

## Input Signals (Ch. 5)

The quality of the estimated model depends on the choice of input signal.

Examples:

- Step function
- Pseudo-random binary sequences (PRBS)
- Autoregressive moving average process (ARMA)
- Sum of sinusoids.

Most often the input signal is characterized by its first and second moments:

$$\begin{cases} m = E[u(t)] \\ r(\tau) = E[(u(t) - m)(u(t) - m)^T] \end{cases}$$

and/or its spectral density:

$$\phi(\omega) = \frac{1}{2\pi} \sum_{\tau=-\infty}^{\infty} r(\tau) e^{-i\tau\omega}$$

**Rem.** for stationary signals

$$m = \frac{1}{N} \sum_{t=1}^N u(t)$$

# Pseudo-Random Binary Sequences (PRBS)

A PRBS  $(u(t))_t$  is a periodic, deterministic signal with white noise-like properties.

$$u(t) = \text{rem} \left( A(q^{-1})e(t), 2 \right)$$

## Properties

- The signal takes values  $\{0, 1\}$  in a fashion dictated by  $A$ .
- Spectral properties are determined by  $A(q)$  and in particular by the period length  $M = 2^n - 1$ .
- Deterministic sequence behaving as noise (reproducible).

# ARMA Process

$$A(q^{-1})y(t) = C(q^{-1})e(t)$$

where  $e(t)$  is white noise with  $E[e(t)] = 0$  and  $E[e(t)e(s)] = \lambda^2 \delta_{ts}$ .

## Properties

- The signal  $u(t)$  can be obtained by filtering  $e(t)$ .
- The filters  $(A, C)$  can be tuned to possess (almost) any frequency characteristics.
- The spectral density of an ARMA process  $y(t)$  is given as

$$\phi_y(\omega) = \frac{\lambda^2}{2\pi} \left| \frac{C(e^{i\omega})}{A(e^{i\omega})} \right|^2$$

# Persistent Excitation

In order to obtain a good estimate of a (parametric) model, the input signal has to be 'rich' enough so that all 'modes' of the system are excited.

An input is said to be persistently exciting (PE) if:

- The following limit exists for all  $\tau$

$$r_u(\tau) = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{t=1}^{N-\tau} u(t+\tau)u^T(t)$$

**Rem.**  $u(t)$  ergodic implies that for any  $t$

$$r_u(\tau) = E[u(t+\tau)u^T(t)]$$

- The matrix  $\mathbf{R}_u(n)$

$$\mathbf{R}_u = \begin{bmatrix} r_u(0) & r_u(1) & \dots & r_u(n-1) \\ r_u(1) & r_u(0) & \dots & \vdots \\ \vdots & & \ddots & \\ r_u(n-1) & \dots & & r_u(0) \end{bmatrix}$$

is positive (strictly) definite.

- Or,  $\det(\mathbf{R}_u(n)) \neq 0$ .
- Or  $u(t)$  is PE of order  $n$  if  $\phi_u(\omega) \neq 0$  on at least  $n$  points on the interval  $-\pi < \omega < \pi$ .

An input signal is PE of order  $2n$  can be used to consistently estimate parameters of a model of order  $\leq n$ .

- A step function that is PE of order 1
- A PRBS with period  $M$  is PE of order  $M$ .
- An ARMA process is PE of any finite order.
- A sum of  $m$  sinusoids is PE of order  $2M$  (if  $\omega_m \neq 0, -\pi, \pi$ )

Another important observation!

**A parametric model becomes more accurate in the frequency region where the input signal has a major part of its energy.**

A physical process is often of low frequency character → use low-pass filtered signal as input.