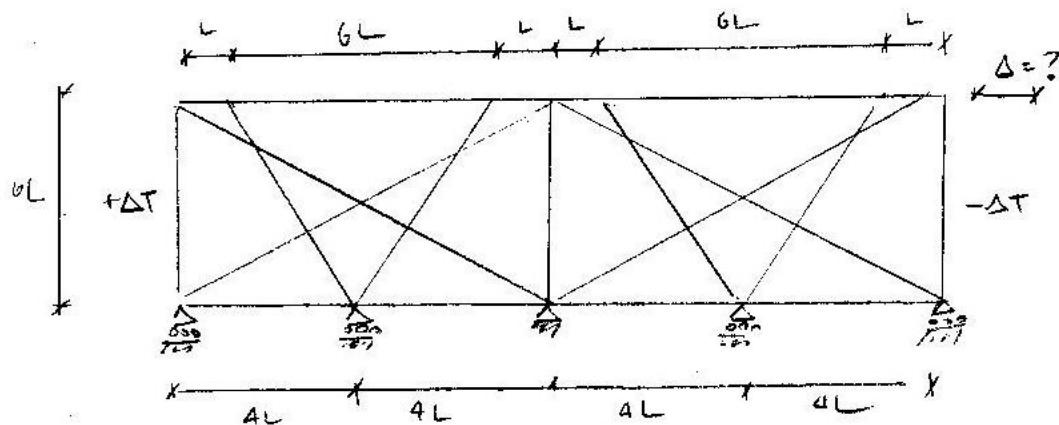


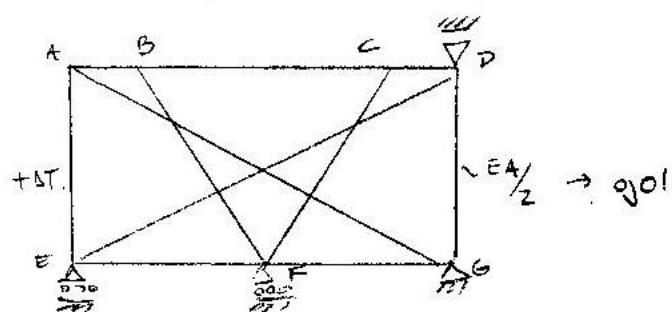
P1 PARA LA ESTRUCTURA DE LA FIG. 1 SE PIDE DETERMINAR:

- GIE
- Reacciones
- Diagramas de esfuerzos
- Desplazamiento horizontal Δ .



Solución: Aplicando simetría

Simetría planar, acciones antisimétricas.

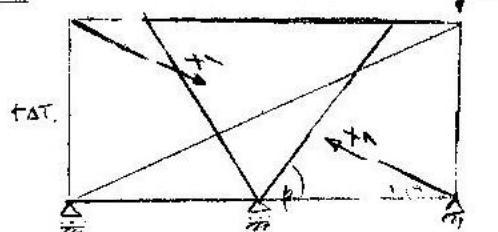


GIE estructura inicial = 3

GIE estructura resultante = 2 //

Wegs, liberando NAO y VD.

EIF

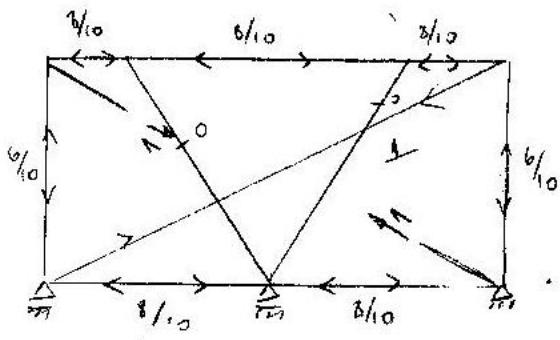


$$\sin(\alpha) = \frac{6}{10}, \cos(\alpha) = \frac{8}{10}$$

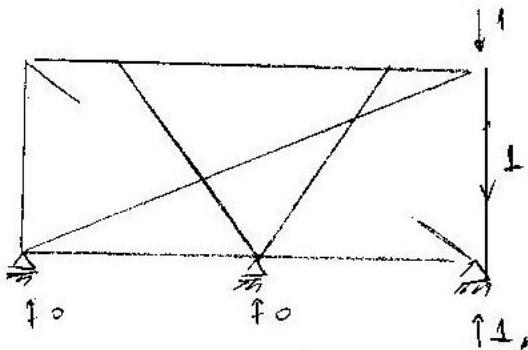
$$\sin(\beta) = \frac{6}{\sqrt{10}}, \cos \beta = \frac{8}{\sqrt{10}}$$

$$\cdot) N_{AB} = 1, \epsilon_2 = 2$$

(2)



$$\cdot) x_2 = 1, N_{AB} = 0$$



flexibilidad

$$f = [f] \{x\} + r(\Delta T)$$

$$\sum K_i \frac{\Delta L_i}{EA}$$

$$f_{11} = -\frac{8}{10} \frac{8}{10} (2 \cdot L + 6L + 2 \cdot 4L) / EA + 2 \cdot 1 \cdot 1 \cdot 10L / EA + \frac{6 \cdot 6}{10} \frac{6L}{EA} + \frac{6 \cdot 6}{10} \frac{6L}{EA}$$

$$f_{11} = (10, 24 + 20 + 2, 16 + 4, 32) \frac{L}{EA} \Rightarrow f_{11} = 36,72L / EA$$

$$f_{12} = \frac{6}{10} \cdot 1 \frac{6L}{EA/2} = \frac{12L}{10EA} = f_{21} \Rightarrow f_{21} = f_{12} = 7,2L / EA$$

$$f_{22} = 1^2 \frac{6L}{EA/2} \Rightarrow f_{22} = 12L / EA$$

(3)

$$\Gamma_1(\Delta T) = \bar{C}_N \cdot \varepsilon \cdot L = -\frac{6}{10} \cdot \alpha \Delta T \cdot 6L = -\frac{36}{10} \alpha \Delta T L = -\frac{18}{5} \alpha \Delta T L // = -36 \alpha \Delta T L$$

$$\Gamma_2(\Delta T) = \bar{C}_N \cdot \varepsilon \cdot L = 0 //$$

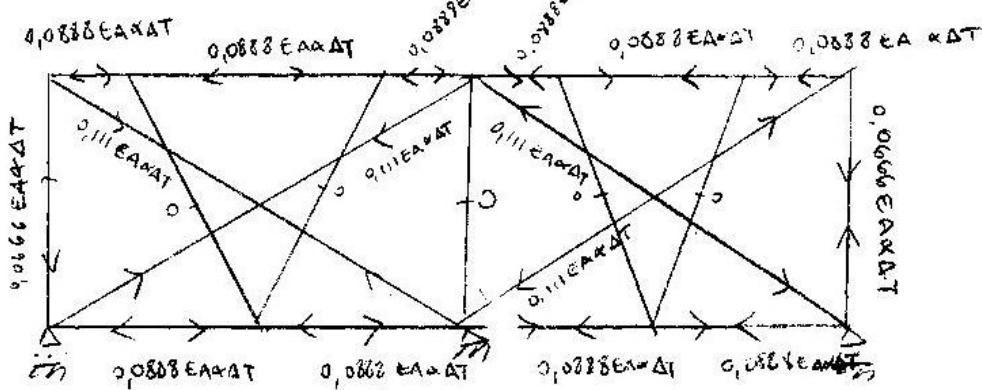
$$\Rightarrow -\frac{L}{EA} \begin{bmatrix} 36,72 & 7,2 \\ 7,2 & 12 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} -3,6 \alpha \Delta T L \\ 0 \end{pmatrix} = 0$$

$$\Rightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \frac{EA}{L} \begin{bmatrix} 36,72 & 7,2 \\ 7,2 & 12 \end{bmatrix}^{-1} \begin{pmatrix} 3,6 \alpha \Delta T L \\ 0 \end{pmatrix}$$

$$\Rightarrow x_1 = 0,111 EA \alpha \Delta T //$$

$$x_2 = -0,067 EA \alpha \Delta T //$$

Luego, los esfuerzos servirán (por la antisimetría de las cargas)

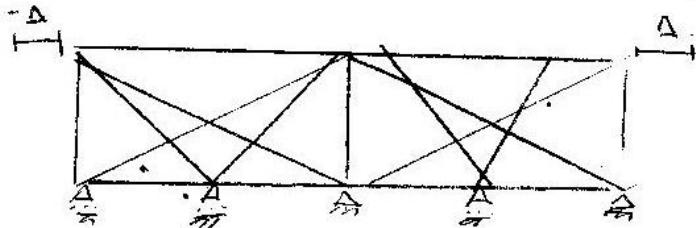


$$\frac{6}{10} \cdot 0,111 = 0,0666$$

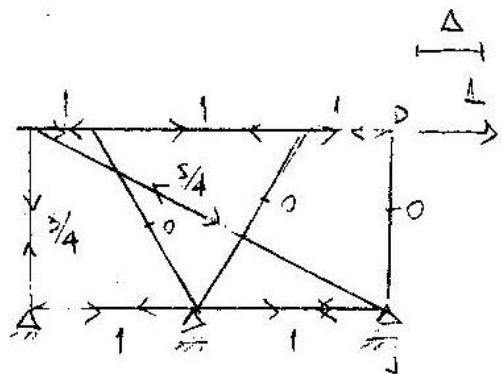
$$\frac{6}{10} \cdot 0,111 = 0,0666.$$

Desplazamiento Δ

(4)



EN LA EIF, por simetría

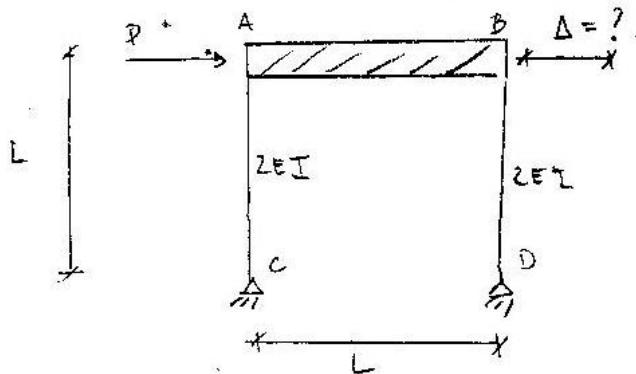


$$\text{PTV} \Rightarrow 1 \cdot \Delta = 2 \cdot 1,0082 \frac{\text{EA}}{\text{EK}} \alpha \Delta T \cdot \left(\frac{8L}{\text{EK}} \right) + \frac{5}{4} \cdot 0,111 \frac{\text{EA}}{\text{EK}} \alpha \Delta T \frac{10L}{\text{EA}}$$

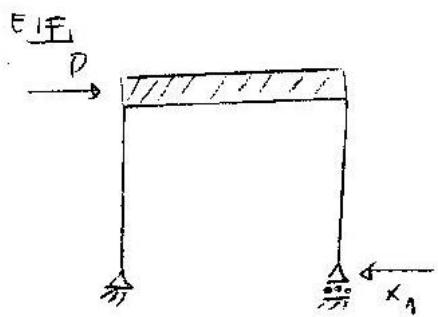
$$-1 \Delta = 2,8083 \alpha \Delta T L //$$

(5)

PzJ (a) En el marco de la figura, se aplica una carga lateral P en la viga. Determine GIE, reacciones, diagramas de esfuerzos y el desplazamiento horizontal Δ .

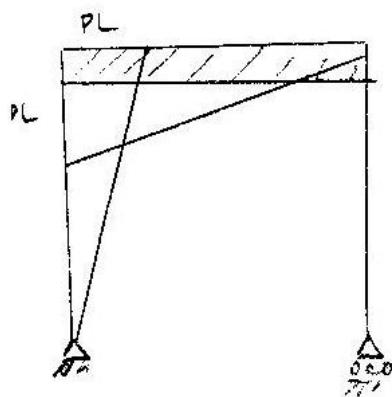
Soluc

$$GIE = 1$$

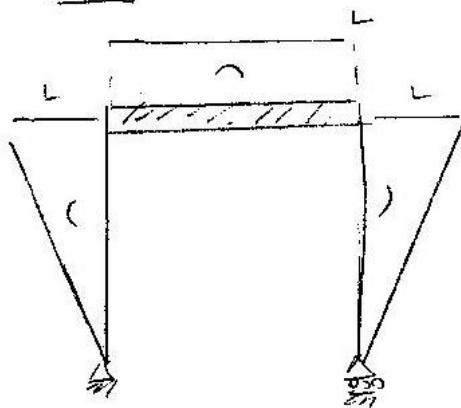


(desplazamiento inicial nulo)

$$\delta_1 = r_1(P) + r_1(x_1)$$

Pj

$$x_1 = \pm$$



(6)

$$f_{11} = 2 \cdot \frac{L}{2EI} \cdot \frac{L}{2EI} + \boxed{\frac{L}{2EI} \cdot \frac{L}{2EI}}^0$$

$$\Rightarrow f_{11} = 2 \cdot \frac{1}{3} \cdot L^2 \cdot \frac{L}{2EI} \quad ; \quad \boxed{f_{11} = \frac{L^3}{3EI}}$$

$$r_1(\rho) = \frac{PL}{2EI} \cdot \frac{L}{2EI}$$

$$\Rightarrow r_1(\rho) = -\frac{1}{3} PL \cdot \frac{L}{2EI} \quad ; \quad r_1(\rho) = -\frac{\rho L^3}{6EI}$$

De la otra parte,

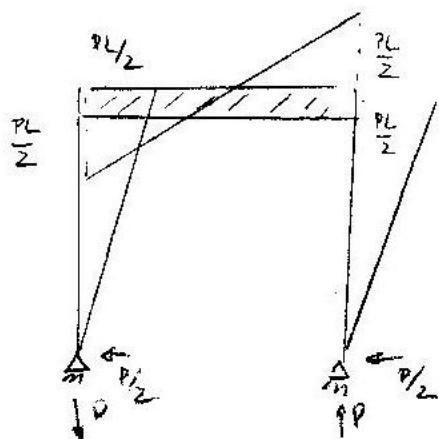
$$\Rightarrow f_{11} x_1 + r_1(\rho) = 0$$

Reemplazando,

$$\Rightarrow y_1 = \frac{PL^3}{6EI} \cdot \frac{L^3}{3EI} \Rightarrow \boxed{y_1 = \frac{\rho L}{2}}$$

Finalmente,

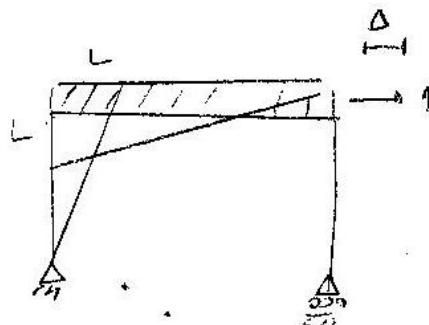
Diagrama de momentos y reacciones (N y Q propuestos)



(7)

Desplazamientos Δ

EIF

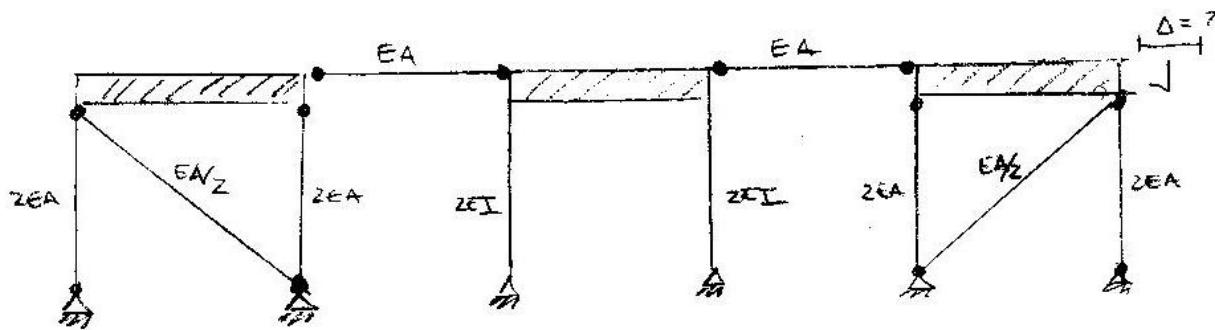


$$\Rightarrow \perp \Delta = \frac{L}{2} \cdot \frac{\frac{PL}{2}}{2EI}$$

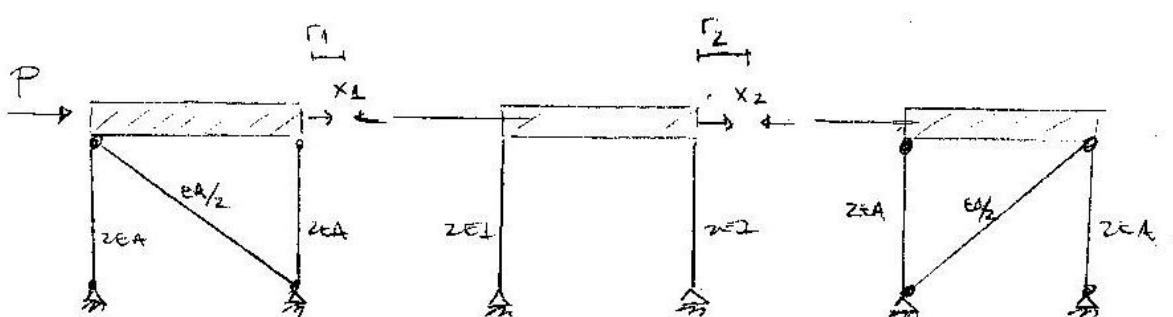
$$\Delta = \frac{1}{3} \cdot L \cdot \frac{PL}{2} \cdot \frac{L}{2EI}$$

$$\boxed{\Delta = \frac{PL^3}{12EI}}$$

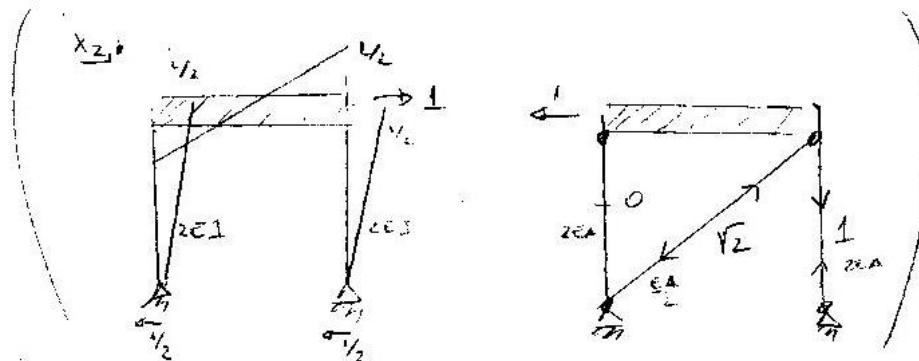
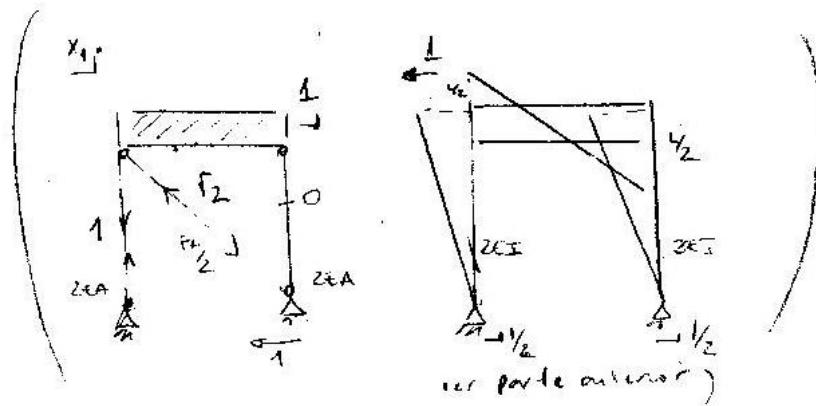
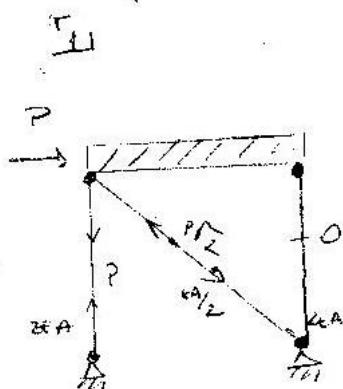
- (b) Utilice el resultado de (a) para resolver la estructura siguiente y obtener el desplazamiento del punto J. Consideré que $EA = EI/L$

Solución

EIF



$$r = r_1(x_1) + r_2(x_2) + r_3(\theta) \quad (8)$$



$$r_1(x_1) = \frac{1^2}{2EA} x_1 + \frac{(r_2)^2}{\frac{EI}{2}} \cdot x_1 + 2 \cdot \frac{1}{3} \cdot \frac{L}{2} \cdot \frac{L}{2} \cdot \frac{L}{2} x_1 + 2 \cdot \frac{1}{3} \cdot \frac{L}{2} \cdot \frac{L}{2} \cdot \frac{L}{2} x_1$$

$$+ \underbrace{\frac{x_1 L}{EA}}_{B121a}$$

$$= \left(\frac{L}{2EA} + \frac{4r_2 L}{EA} + \frac{L^3}{12EI} + \frac{L}{EA} \right) x_1 = \frac{L^3}{EI} \left(\frac{1}{2} + 4r_2 + \frac{1}{12} + 1 \right) x_1$$

$$r_2(x_1) = -2 \cdot \frac{1}{3} \cdot \frac{L}{2} \cdot \frac{L}{2} \cdot \frac{L}{2} x_1$$

$$= -\frac{L^3}{12EI} x_1$$

(9)

$$r_1(x_2) = -2 \cdot \frac{1}{3} \cdot \frac{L}{2} \cdot \frac{L}{2} \cdot \frac{L}{2EI} \cdot x_2 \\ = -\frac{L^3}{12EI} x_2$$

$$r_2(x_2) = \frac{1^2}{2EA} x_2 + \frac{(r_2)^2 \cdot r_2 L}{EI/2} x_2 + 2 \cdot \frac{1}{3} \cdot \frac{L}{2} \cdot \frac{L}{2} \cdot \frac{L}{2EI} + \frac{x_L \cdot L}{EA} \\ = \left(\frac{L}{2EA} + \frac{4r_2 L}{EI} + \frac{L^3}{12EI} + \frac{L}{EA} \right) x_2 = \frac{L^3}{EI} \left(\frac{1}{2} + 4r_2 + \frac{1}{12} + 1 \right) x_2$$

$$r_1(\varphi) = +P \frac{1}{2EA} L + +P \frac{r_2 \cdot r_2 \cdot L \cdot r_2}{EI/2} = +P \left(\frac{1}{2} + 4r_2 \right) \frac{L^3}{EI}$$

$$r_2(\varphi) = \emptyset$$

Wegs,

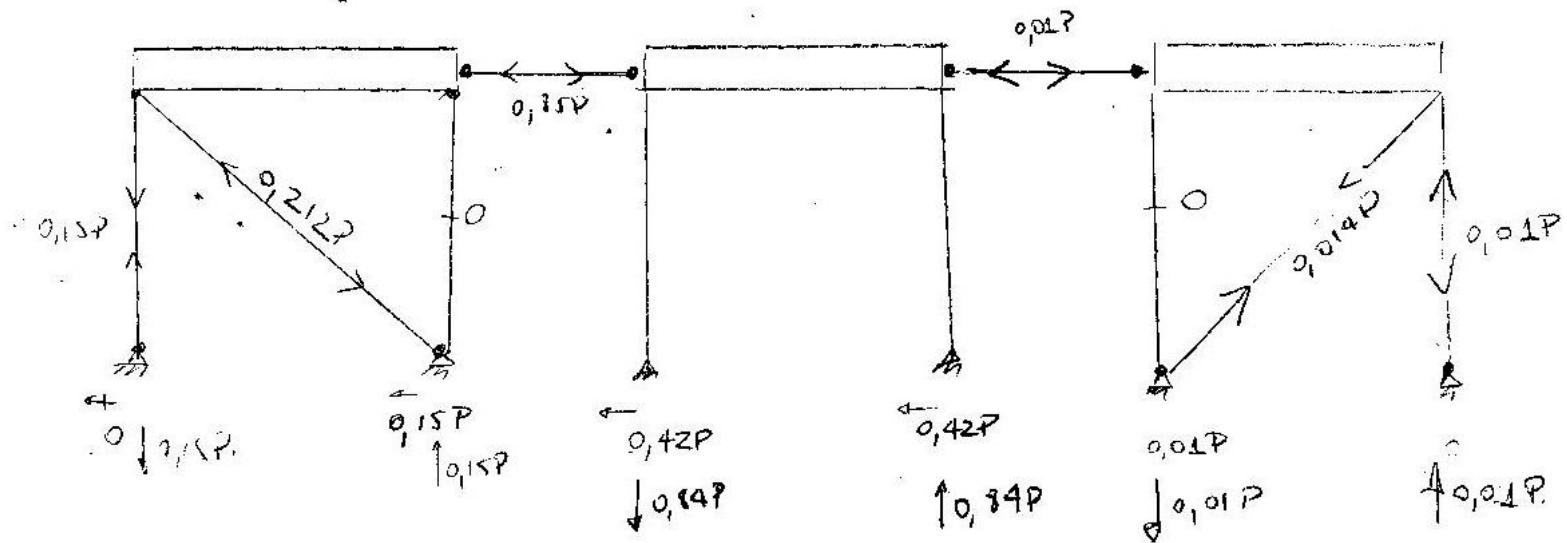
$$\frac{1}{EI} \begin{bmatrix} (4r_2 + 19/2) & -1/2 \\ -1/2 & (4r_2 + 19/2) \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \frac{L^3}{EI} \begin{pmatrix} -P(1/2 + 4r_2) \\ 0 \end{pmatrix}$$

$$x_1 = -0,85P$$

$$x_2 = -0,01P$$

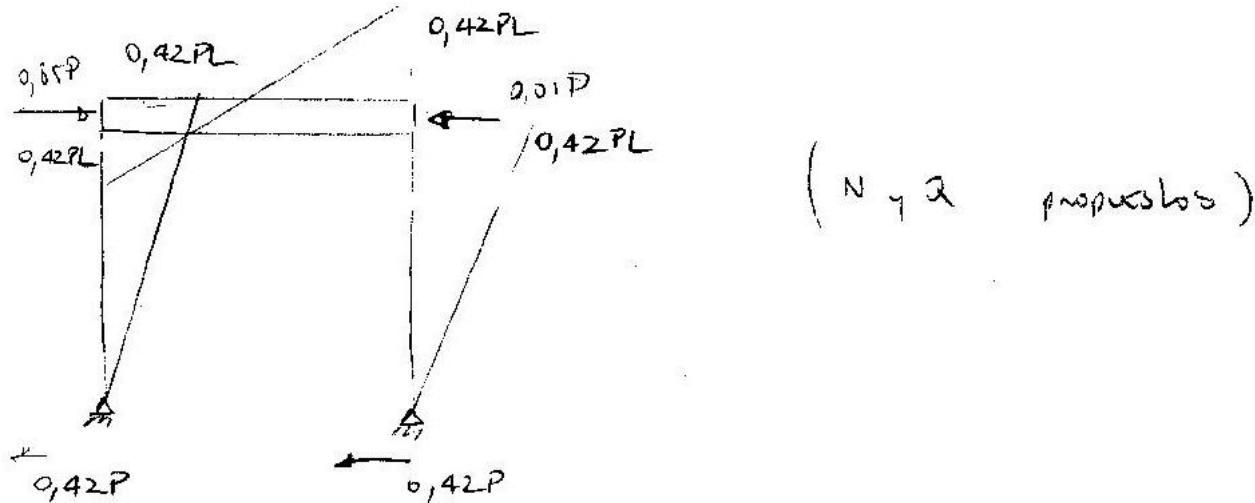
Luego, siendo los efectos de x_1 y x_2 y P

(10)



DIAGRAMAS EN SECCIÓN CENTRAL

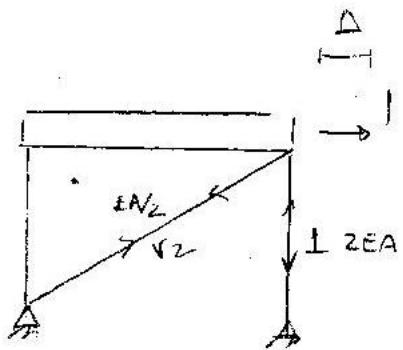
nx)



(11)

Desplazamiento Δ

EN LA EIF



$$1 \times \Delta = \frac{F_2 + 0,014P}{E_A/2} r_{2L} + \frac{1 + 0,01PL}{2E_A}$$

$$\Delta = +0,061PL/E_A$$