



a) Calculamos la capacitancia $C = \frac{\epsilon \cdot A}{h}$ (0,5 pts) Luego circuitalmente: $V(t)$

LVR $\Rightarrow V(t) = R \cdot I + V_C(t)$ Pero $I = I_C = C \frac{dV_C}{dt} \Rightarrow V(t) = RC \frac{dV_C}{dt} + V_C$

$\Rightarrow \otimes \frac{dV_C}{dt} + \frac{V_C}{RC} = \frac{V(t)}{RC}$ Sol homogénea: $V_C(t) = A \cdot e^{-t/RC}$ (0,5 pts)

Sol particular: proponemos una senoide: $V_C(t) = B \cos(\omega t) + D \sin(\omega t)$ en $\otimes$:

$$-\omega B \sin(\omega t) + \omega D \cos(\omega t) + \frac{B \cos(\omega t) + D \sin(\omega t)}{RC} = \frac{V_0 \cos(\omega t)}{RC}$$

$\omega t \in \{0, \pi, 2\pi, \dots\} \Rightarrow \omega D + \frac{B}{RC} = V_0$

$\omega t \in \{\pi/2, 3\pi/2, \dots\} \Rightarrow -\omega B + \frac{D}{RC} = 0 \Rightarrow D = \omega B RC \Rightarrow \omega^2 B RC + \frac{B}{RC} = V_0$

$\Rightarrow B = \frac{V_0}{\omega^2 RC + \frac{1}{RC}} = \frac{RC V_0}{1 + (\omega RC)^2} = B \Rightarrow D = \frac{\omega RC^2 V_0}{1 + (\omega RC)^2}$

$\Rightarrow V_{Cp}(t) = \frac{V_0 RC}{1 + (\omega RC)^2} [\cos(\omega t) + \omega RC \sin(\omega t)]$ (1,5 pts)

$\Rightarrow V_C(t) = A e^{-t/RC} + \frac{V_0 RC}{1 + (\omega RC)^2} [\cos(\omega t) + \omega RC \sin(\omega t)]$

En $t=0$: $Q = Q_0 \Rightarrow V_0 = Q_0/C \Rightarrow V_C(t=0) = A + \frac{V_0 RC}{1 + (\omega RC)^2} = \frac{Q_0}{C}$

$\Rightarrow A = \frac{Q_0}{C} - \frac{RC V_0}{1 + (\omega RC)^2} \Rightarrow V_C(t) = \left(\frac{Q_0}{C} - \frac{RC V_0}{1 + (\omega RC)^2} \right) e^{-t/RC} + \frac{V_0 RC}{1 + (\omega RC)^2} [\cos(\omega t) + \omega RC \sin(\omega t)]$ (0,5 pts)

$\Rightarrow I = C \cdot \frac{dV_C(t)}{dt} = \left[\left(\frac{Q_0}{C} - \frac{RC V_0}{1 + (\omega RC)^2} \right) e^{-t/RC} + \frac{V_0 RC \omega}{1 + (\omega RC)^2} [-\sin(\omega t) + \omega RC \cos(\omega t)] \right] = I$

(0,5 pts)

$$b) \text{ Ec Laplace } \Rightarrow \nabla^2 V = 0 \Rightarrow \frac{\partial^2 V}{\partial z^2} = 0 \Rightarrow V(z) = A + Bz$$

$$C. \& B: V(0) = 0, V(h) = V_0(t) \Rightarrow V(z, t) = \frac{V_0(t) \cdot z}{h}$$

$$\Rightarrow \vec{E} = -\nabla V = -\frac{\partial V}{\partial z} \hat{k} = -\frac{V_0(t)}{h} \hat{k} \Rightarrow \vec{D} = \frac{\epsilon V_0(t)}{h} \hat{k}$$

$$\Rightarrow \frac{d\vec{D}}{dt} = -\frac{\epsilon}{h} \cdot \frac{\partial V_0(t)}{\partial t} = -\frac{\epsilon}{h} \cdot (I(t)/C) \Rightarrow \boxed{\vec{J}_D = \frac{d\vec{D}}{dt} = -\frac{\epsilon}{h \cdot C} I(t)}$$

(1,5 pts)