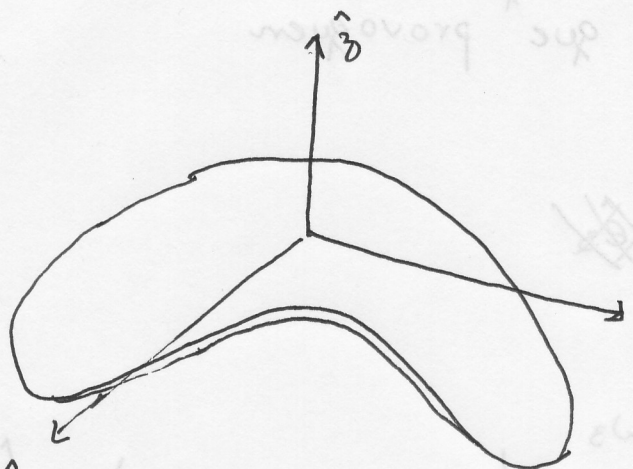


Un boomerang plano se lanza al aire rotando inicialmente con velocidad angular  $\vec{\omega}(t=0)$



tg:

$$\vec{\omega}_0 = \omega_0 \hat{z} + \omega_0 \sqrt{3} \hat{y}$$

Los momentos de inercia respecto a los ejes principales  $\hat{x}$  e  $\hat{y}$  son conocidos y valen  $I_x = 2I_0$ ,  $I_y = I_0$   
 $I_z = I_x + I_y = 3I_0$   
 Calcule  $\vec{\omega}(t)$ .

Ecs. de Euler:

$$I_1 \dot{\omega}_1 + \omega_2 \omega_3 (I_3 - I_2) = \tau_1^{ext}$$

$$I_2 \dot{\omega}_2 + \omega_3 \omega_1 (I_1 - I_3) = \tau_2^{ext}$$

$$I_3 \dot{\omega}_3 + \omega_1 \omega_2 (I_2 - I_1) = \tau_3^{ext}$$

Cuando el cuerpo no está bajo la acción de fuerzas externas

$$\Rightarrow I_1 \dot{\omega}_1 + \omega_2 \omega_3 (I_3 - I_2) = 0 \quad (1)$$

$$I_2 \dot{\omega}_2 + \omega_3 \omega_1 (I_1 - I_3) = 0 \quad (2)$$

$$I_3 \dot{\omega}_3 + \omega_1 \omega_2 (I_2 - I_1) = 0 \quad (3)$$

$$\Rightarrow 2I_0 \dot{\omega}_x + \omega_y \omega_z (3I_0 - I_0) = 0 \Rightarrow 2\dot{\omega}_x + 2\omega_y \omega_z = 0$$

$$I_0 \dot{\omega}_y + \omega_z \omega_x (2I_0 - 3I_0) = 0 \Rightarrow \dot{\omega}_y - \omega_z \omega_x = 0$$

$$3I_0 \dot{\omega}_z + \omega_x \omega_y (I_0 - 2I_0) = 0 \Rightarrow 3\dot{\omega}_z - \omega_x \omega_y = 0$$

sistema de 3 ecs. y 3 incógnitas

Antes de ponerse a integrar veamos qué ocurre con un sólido libre de fuerzas externas que provoquen torque.

~~$$\vec{L} = I_1 \omega_1 \vec{e}_1 + I_2 \omega_2 \vec{e}_2 + I_3 \omega_3 \vec{e}_3$$~~

$$(1) \cdot \omega_1 + (2) \cdot \omega_2 + (3) \cdot \omega_3$$

$$\Rightarrow I_1 \omega_1 \dot{\omega}_1 + I_2 \omega_2 \dot{\omega}_2 + I_3 \omega_3 \dot{\omega}_3$$

$$+ \omega_2 \omega_1 \omega_3 (I_3 - I_2) + \omega_1 \omega_2 \omega_3 (I_1 - I_3) + \omega_1 \omega_2 \omega_3 (I_2 - I_1) = 0$$

$$\Rightarrow I_1 \frac{d}{dt} \left( \frac{\omega_1^2}{2} \right) + I_2 \frac{d}{dt} \left( \frac{\omega_2^2}{2} \right) + I_3 \frac{d}{dt} \left( \frac{\omega_3^2}{2} \right) = 0$$

$$\Rightarrow I_1 \omega_1^2 + I_2 \omega_2^2 + I_3 \omega_3^2 = \text{cte.}$$

Quando no hay torque:

$$\Rightarrow \vec{L}^{\text{ep}} = \text{cte.}$$

$$\Rightarrow I_1^2 \omega_1^2 + I_2^2 \omega_2^2 + I_3^2 \omega_3^2 = \text{cte.}$$

En nuestro caso:

$$\begin{aligned} \cdot 2 I_0 \omega_1^2 + I_0 \omega_2^2 + 3 I_0 \omega_3^2 &= 2 I_0 \cancel{\omega_0^2} + I_0 \omega_0^2 \cdot 3 + 3 I_0 \omega_0^2 \\ &= 6 I_0 \cdot \omega_0^2 \end{aligned}$$

$$\begin{aligned} \cdot 4 I_0^2 \omega_1^2 + I_0^2 \omega_2^2 + 9 I_0^2 \omega_3^2 &= I_0^2 \cdot 3 \omega_0^2 + 9 I_0^2 \omega_0^2 \\ &= 12 I_0^2 \omega_0^2 \end{aligned}$$

$$\Rightarrow 2 \omega_1^2 + \omega_2^2 + 3 \omega_3^2 = 6 \omega_0^2 \quad (1)$$

$$4 \omega_1^2 + \omega_2^2 + 9 \omega_3^2 = 12 \omega_0^2 \quad (2)$$

(2)-(1):

$$2\omega_x^2 + 6\omega_z^2 = 6\omega_0^2$$

$$\Rightarrow \omega_z = \sqrt{\omega_0^2 - \frac{\omega_x^2}{3}}$$

$$\frac{d\omega_x}{\left(1 - \frac{\omega_x^2}{3\omega_0^2}\right)\omega_0^2}$$

C.V:  $u = \frac{\omega_x}{\sqrt{3}\omega_0}$

$$\Rightarrow du = \frac{d\omega_x}{\sqrt{3}\omega_0}$$

$$\Rightarrow I = \int_0^{\omega_x} \frac{\sqrt{3}\omega_0 du}{(1-u^2)\omega_0^2}$$

(2)-2.(1):

$$-\omega_y^2 + 3\omega_z^2 = 0$$

$$\Rightarrow \omega_y = \sqrt{3}\omega_z = \sqrt{3} \sqrt{\omega_0^2 - \frac{\omega_x^2}{3}}$$

$$(1) \Rightarrow \dot{\omega}_x = -\omega_y \omega_z$$

$$\Rightarrow \dot{\omega}_x = -\sqrt{3} \left( \omega_0^2 - \frac{\omega_x^2}{3} \right)$$

$$\Rightarrow \frac{d\omega_x}{dt} = -\sqrt{3} \left( \omega_0^2 - \frac{\omega_x^2}{3} \right)$$

$$\Rightarrow \frac{d\omega_x}{\left( \omega_0^2 - \frac{\omega_x^2}{3} \right)} = -\sqrt{3} dt$$

$$\int_{\omega_x(0)}^{\omega_x(t)} = \int_0^t$$

$$\frac{\sqrt{3}}{\omega_0} \operatorname{arctanh} u \Big|_0^u = -\sqrt{3} \cdot t$$

$$\Rightarrow \operatorname{arctanh} u = -\omega_0 \cdot t$$

$$\Rightarrow u = \tanh(-\omega_0 \cdot t)$$

$$\Rightarrow \boxed{\omega_x = -\sqrt{3}\omega_0 \cdot \tanh(\omega_0 \cdot t)}$$



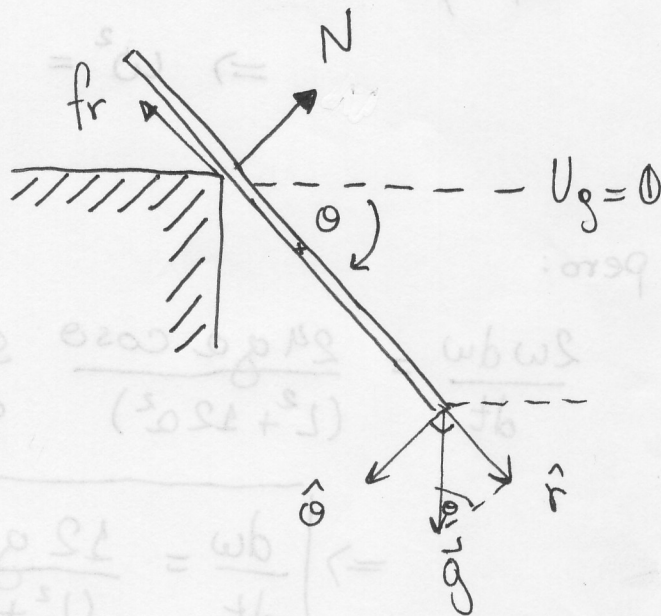
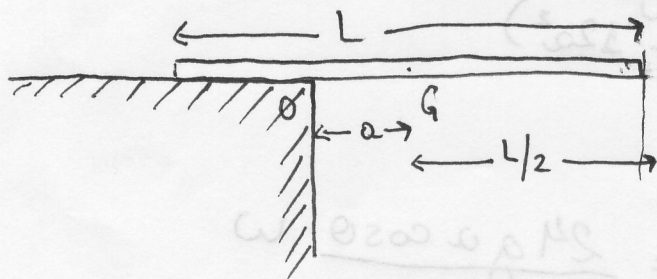
$$M \frac{d\vec{V}_G}{dt} = \vec{F}^{ext}$$

$$\vec{L}_S = M \vec{R}_G \times \vec{V}_G + \vec{L}'$$

$$\Rightarrow \frac{d\vec{L}_S}{dt} = \vec{\tau}^{ext}$$

$$\Rightarrow \frac{d}{dt} (M \vec{R}_G \times \vec{V}_G + \vec{L}') = \vec{\tau}^{ext}$$

### Problema 1



$$T = \frac{1}{2} M \vec{V}_0^2 + M \vec{V}_0 \cdot \vec{V}_{G|ro} + \frac{1}{2} I_0 \vec{\omega}^2$$

$$\vec{V}_0 = \vec{0} \Rightarrow T = \frac{1}{2} I_0 \vec{\omega}^2$$

$$I_{33} = \frac{1}{3} M L^2$$

$$\text{però } I_{cn} = \frac{1}{3} M L^2 - M \left( \frac{L}{2} \right)^2 = \frac{1}{12} M L^2 \Rightarrow I = \frac{1}{12} M L^2 + M a^2$$

$$\Rightarrow T = \frac{1}{2} I_0 \omega^2 = \frac{1}{2} \left( \frac{1}{12} M L^2 + M a^2 \right) \omega^2$$

$$= \frac{M}{24} (L^2 + 12a^2) \omega^2$$

$$\Rightarrow E = \frac{M}{24} (L^2 + 12a^2) \omega^2 - M g a \sin \theta$$

Por cond. iniciales:

$$E_0 = 0$$

$$\Rightarrow M (L^2 + 12a^2) \omega^2 = 24 M g a \sin \theta$$

$$\Rightarrow \omega^2 = \frac{24 g a \sin \theta}{(L^2 + 12a^2)}$$

pero:

$$\frac{2\omega d\omega}{dt} = \frac{24 g a \cos \theta}{(L^2 + 12a^2)} \frac{d\theta}{dt} = \frac{24 g a \cos \theta}{(L^2 + 12a^2)} \omega$$

$$\Rightarrow \boxed{\frac{d\omega}{dt} = \frac{12 g a \cos \theta}{(L^2 + 12a^2)}}$$

$$\hat{r}) M g \sin \theta - f_r = M(\ddot{r} - r\dot{\theta}^2) = -M r \omega^2$$

$$\Rightarrow M g \sin \theta - f_r = -M r \omega^2$$

$$\hat{\theta}) M g \cos \theta - N = M(2\dot{r}\dot{\theta} + r\ddot{\theta})$$

$$\dot{\theta} = \omega$$

$$\Rightarrow N = Mg \cos \theta' - r \ddot{\theta} M$$

$$N = Mg \cos \theta' - Mr \dot{\omega}$$

$$N = Mg \cos \theta' - \frac{M \cdot a \cdot 12ga \cos \theta'}{(L^2 + 12a^2)}$$

$$= Mg \cos \theta' \left( \frac{L^2 + \cancel{12a^2} - \cancel{12a^2}}{L^2 + 12a^2} \right)$$

$$N = Mg \cos \theta' \frac{L^2}{(L^2 + 12a^2)}$$

pero además:

$$f_r = Mg \sin \theta' + Ma \omega^2$$

$$f_r = Mg \sin \theta' + \frac{Ma \cdot 24ga \sin \theta'}{(L^2 + 12a^2)}$$

$$\omega = 0$$

$$= Mg \sin \theta' \left( \frac{L^2 + 12a^2 + 24a^2}{L^2 + 12a^2} \right)$$

$$\Rightarrow f_r = Mg \sin \theta' \left( \frac{L^2 + 36a^2}{L^2 + 12a^2} \right)$$

$$\Rightarrow \cancel{Mg} \sin \theta' \left( \frac{L^2 + 36a^2}{L^2 + 12a^2} \right) = \mu \cancel{Mg} \cos \theta' \frac{L^2}{\cancel{L^2 + 12a^2}}$$

$$\Rightarrow \tan \theta' = \frac{\mu L^2}{(L^2 + 36a^2)}$$