



$$\vec{r}' = R\hat{r}; \vec{\tau}' = R\dot{\theta}\hat{\theta}; \vec{\alpha}' = -R\ddot{\theta}\hat{r} + R\ddot{\theta}\hat{\theta}$$

$$\overset{\text{oo}}{\vec{R}} = -2R\Omega^2\hat{\phi}$$

$$\vec{\omega}_o = \Omega_o \hat{k} = \Omega_o (\sin\theta\hat{r} + \cos\theta\hat{\theta})$$

$$\overset{\text{oo}}{\vec{R}} = -2R\Omega_o^2 (\sin\theta\hat{\theta} - \cos\theta\hat{r})$$

$$\vec{F} = N_r\hat{r} + N_k\hat{k}' - mg(\sin\theta\hat{r} + \cos\theta\hat{\theta}) - kR\theta\hat{\theta}$$

Normal                      peso                      resorte

$$* \vec{\omega}_o \times (\vec{\omega}_o \times \vec{r}') = \underbrace{(\Omega_o \sin\theta\hat{r} + \Omega_o \cos\theta\hat{\theta})}_{\Omega_o \hat{k}} \times \underbrace{[(\Omega_o \sin\theta\hat{r} + \Omega_o \cos\theta\hat{\theta}) \times R\hat{r}]}_{-R\Omega_o \cos\theta\hat{k}'} = -R\Omega_o \cos\theta\hat{\phi}$$

$$= -R\Omega_o^2 \cos\theta(-\hat{\phi}) = R\Omega_o^2 \cos\theta(\sin\theta\hat{\theta} - \cos\theta\hat{r})$$

$$* 2\vec{\omega} \times \vec{\tau}' = 2(\Omega_o \sin\theta\hat{r} + \Omega_o \cos\theta\hat{\theta}) \times R\dot{\theta}\hat{\theta} = 2R\Omega_o \dot{\theta} \sin\theta\hat{k}'$$

$$* \vec{\omega} \times \vec{r}' = 0$$

Luego:

$$-mR\ddot{\theta}\hat{r} + mR\ddot{\theta}\hat{\theta} = N_r\hat{r} + N_k\hat{k}' - mg\sin\theta\hat{r} - mg\cos\theta\hat{\theta} - kR\theta\hat{\theta}$$

$$+ 2mR\Omega_o^2 \sin\theta\hat{\theta} - 2mR\Omega_o^2 \cos\theta\hat{r} - mR\Omega_o^2 \cos\theta \sin\theta\hat{\theta} + mR\Omega_o^2 \cos^2\theta\hat{r}$$

$$- 2mR\Omega_o \dot{\theta} \sin\theta\hat{k}'$$

$$\hat{1}) -MR\ddot{\theta}^2 = N_r - mg \sin \theta - 2MR\omega_0^2 \cos \theta + mR\omega_0^2 \cos^2 \theta$$

$$\hat{2}) MR\ddot{\theta}^2 = -mg \cos \theta - kR\theta + 2MR\omega_0^2 \sin \theta - mR\omega_0^2 \cos \theta \sin \theta$$

$$\hat{3}) 0 = N_k - 2mR\omega_0^2 \sin \theta$$

a) Para que esté en reposo en A ( $\theta = \pi/2$ ), debemos imponer que  $\ddot{\theta} = \dot{\theta} = 0$ , con  $\theta = \pi/2$ :

$$\Rightarrow 0 = -mg \cos(\pi/2) - \frac{kR\pi}{2} + 2mR\omega_0^2 \sin(\pi/2) - mR\omega_0^2 \cos(\pi/2) \sin(\pi/2)$$

$$\Rightarrow 2mR\omega_0^2 = \frac{kR\pi}{2} \Rightarrow \boxed{\omega_0^2 = \frac{k\pi}{4m}}$$

b)

$$\ddot{\theta} = -\frac{g}{R} \cos \theta - \frac{k}{m} \theta + 2\omega_0^2 \sin \theta - \omega_0^2 \cos \theta \sin \theta$$

$$\ddot{\theta} d\theta = \left[ -\frac{g}{R} \cos \theta - \frac{k}{m} \theta + 2\omega_0^2 \sin \theta - \omega_0^2 \cos \theta \sin \theta \right] d\theta$$

$$\frac{\partial \theta^2}{2} \Big|_{\theta_A}^0 = -\frac{g}{R} \sin \theta \Big|_{\theta_A}^0 - \frac{k}{m} \frac{\theta^2}{2} \Big|_{\theta_A}^0 + 2\omega_0^2 \cos \theta \Big|_{\theta_A}^0 + \omega_0^2 \frac{\cos^2 \theta}{2} \Big|_{\theta_A}^0$$

$$\theta_A: 2 \left[ -\frac{g}{R} - \frac{g}{R} \theta_A^2 - \frac{k}{m} \frac{\pi^2}{8} \right] + 2\omega_0^2 \theta_A^2 + \frac{\omega_0^2}{2} \pi^2 \theta_A^2 = 0$$

$$\Rightarrow \theta_A^2 = \frac{3k\pi^2}{4m} - \frac{2g}{R} - 5\omega_0^2$$

$$\frac{3k\pi^2}{4m} - \frac{2g}{R} > \omega_0^2$$

$$\frac{3k\pi^2}{4m}$$

$$\frac{3k\pi^2}{4m} - \frac{5k\pi}{4m} > 0$$

(c)

$$N_r = mg \sin\theta + 2MR\omega_0^2 \cos\theta + MR\omega_0^2 \cos^2\theta - MR\dot{\theta}^2$$

$$N_k = 2MR\omega_0 \dot{\theta} \sin\theta$$

A:  $\theta = \pi/2 \Rightarrow N_r(\theta=\pi/2) = mg - MR \left[ \frac{3k\pi^2}{4m} - \frac{2g}{R} - 5\omega_0^2 \right]$

$$N_r(\pi/2) = 3mg + 5MR\omega_0^2 - \frac{3kR\pi^2}{4}$$

$$N_k = 2MR\omega_0 \left[ \frac{3k\pi^2}{4m} - \frac{2g}{R} - 5\omega_0^2 \right]^{1/2}$$

B:  $\theta = \pi, \dot{\theta} = 0$  (condición de (b)):

$$N_r(\pi) = 3MR\omega_0^2$$

$$N_k = 0$$

(d)

en A:  $\vec{N}_A = \left( 3mg + 5MR\omega_0^2 - \frac{3kR\pi^2}{4} \right) \hat{r} + 2MR\omega_0^2 \left[ \frac{3k\pi^2}{4m} - \frac{2g}{R} - 5\omega_0^2 \right]^{1/2} \hat{k}$

en B:

$$\vec{N}_B = 3MR\omega_0^2 \hat{r}$$