

IQ57A- Dinámica y Control de Procesos
Control- Semestre Primavera 2008

Profesor: Cristian Salgado

Problema 3

(a) Obtenga el modelo linealizado del sistema

Ecuaciones del sistema:

$$\frac{d\xi_1}{dt} = 10(6 - \xi_1) - 2\xi_1\sqrt{\xi_2} \quad (1)$$

$$\frac{d\xi_2}{dt} = 80\mu - 10\xi_2 \quad (2)$$

$$\frac{d\xi_3}{dt} = \xi_1\sqrt{\xi_2} + 0,1\xi_2 - 10\xi_3 \quad (3)$$

$$\frac{d\xi_4}{dt} = 100\xi_1\sqrt{\xi_2} - 10\xi_4 \quad (4)$$

Usando la expansión de Taylor:

$$f(X_1, X_2) = f(X_1^{ee}, X_2^{ee}) + \frac{\partial f(X_1^{ee}, X_2^{ee})}{\partial X_1}(X_1 - X_1^{ee}) + \frac{\partial f(X_1^{ee}, X_2^{ee})}{\partial X_2}(X_2 - X_2^{ee}) \quad (5)$$

Se tiene lo siguiente:

$$\xi_1\sqrt{\xi_2} = \xi_1^{ee}\sqrt{\xi_2^{ee}} + \sqrt{\xi_2^{ee}}(\xi_1 - \xi_1^{ee}) + \frac{\xi_1^{ee}}{2\sqrt{\xi_2^{ee}}}(\xi_2 - \xi_2^{ee}) \quad (5.1)$$

Llamando:

$$\alpha = \sqrt{\xi_2^{ee}}$$
$$\beta = \frac{\xi_1^{ee}}{2\sqrt{\xi_2^{ee}}}$$

La linealización queda:

$$\xi_1\sqrt{\xi_2} = \alpha\xi_1 + \beta(\xi_2 - \alpha) \quad (5.2)$$

Reemplazando en las ecuaciones se tiene:

$$\frac{d\xi_1}{dt} = 10(6 - \xi_1) - 2[\alpha\xi_1 + \beta(\xi_2 - \alpha)] \quad (1.1)$$

$$\frac{d\xi_2}{dt} = 80\mu - 10\xi_2 \quad (2.1)$$

$$\frac{d\xi_3}{dt} = \alpha\xi_1 + \beta(\xi_2 - \alpha) + 0,1\xi_2 - 10\xi_3 \quad (3.1)$$

$$\frac{d\xi_4}{dt} = 100[\alpha\xi_1 + \beta(\xi_2 - \alpha)] - 10\xi_4 \quad (4.1)$$

Definiendo las siguientes variables de desviación:

$$\xi'_i = \xi_i - \xi_i^{ee}$$
$$\mu' = \mu - u^{ee}$$

Las ecuaciones quedan:

$$\frac{d\xi'_1}{dt} = -10\xi'_1 - 2[\alpha\xi'_1 + \beta\xi'_2] = -\xi'_1(10 + 2\alpha) - 2\beta\xi'_2 \quad (1.3)$$

$$\frac{d\xi'_2}{dt} = 80\mu' - 10\xi'_2 \quad (2.3)$$

$$\frac{d\xi'_3}{dt} = \alpha\xi'_1 + \beta\xi'_2 + 0,1\xi'_2 - 10\xi'_3 = \alpha\xi'_1 + (\beta + 0,1)\xi'_2 - 10\xi'_3 \quad (3.3)$$

$$\frac{d\xi'_4}{dt} = 100[\alpha\xi'_1 + \beta\xi'_2] - 10\xi'_4 \quad (4.3)$$

Aplicando la transformada de Laplace:

$$s\overline{\xi'_1} = -\overline{\xi'_1}(10 + 2\alpha) - 2\beta\overline{\xi'_2} \quad (1.4)$$

$$s\overline{\xi'_2} = 80\overline{\mu'} - 10\overline{\xi'_2} \quad (2.4)$$

$$s\overline{\xi'_3} = \alpha\overline{\xi'_1} + (\beta + 0,1)\overline{\xi'_2} - 10\overline{\xi'_3} \quad (3.4)$$

$$s\overline{\xi'_4} = 100[\alpha\overline{\xi'_1} + \beta\overline{\xi'_2}] - 10\overline{\xi'_4} \quad (4.4)$$

De (1.4)

$$G_{12} = \frac{\overline{\xi'_1}}{\overline{\xi'_2}} = \frac{-2\beta / (10+2\alpha)}{s / (10+2\alpha) + 1} \quad (1.5)$$

De (2.4)

$$G_{\mu 2} = \frac{\overline{\xi'_2}}{\overline{\mu'}} = \frac{8}{0,1s+1} \quad (2.5)$$

De (3.4)

$$\overline{\xi'_3} = \frac{\alpha/10}{0,1s+1} \overline{\xi'_1} + \frac{(\beta+0,1)/10}{0,1s+1} \overline{\xi'_2}$$

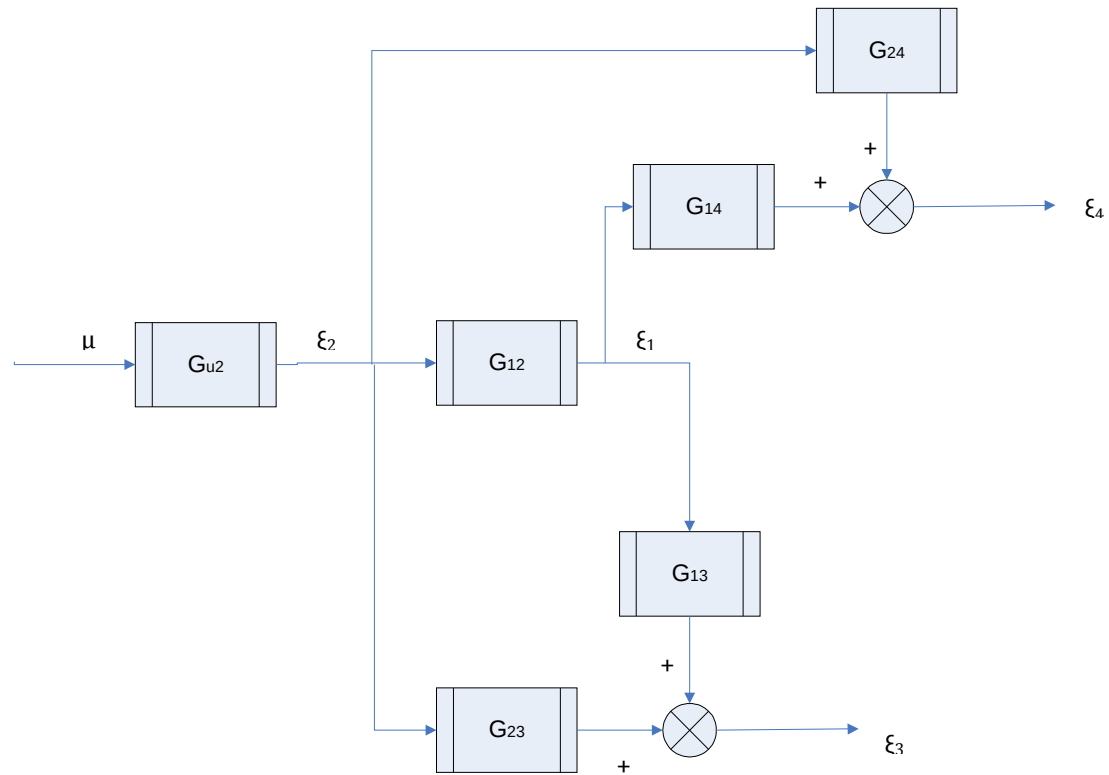
$$\overline{\xi'_3} = G_{13}\overline{\xi'_1} + G_{23}\overline{\xi'_2} \quad (3.5)$$

De (4.4)

$$\overline{\xi'_4} = \frac{10\alpha}{0,1s+1} \overline{\xi'_1} + \frac{10\beta}{0,1s+1} \overline{\xi'_2}$$

$$\overline{\xi'_4} = G_{14}\overline{\xi'_1} + G_{24}\overline{\xi'_2} \quad (4.5)$$

b) Dibuje un diagrama de bloques del sistema completo indicando las variables de entrada y salida



c) Usando el modelo linealizado encuentre la función de transferencia entre $\bar{\mu}'(s)$ y $\bar{\xi}'_3(s)$

De(1.5) (2.5) (3.5):

$$\bar{\xi}'_3 = G_{13}\bar{\xi}'_1 + G_{23}\bar{\xi}'_2$$

$$G_{\mu 2} = \frac{\bar{\xi}'_2}{\bar{\mu}} \rightarrow \bar{\xi}'_2 = G_{\mu 2}\bar{\mu}$$

$$G_{12} = \frac{\bar{\xi}'_1}{\bar{\xi}'_2} \rightarrow \bar{\xi}'_1 = G_{12}\bar{\xi}'_2$$

Reemplazando

$$\bar{\xi}'_3 = G_{13}G_{12}\bar{\xi}'_2 + G_{23}\bar{\xi}'_2 = (G_{13}G_{12} + G_{23})\bar{\xi}'_2 = (G_{13}G_{12} + G_{23})G_{\mu 2}\bar{\mu}$$

$$\frac{\bar{\xi}'_3}{\bar{\mu}} = \left(\frac{\alpha/10}{0,1s + 1} * \frac{-2\beta/(10 + 2\alpha)}{s/(10 + 2\alpha) + 1} + \frac{(\beta + 0,1)/10}{0,1s + 1} \right) * \frac{8}{0,1s + 1}$$