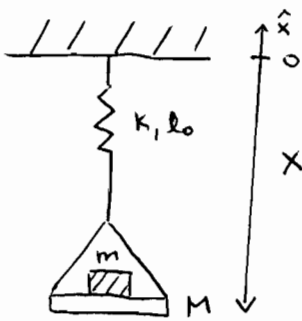


P1]

 $\downarrow \vec{g}$ Datos: M, m, k

M:



$$f_k - Mg - n = M \ddot{x}$$

$$\text{donde } f_k = -k(x - (-l_0)) = -k(x + l_0)$$

posición del largo natural
c/r al sistema de referencia

$$\Rightarrow -k(x + l_0) - Mg - n = M \ddot{x} \quad (1)$$

m:



$$n - mg = m \ddot{x} \quad (2)$$

$$(1) + (2) \Rightarrow -k(x + l_0) - (M + m)g = (M + m) \ddot{x}$$

$$\Rightarrow \ddot{x} + \frac{k}{M + m}(x + l_0) + g = 0$$

$$\Rightarrow \ddot{x} + \frac{k}{M + m} \left(x + l_0 + \frac{M + m}{k} g \right) = 0$$

$$\Rightarrow x(t) = A \cos \left(\sqrt{\frac{k}{M + m}} t + \phi \right) + l_0 + \frac{M + m}{k} g \quad (3)$$

$$(3) \text{ en } (2) \Rightarrow n = mg - m \cdot A \frac{k}{M + m} \cos(\cdot) \geq 0$$

↑ se impone

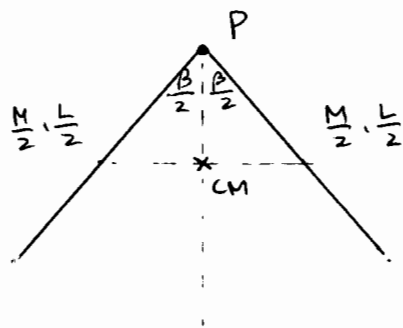
$$\Rightarrow A \cos(\cdot) \leq \frac{M + m}{k} g$$

Casos extremos: • Si $\cos(\cdot) = 1 \Rightarrow A \leq \frac{M + m}{k} g$

• Si $\cos(\cdot) = -1 \Rightarrow -A \leq \frac{M + m}{k} g \Leftrightarrow A \geq -\frac{M + m}{k} g$

$$\Rightarrow \boxed{|A| \leq \frac{M + m}{k} g}$$

P2]



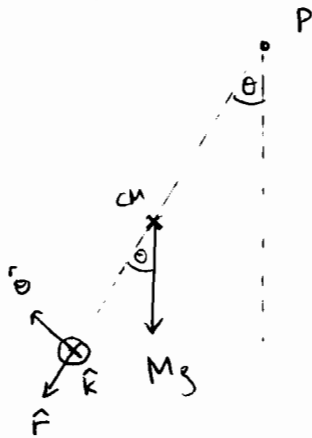
\vec{v}_g

Datos: M, L, β

\dot{T} ?

distancia del CM a P: $\frac{L}{4} \cos \frac{\beta}{2}$

$$I_P = \frac{1}{3} \left(\frac{M}{2} \right) \left(\frac{L}{2} \right)^2 + \frac{1}{3} \left(\frac{M}{2} \right) \left(\frac{L}{2} \right)^2 = \frac{1}{12} M L^2$$



$$\tau_P = I_P \ddot{\theta}$$

$$- \frac{L}{4} \cos \frac{\beta}{2} \cdot Mg \sin \theta = \frac{1}{12} M L^2 \ddot{\theta}$$

$$\Rightarrow \ddot{\theta} + \frac{3g \cos \beta/2}{L} \sin \theta = 0$$

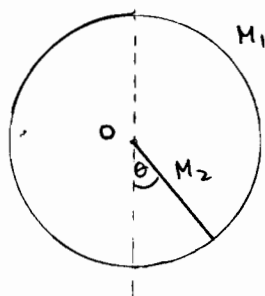
pequeñas oscilaciones $\sin \theta \approx \theta$

$$\Rightarrow \ddot{\theta} + \underbrace{\frac{3g \cos \beta/2}{L}}_{\omega^2} \theta = 0$$

$$\Rightarrow \omega = \sqrt{\frac{3g \cos \beta/2}{L}} ; \quad \omega = \frac{2\pi}{T}$$

$$\Rightarrow \boxed{T = 2\pi \sqrt{\frac{L}{3g \cos \beta/2}}}$$

P3]



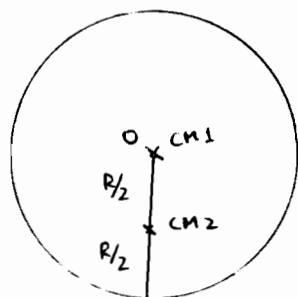
\vec{V}_g

Datos: M_1, R

Llamemos M_1 : masa del aro

M_2 : masa de la barra

\Rightarrow densidad lineal de masa $\lambda = \frac{M}{2\pi R + R} = \frac{1}{2\pi + 1} \frac{M}{R}$



distancia del CM al pto o

$$= \frac{M_1 \cdot 0 + M_2 \cdot R/2}{M} \quad \text{donde} \quad M_1 = \lambda \cdot 2\pi R$$

$$M_2 = \lambda \cdot R$$

$$= \frac{\lambda R^2}{2M}$$

$$= R / (2(2\pi + 1))$$

$$I_o = M_1 R^2 + \frac{1}{3} M_2 R^2$$

$$= \frac{2\pi + 1/3}{2\pi + 1} M R^2$$

$$\tau_o = I_o \ddot{\theta} \Rightarrow - \frac{R}{2(2\pi + 1)} M g \sin \theta = \frac{2\pi + 1/3}{2\pi + 1} M R^2 \ddot{\theta}$$

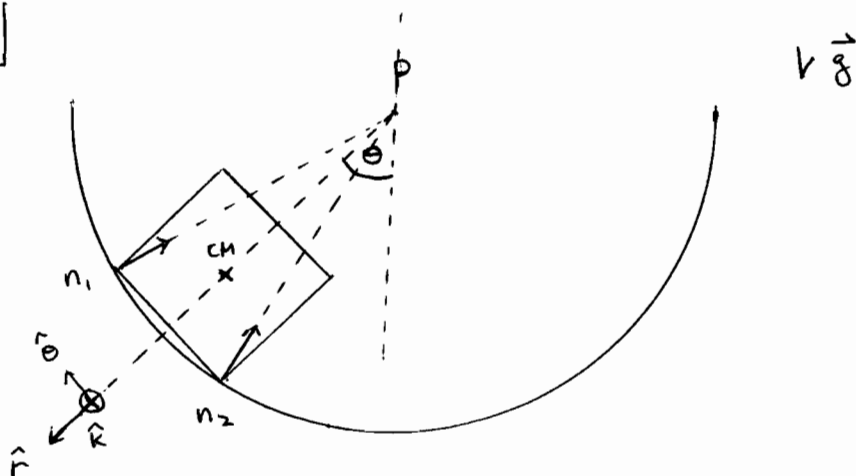
osc.
pequeñas

$$\Rightarrow \ddot{\theta} + \underbrace{\frac{g/R}{2(2\pi + 1/3)}}_{\omega^2} \theta = 0$$

$$\Rightarrow T = 2\pi \sqrt{\frac{2(2\pi + 1/3) \cdot R}{g}}$$

P4]

Datos: b, R .



Recuerdo: $\begin{cases} \tau_{cm} = I_{cm} \ddot{\theta} \\ \tau_o = I_o \ddot{\theta} \end{cases}$, donde o es un punto fijo en torno al cual rota el sólido.

En este caso aplicamos $\tau_p = I_p \ddot{\theta}$

Llamemos a la distancia $\overline{PCM} \equiv l$

$$I_{\text{cuadrado}} = \frac{1}{3} M b^2 \quad (\text{propuesto})$$

por Steiner, $I_{\text{cuadrado}} = \frac{1}{3} M b^2 + M l^2$

$$\tau_p = I_p \ddot{\theta} \Rightarrow -l M g \sin \theta = \left(\frac{1}{3} M b^2 + M l^2 \right) \ddot{\theta}$$

$$\Rightarrow \ddot{\theta} + \frac{g/l}{\frac{1}{3} \left(\frac{b}{l} \right)^2 + 1} \sin \theta = 0$$

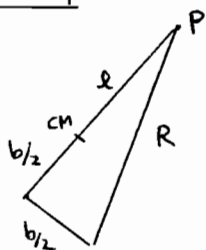
Pequeñas oscilaciones $\Rightarrow \ddot{\theta} + \frac{g/l}{\frac{1}{3} \left(\frac{b}{l} \right)^2 + 1} \theta = 0$

($\theta \ll 1 \Rightarrow \sin \theta \approx \theta$)

ω^2

$$\Rightarrow f = \frac{1}{2\pi} \sqrt{\frac{g/l}{\frac{1}{3} \left(\frac{b}{l} \right)^2 + 1}}$$

falta calcular l :



$$R^2 = (l + b/2)^2 + (b/2)^2$$

$$\Rightarrow l = \sqrt{R^2 - (b/2)^2} - b/2$$

Si $b \ll R \Rightarrow l \approx R$ y $b/l \ll 1 \Rightarrow f \approx \frac{1}{2\pi} \sqrt{\frac{g}{l}}$ resultado conocido

