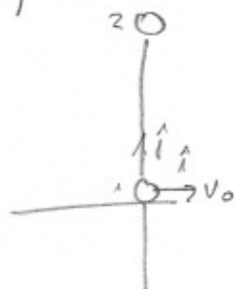
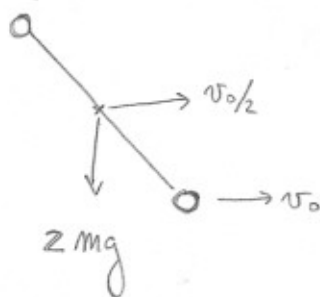


P1) a)



$$\vec{v}_{OCH} = \frac{m v_0 \hat{i} + m \cdot 0}{2m} = \frac{v_0}{2} \hat{i}$$

DCL



$$\hat{i}) \quad 0 = 2m \ddot{x}_{CH} = 0$$

$$\hat{j}) \quad -2mg = 2m \ddot{y}_{CH}$$

$$\ddot{y}_{CH} = -g$$

$$\boxed{\dot{y}_{CH} = -gt}$$

Se tiene además que

$$\vec{\tau}_{CH} = 0 \Rightarrow I_{CH} \ddot{\theta} = 0$$

$$\Rightarrow \ddot{\theta} = 0$$

$$l_{CH} = ct_0$$

Además:

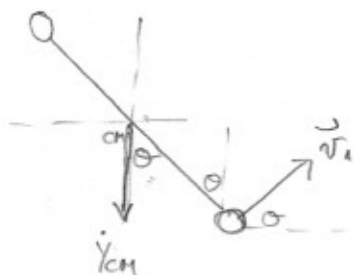
$$\vec{l}_{O_{CH}} = m \frac{L}{2} v_0 \hat{i}$$

$$\vec{l}_{CH} = \left(m \frac{L}{2} \vec{v}_1 + m \frac{L}{2} \vec{v}_2 \right) \hat{i}$$

$$v_1 = v_2 = \frac{L}{2} \dot{\theta}$$

$$\Rightarrow v_0 = L \dot{\theta} \Rightarrow \dot{\theta} = \frac{v_0}{L} \Rightarrow \theta(t) = \frac{v_0}{L} t$$

b) La velocidad vertical será



$$\dot{y}_1(t) = -gt + \frac{L}{2} \dot{\theta} \sin \theta$$

$$\dot{y}_1(t) = -gt + \frac{v_0}{2} \sin\left(\frac{v_0}{L} t\right)$$

$$\dot{y}_1 > 0 \Rightarrow gt < \frac{v_0}{2} \sin\left(\frac{v_0}{L} t\right)$$

$$\Rightarrow \sin\left(\frac{v_0}{L} t\right) \geq \frac{2gt}{v_0}$$

c)



$$\vec{a}_0 = -g \hat{j}$$

$$\vec{a}' = -\frac{L}{2} \ddot{\theta} \hat{s}$$

$$\vec{F} = -T \hat{s} - mg \cos \theta \hat{s} + mg \sin \theta \hat{\theta}$$



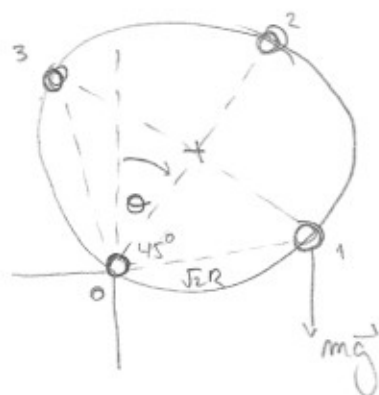
$$\hat{j} = \hat{s} \cos \theta - \hat{\theta} \sin \theta$$

$$\vec{a}_0 = -g \cos \theta \hat{s} + g \sin \theta \hat{\theta}$$

$$-T - mg \cos \theta = -mg \cos \theta - \frac{mL}{2} \ddot{\theta}$$

$$T = \frac{mL}{2} \ddot{\theta} \Rightarrow T = m \frac{v_0^2}{2L}$$

P2



$$\vec{r}_1 = \sqrt{2}R \sin(\theta + 45^\circ) mg \hat{k}$$

$$\vec{r}_2 = 2R \sin \theta mg \hat{k}$$

$$\vec{r}_3 = -\sqrt{2}R \sin(45^\circ - \theta) mg \hat{k}$$

$$\vec{L}_0 = (m r_1^2 \dot{\theta} + m r_2^2 \dot{\theta} + m r_3^2 \dot{\theta}) \hat{k}$$

$$= m (2R^2 + 4R^2 + 2R^2) \dot{\theta} \hat{k}$$

$$\vec{L}_0 = 8mR^2 \dot{\theta} \hat{k}$$

$$\vec{L}_0 = 8mR^2 \dot{\theta} \hat{k}$$

$$\sin(\theta + 45^\circ) = \sin \theta \cos 45^\circ + \cos \theta \sin 45^\circ = \frac{\sin \theta + \cos \theta}{\sqrt{2}}$$

$$\sin(45^\circ - \theta) = \sin \theta \cos 45^\circ - \cos \theta \sin 45^\circ = \frac{-\sin \theta + \cos \theta}{\sqrt{2}}$$

$$\Rightarrow \Sigma \vec{r} = (2R mg \sin \theta + 2R mg \sin \theta) \hat{k}$$

$$2R \cdot 4R mg \sin \theta = 8mR^2 \ddot{\theta}$$

$$\Rightarrow \ddot{\theta} = \frac{g}{4R} \sin \theta$$

$$\Rightarrow \ddot{\theta} = \frac{g}{2R} (1 - \cos \theta)$$

b)



$$\Sigma \vec{F} = N \hat{p} - 4mg \cos \theta \hat{p} + 4mg \sin \theta \hat{\theta} - \frac{mv^2}{R} \hat{\theta}$$

$$N - 4mg \cos \theta = -4mR \dot{\theta}^2$$

$$N = 4mg \cos \theta - 2mg (1 - \cos \theta)$$

$$N = 2mg (1 + \cos \theta)$$

$$\sin 30^\circ = \frac{1}{2}$$

$$\cos 30^\circ = \frac{\sqrt{3}}{2}$$

c)

$$4mg \sin \theta - \frac{mv^2}{R} = 4mR \dot{\theta}^2 \Rightarrow \frac{mv^2}{R} = \frac{4mg}{2} - \frac{mg}{2}$$

$$\frac{mv^2}{R} = \frac{3mg}{2} \Rightarrow v^2 = \frac{3gR}{2} \Rightarrow v = \sqrt{\frac{3gR}{2}}$$