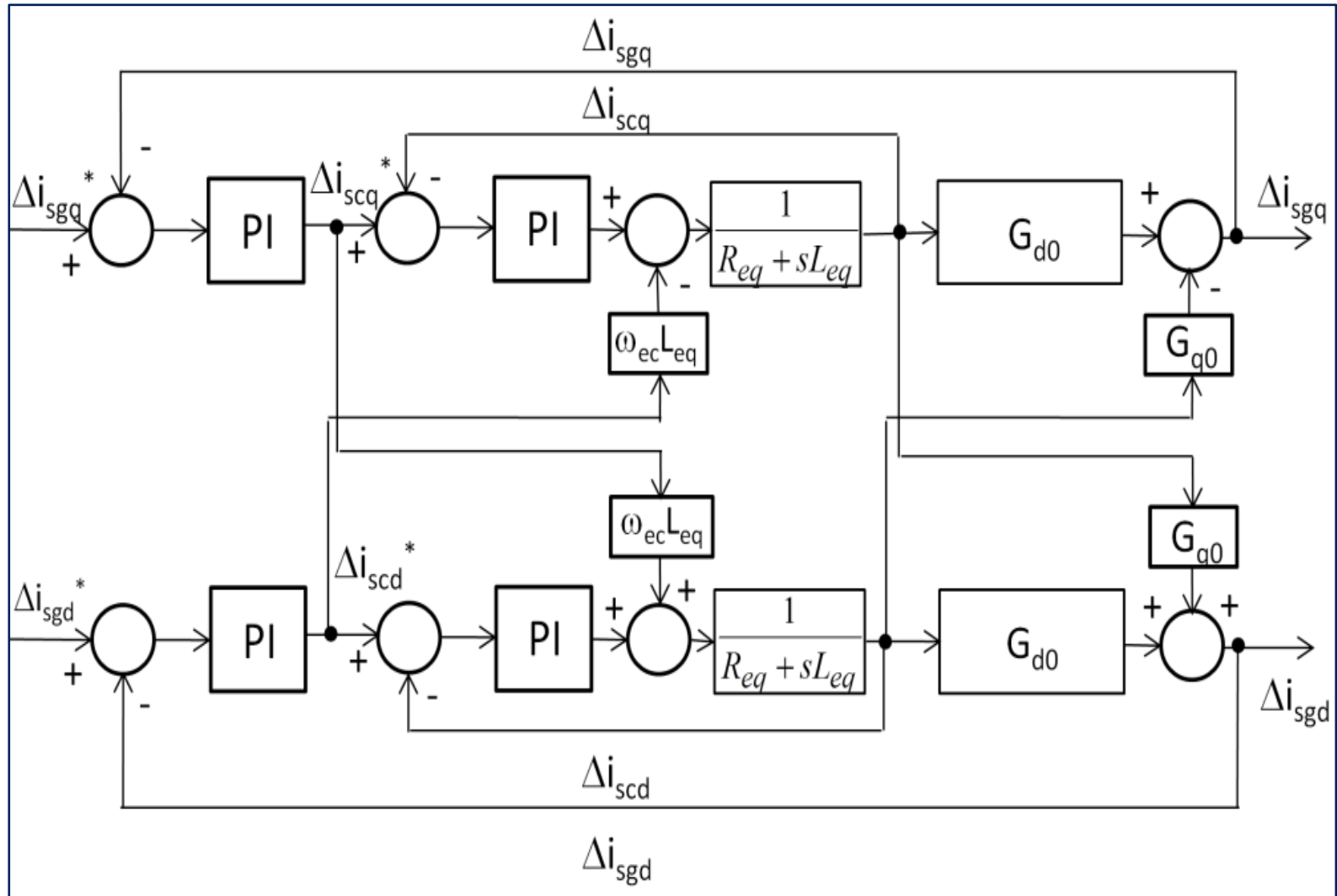
$$G_d(\omega)$$

Relationship between the currents in the excitation and power machines



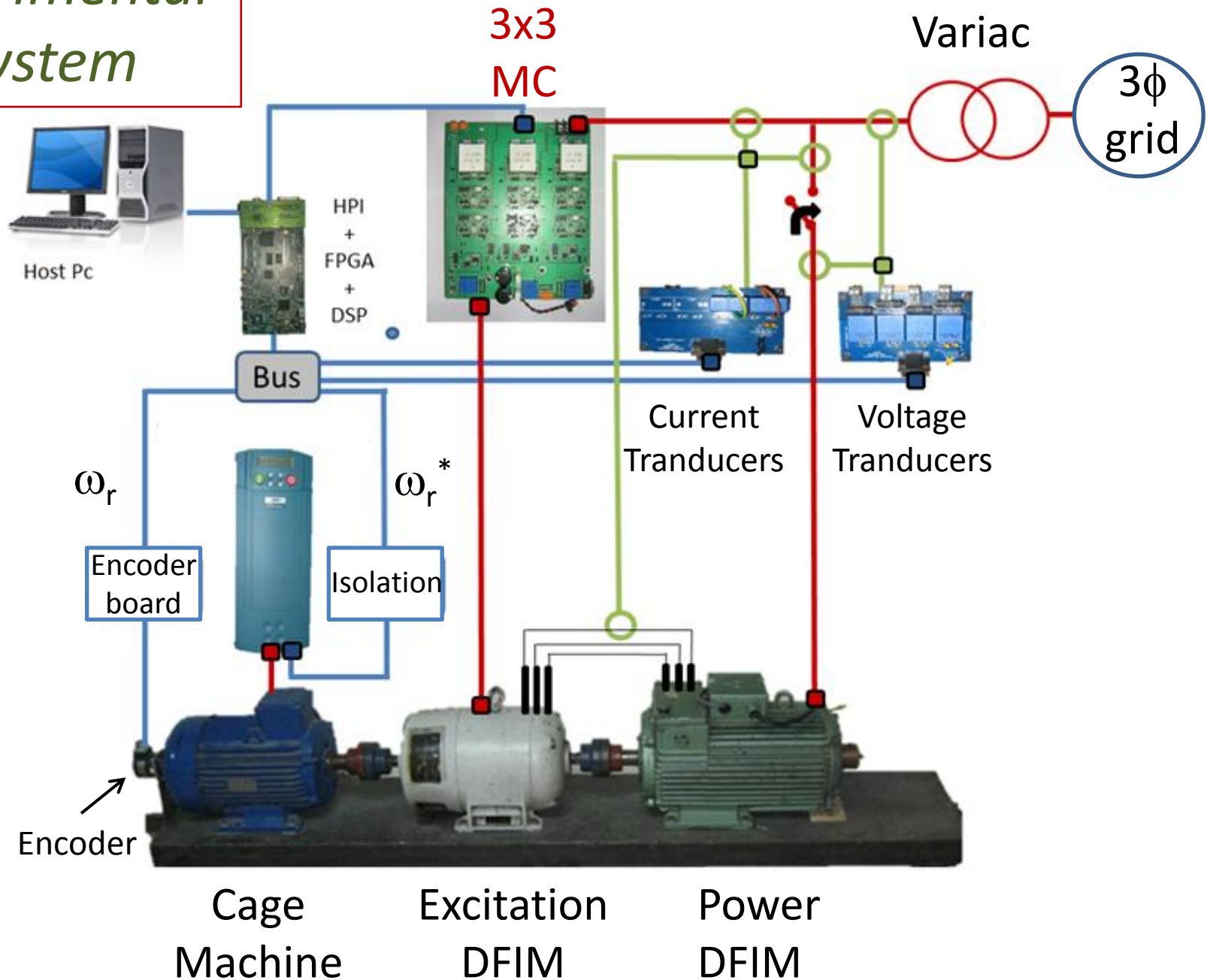
$$G_q(\omega)$$

Control Loops

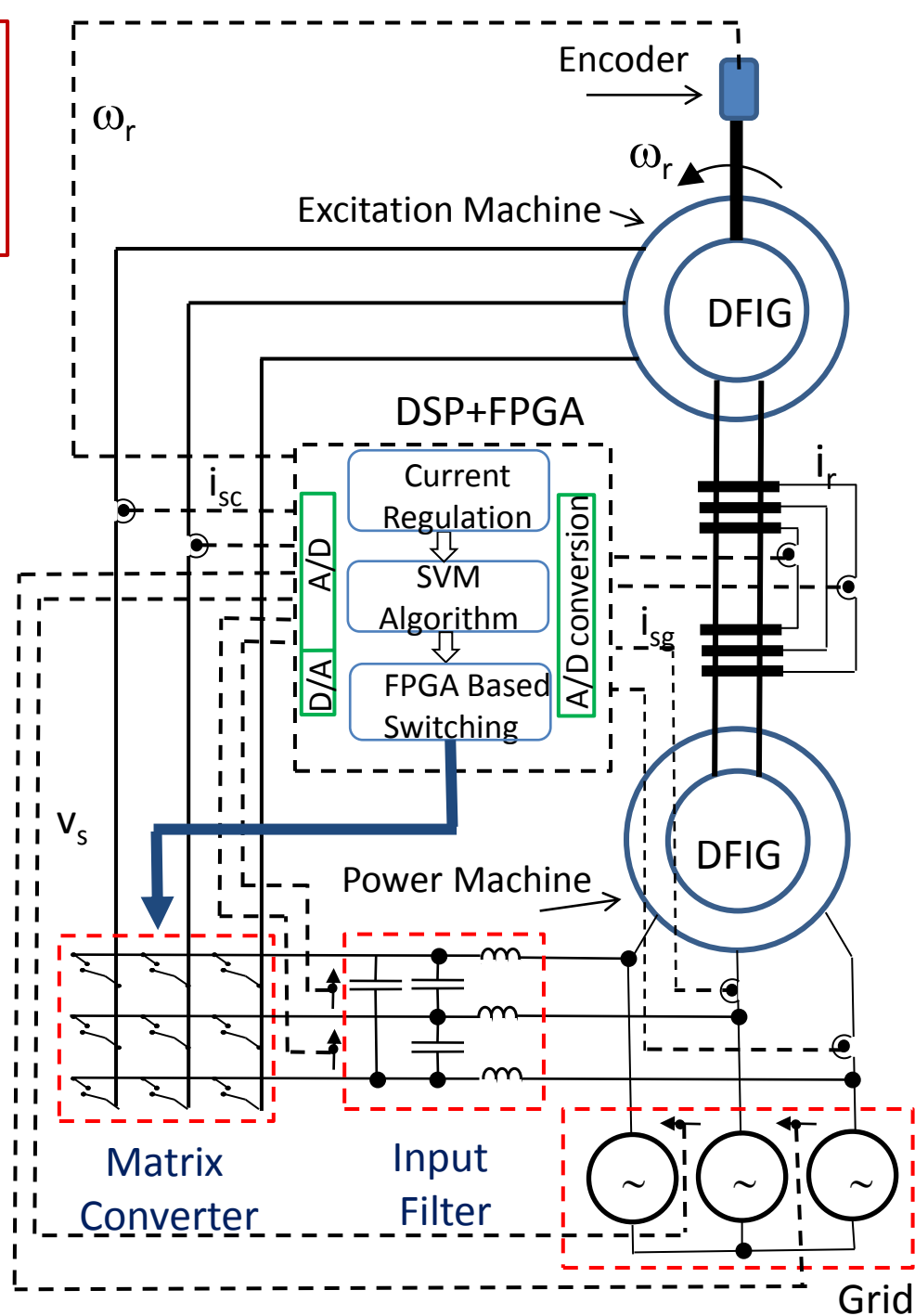


Nested control loops. The outer loop is regulating the currents of the power machine. The inner control loop is regulating the currents of the excitation machine.

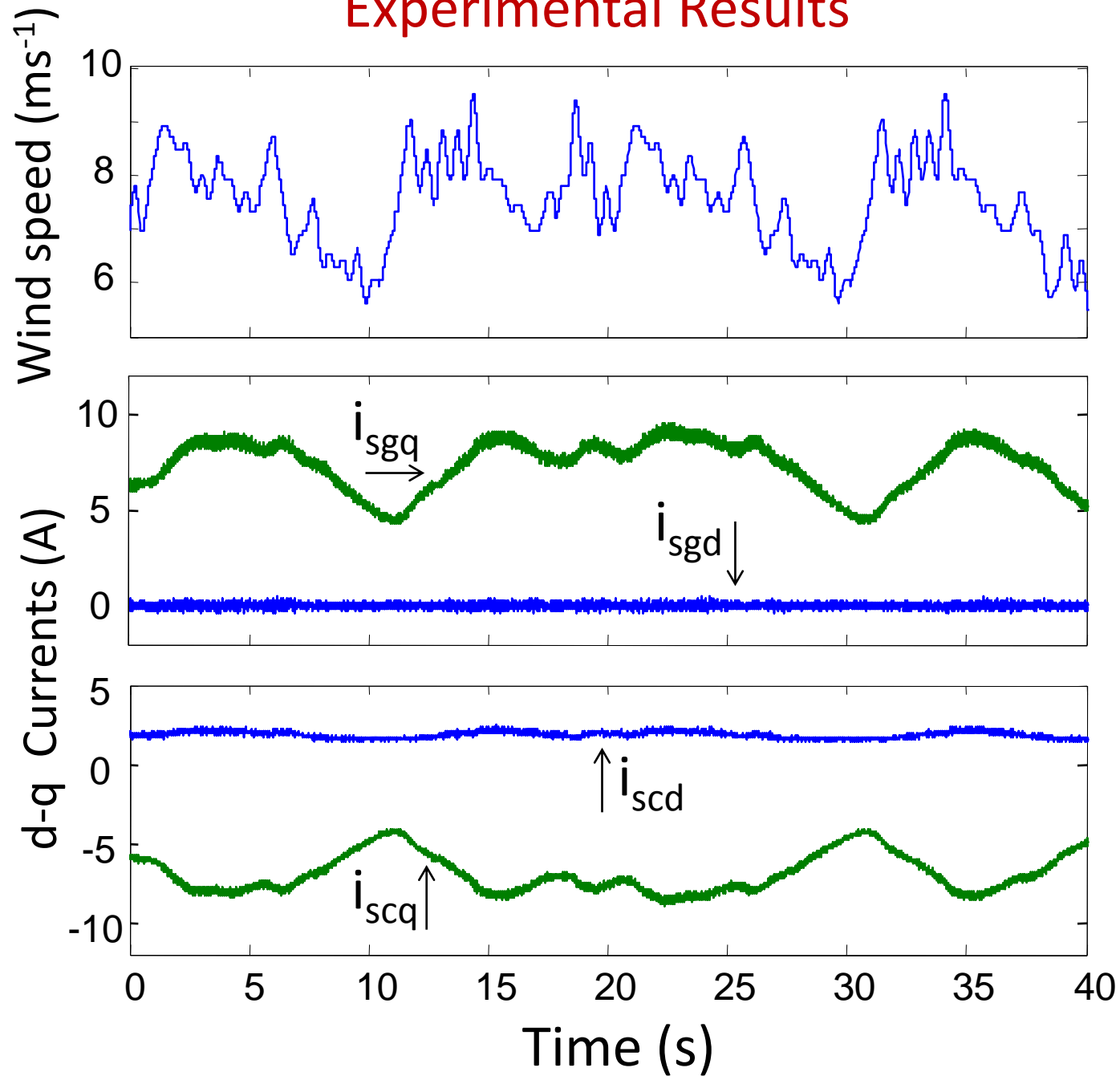
Experimental System



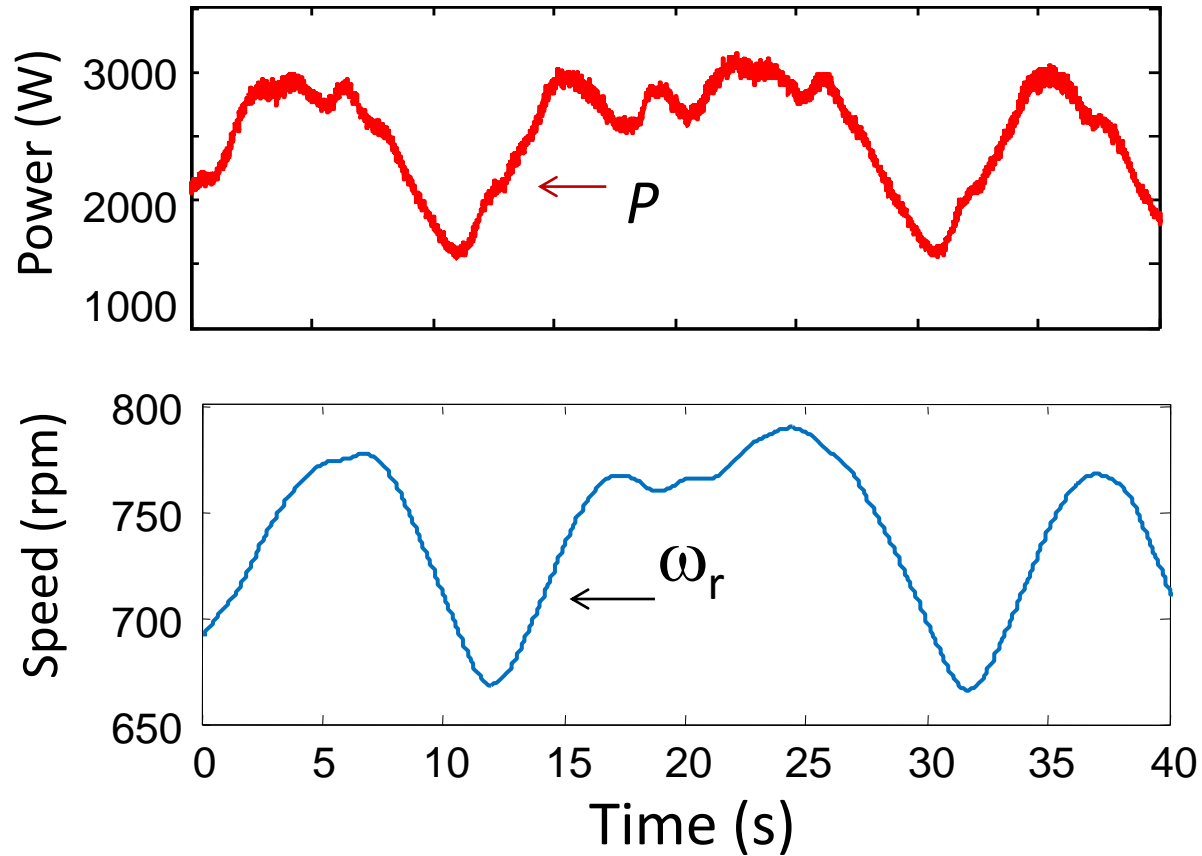
Experimental System



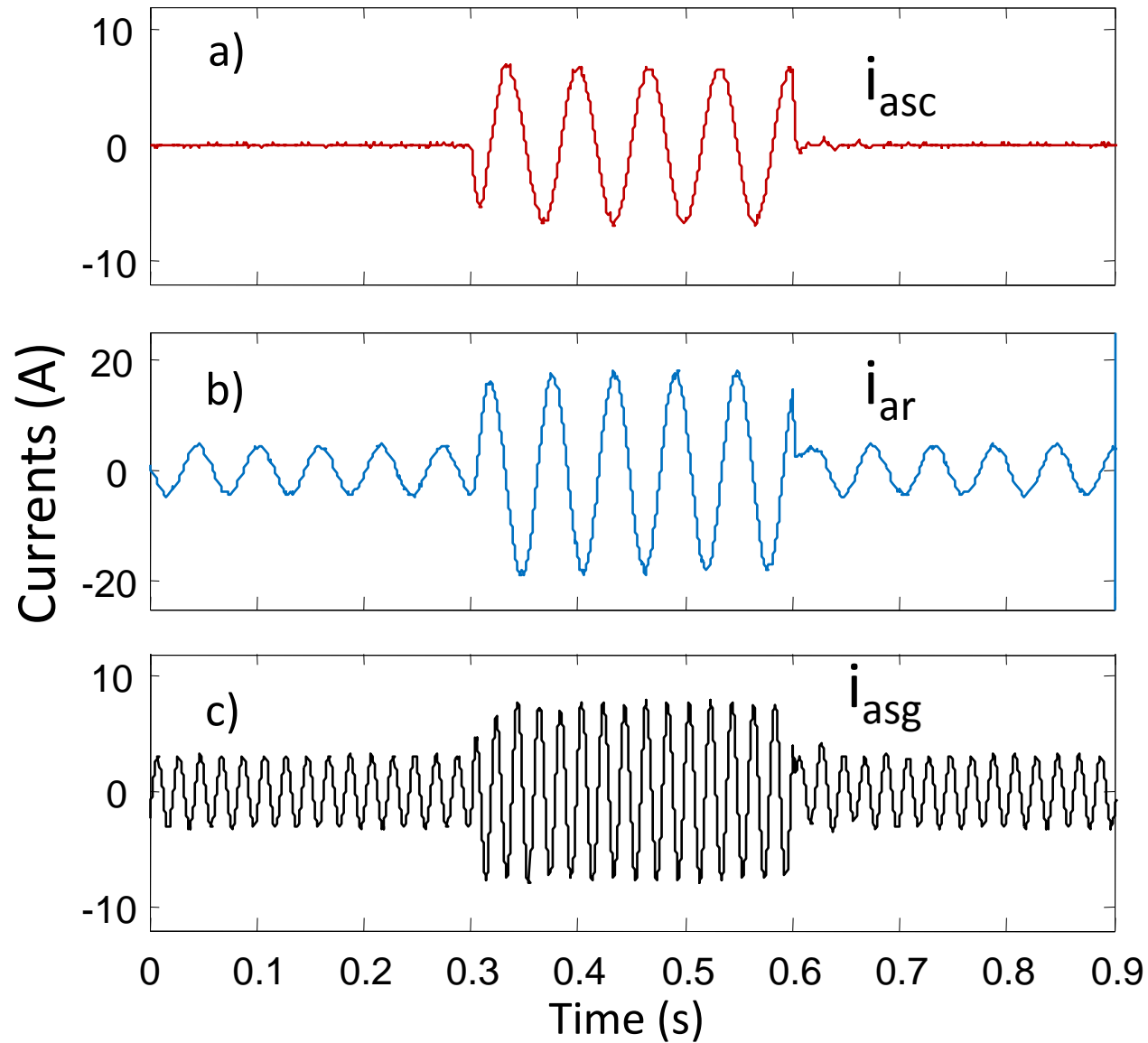
Experimental Results



Experimental Results



Experimental Results



Conclusions

- The BDFIG is an alternative to the conventional Doubly-Fed Generator in remote sites where maintenance is not simple to achieve.
- The simplified model proposed here can be used to design the control system. The simplifications arise from the fact that wind energy systems have slow dynamic due to the relatively large blade inertia.
- Experimental results have been obtained which confirm the performance of the proposed methodology.

Any question?