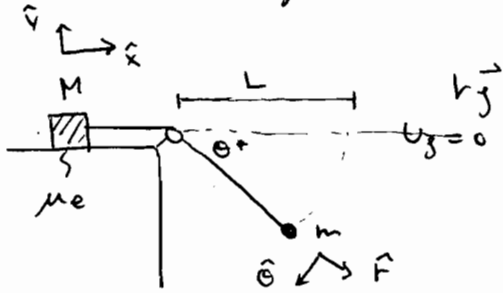


P11


 Datos: M, m, L, μ_e
 $\angle \theta^*$

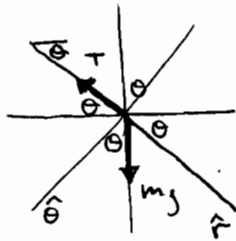
$$E_f = E_i + \underbrace{W(\vec{f}_{roce})}_{\vec{f}_{roce} \cdot \Delta \vec{r}^0}$$

$$E_i = 0$$

$$E_f = \frac{1}{2} m v^2 - m g L \sin \theta$$

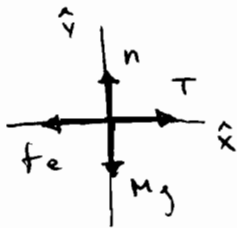
$$E_i = E_f \Rightarrow v^2 = 2 g L \sin \theta \quad (1)$$

DCL m



$$\hat{r}) - T + m_j \sin \theta = - m \frac{v^2}{L} \quad (2)$$

DCL M



$$\hat{y}) n - M_j = 0$$

$$\hat{x}) - \underbrace{f_e}_{\mu_e n} + T = 0$$

$$\Rightarrow T = \mu_e M_j \quad (3)$$

$$(1) \text{ en } (2) \Rightarrow - \mu_e M_j + m_j \sin \theta^* = - \frac{m}{L} (2 g L \sin \theta^*)$$

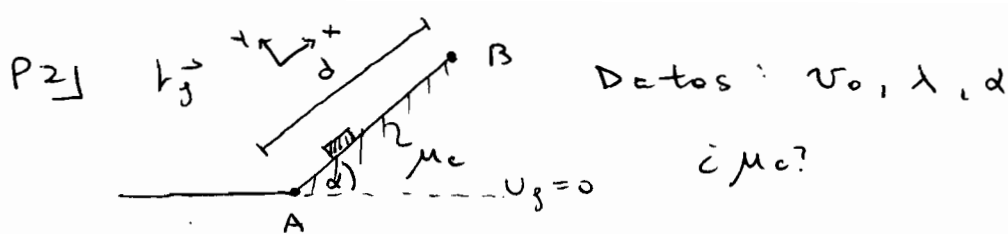
y (3) en (2)

$$\Rightarrow$$

$$3 m \sin \theta^* = \mu_e M$$

$$\Rightarrow$$

$$\boxed{\sin \theta^* = \frac{\mu_e \cdot M}{3 m}}$$



$$E_f = E_i + \underbrace{W(\vec{f}_{roce})}_{\vec{f}_{roce} \cdot \Delta \vec{r}}$$

$$E = \frac{1}{2} m v^2 + m g h$$

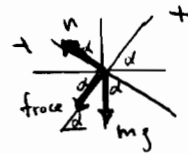
A \rightarrow B:

$$E_B = E_A + \vec{f}_{roce} \cdot \Delta \vec{r}$$

$$E_B = 0 + m g d \sin d$$

$$E_A = \frac{1}{2} m v_0^2 + 0$$

$$\vec{f}_{roce} \cdot \Delta \vec{r} = (-f_{roce} \hat{i}) (d \hat{i}) = - \underbrace{f_{roce} \cdot d}_{\mu_c \cdot n}$$



$$\S) n - m g \cos d = 0$$

$$\Rightarrow n = m g \cos d$$

$$\Rightarrow m g d \sin d = \frac{1}{2} m v_0^2 - \mu_c m g d \cos d$$

$$\Rightarrow \frac{1}{2} v_0^2 = g d (\sin d + \mu_c \cos d) \quad (1)$$

B \rightarrow A:

$$E_A = E_B + \vec{f}_{roce} \cdot \Delta \vec{r}$$

$$E_A = \frac{1}{2} m (\lambda v_0)^2 + 0$$

$$E_B = 0 + m g d \sin d$$

$$\vec{f}_{roce} \cdot \Delta \vec{r} = (f_{roce} \hat{i}) \cdot (-d \hat{i}) = - \underbrace{f_{roce} \cdot d}_{\mu_c \cdot n = \mu_c m g \cos d}$$

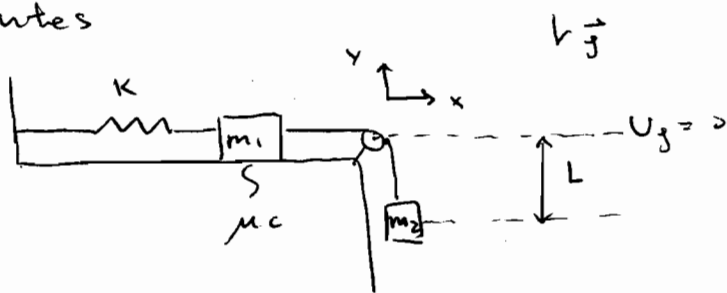
$$\Rightarrow \frac{1}{2} m \lambda^2 v_0^2 = m g d \sin d - \mu_c m g d \cos d$$

$$\Rightarrow \frac{1}{2} \lambda^2 v_0^2 = g d (\sin d - \mu_c \cos d) \quad (2)$$

$$(2)/(1) \Rightarrow \lambda^2 = \frac{\sin d - \mu_c \cos d}{\sin d + \mu_c \cos d}$$

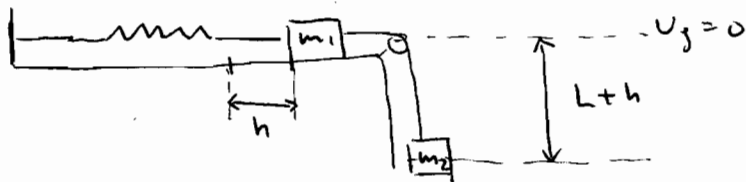
$$\Rightarrow \boxed{\mu_c = \frac{1 - \lambda^2}{1 + \lambda^2} \tan d}$$

P3] Antes



Datos: m_1, m_2, K, h
¿ μ_c ?

Después



$$E = \underbrace{\frac{1}{2} m v^2}_{\text{e. cinética}} + \underbrace{m g h}_{\text{e. pot. gravitatoria}} + \underbrace{\frac{1}{2} K \Delta x^2}_{\text{e. pot. elástica}}$$

$$E_f = E_i + \vec{f}_{roce} \cdot \Delta \vec{r}$$

$$E_i = 0 - m_2 g L + 0$$

$$E_f = - m_2 g (L+h) + \frac{1}{2} K h^2$$

$$\vec{f}_{roce} \cdot \Delta \vec{r} = (-f_{roce} \hat{i}) \cdot (h \hat{i}) = - \underbrace{f_{roce}}_{\mu_c m_1 g} \cdot h$$

$$\Rightarrow - m_2 g (L+h) + \frac{1}{2} K h^2 = - m_2 g L - \mu_c m_1 g h$$

$$\Rightarrow - \cancel{m_2 g L} - m_2 g h + \frac{1}{2} K h^2 = - \cancel{m_2 g L} - \mu_c m_1 g h$$

$$\Rightarrow \mu_c = \frac{m_2 g h - \frac{1}{2} K h^2}{m_1 g h}$$

$$\Rightarrow \boxed{\mu_c = \frac{m_2 g - \frac{1}{2} K h}{m_1 g}}$$